

## Foreground-Aware Knowledge Distillation for Enhanced Damage Detection

Pantelis Mentesidis, Christos Papaioannidis, Ioannis Pitas









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## Introduction



 Automated drone-based inspection with AI improves safety and efficiency in industries.



Fig. 1: Drone inspection on powerlines [1].



Fig. 2: Drone inspection on insulated pipes [2].

[1] Aerial Core H2020 Project, https://aerial-core.eu/

[2] Piloting uses cases. PILOTING H2020 Project. (2023, December 19). https://piloting-project.eu/piloting-uses-cases/



# Introduction



• Early detection on pipe damages prevents leaks, ensuring operational effectiveness and environmental sustainability.



(a) RGB image.

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damage detection.

Fig. 3: DNN inspection results on insulated pipes from AUTH.









# Introduction

- Advanced DNN models often struggle on real-world applications.
- Outdoor industrial settings are typically cluttered and noisy.

Significant challenges under these harsh conditions.



Fig. 4: PDI dataset [3] images.

[3] P. Mentesidis, C. Papaioannidis, and I. Pitas, "ADVANCING INDUSTRIAL INSPECTION: A DATASET FOR AUTOMATED DAMAGE DETECTION IN INSULATED PIPES," 2024.









VML



## **Method**

- Knowledge of pipe regions improved performance of the detection model.
- Obtaining pipe regions during • inference is non-trivial.
  - Slower system performance.
  - Potential errors may propagate.







(Original)



(RB & SF)



(SF)



(RB & EF)



(BB & EF)

Fig. 5: Image preprocessing.













## **Method**

- Model-agnostic Knowledge • Distillation (KD) framework.
- Utilize the foreground knowledge of the pipeline mask only at training.
  - Enhance vision based damage detection in cluttered environment.

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Fig. 6: Architecture overview.









#### Results

 Improves the performance almost in every SOTA detection model.



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Fig. 8: Results.



# Conclusion

- Model-agnostic KD approach.
- Utilize the foreground knowledge.
- 12% increase in mean average precision (mAP)











#### **Q & A**

#### Thank you very much for your attention!

#### Ioannis Pitas Aristotle University of Thessaloniki, pitas@csd.auth.gr





