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- Decentralized DNN Architectures
- Learning-by-Education Node Community (LENC) Framework
- LENC Framework Applications
- LENC Framework Experiments
- LENC Architecture Implementation

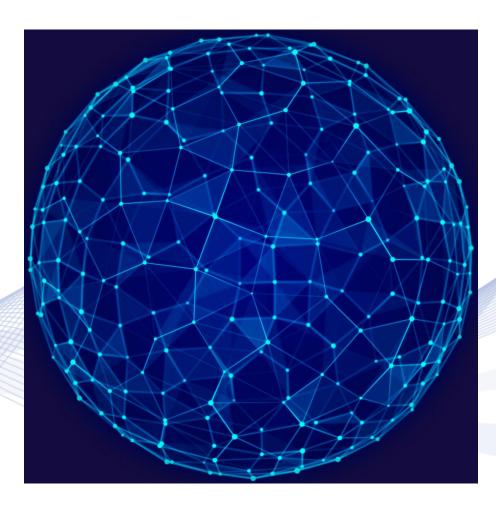




Definition

Decentralized Deep Neural Network architectures distribute computation and decision-making across multiple nodes or devices, offering advantages in:

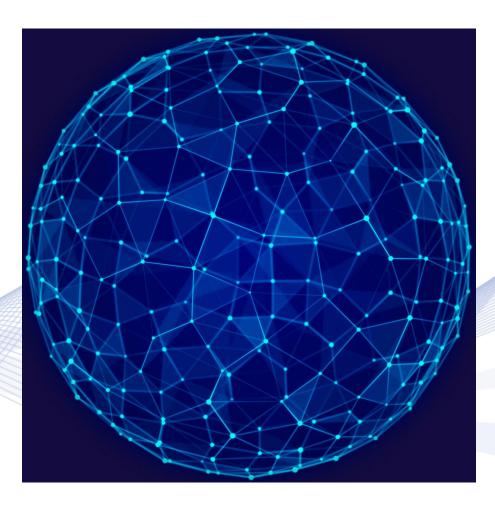
- scalability,
- privacy, and
- robustness.





Decentralized DNN advantages

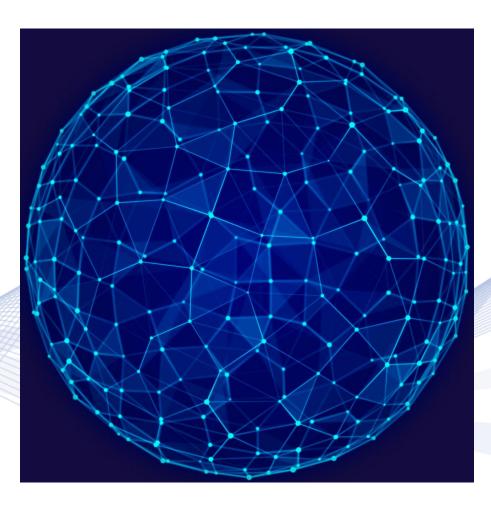
- **Distribution**: Data and computations are spread across multiple nodes or devices.
- **Collaboration**: Nodes can cooperate for DNN model training or inference.
- Privacy Preservation: Data remain local, thus enhancing privacy and security.
- Fault Tolerance: Resilience to individual node failures or attacks.





Decentralized DNN computation

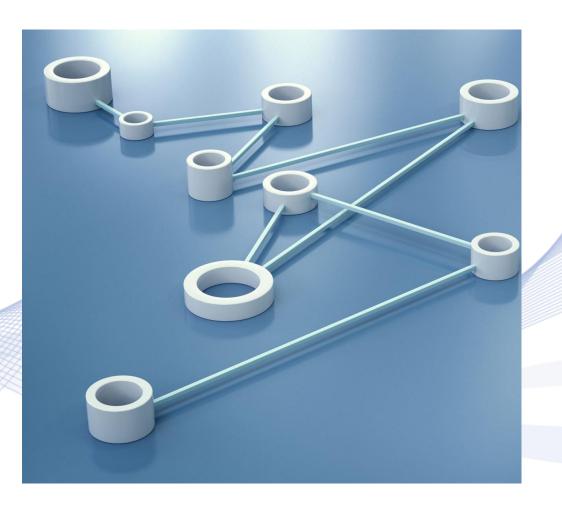
- Peer-to-Peer Networks:
 Collaborative learning (training)
 among peers, without a central server.
- Cloud DNN Computing: Running DNN training and/or inference on cloud nodes.
- Edge Computing: Running DNN inference or lightweight training directly on edge devices.





Peer-to-peer DNN computing.

- **Decentralization**: Reduced dependency on central servers, enhancing scalability and robustness.
- Resource Efficiency: Idle computational resource utilization across peers.
- **Resilience** to node failures or attacks.
- **Community-driven Innovation** through collaborative research and knowledge exchange.





Edge DNN Computing

- Low Latency: Decision-making without reliance on distant servers.
- **Bandwidth Efficiency**: No transfer of large data volumes to central servers.
- Privacy Preservation: Sensitive data can be processed locally, enhancing privacy.
- Offline Capability: DNN operation in disconnected or low-connectivity environments.



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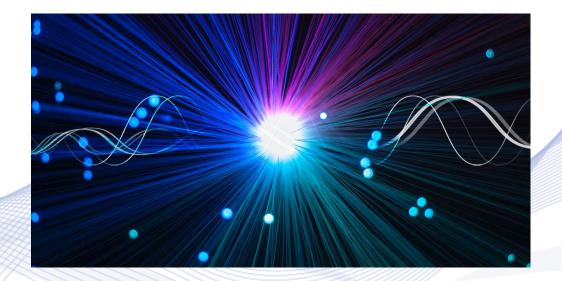


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In *Knowledge Distillation*, a compact DNN model (*student model*), learns from a larger, more complex DNN model (*teacher model*), by mimicking its outputs or internal representations.

Teacher-Student DNN architectures.

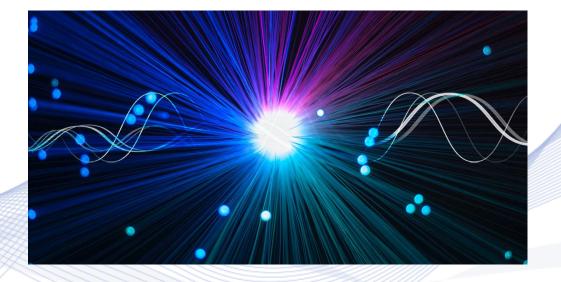




VML



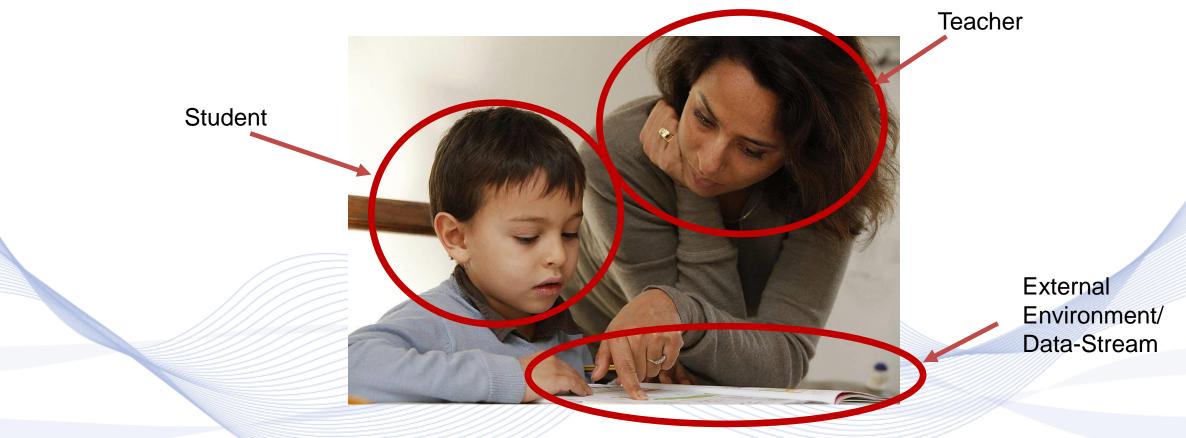
- **Training**: The Student DNN model is trained using a combination of the original training data and the Teacher DNN model predictions or intermediate representations.
 - **Objective Function**: The KD objective is to minimize the discrepancy between the student DNN predictions/ representations from the teacher DNN ones.





VML

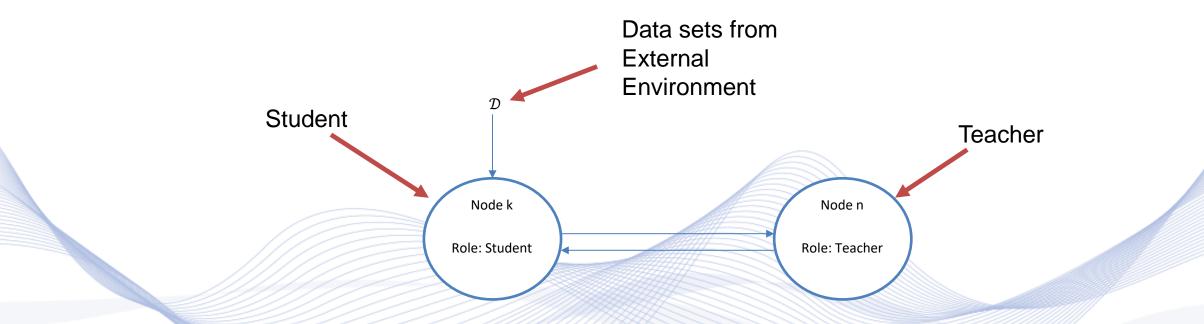




Teacher-Student Learning for Humans: The student asks for tutoring on Artificient Intelligence & Artif



The LENC framework is a network of N interacting LENC nodes.



Teacher-Student Learning for the LENC framework nodes: The Student LENC nodes asks for tutoring from a Teacher LENC node on unknown data.





- A LENC class can have one Teacher and multiple Student nodes.
- LENC can support multiple Teachers and Students.
- Students can choose their Teacher that knows best their task.
- Teachers may learn as well.
- Teacher/student roles may reverse for certain tasks.
- A classification task is defined on a group of semantic classes.
- Regression or clustering taks can be defined as well.





- Students can cooperate with each other during learning.
- Teachers can pull together their knowledge.
- LENC nodes can have a *cooperating* or *competing* behavior.
- Some LENC nodes may be *malicious*.



LENC node structure.

Each LENC node can be trained on various DNN tasks (data classes $1, \dots, T$).

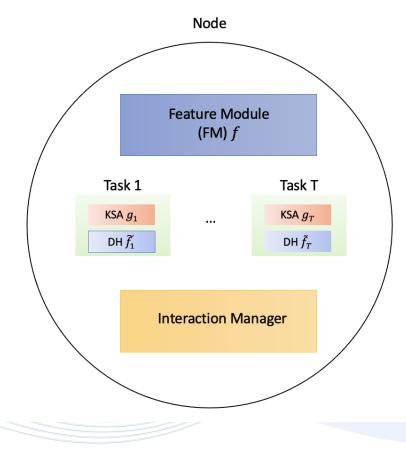
• Feature Module (FM) f.

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- **Decision Heads** (DH) \tilde{f}_i , $i = 1, \dots, T$ (one per task).
- Knowledge Self-Assessment (KSA) Modules g_i , $i = 1, \dots, T$.
- Interaction Manager (IM) interacts with other LENC Ims and receives external environment data sets D.





Feature Module

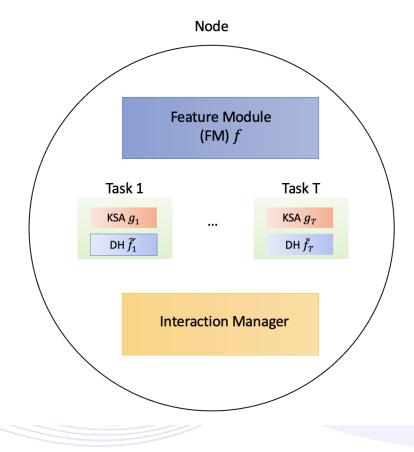
Feature Module (FM) DNN is shared among tasks:

 $\mathbf{f} = f(\mathbf{x}; \mathbf{w}_s).$

Its structure is described by S_s .

• It is parametrized by w_s.







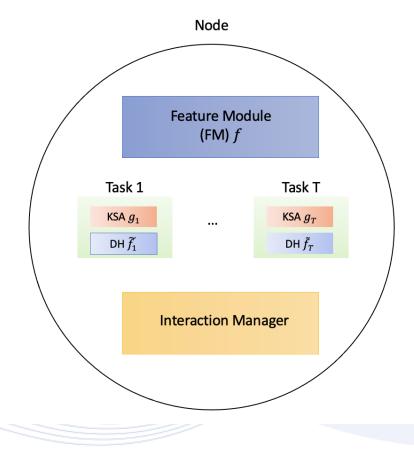
Knowledge Self-Assessment Module

- It decides whether input data x of an input dataset \mathcal{D} belongs to the same probability distribution of the data used for LENC node training for each task.
- It comprises an *Out-of-Distribution* (OOD) detector:

 $g_i(\mathbf{x}): \mathcal{D} \longrightarrow \{0,1\}, \quad i = 1, \cdots, T.$

• It classifies new data samples $x \in \mathcal{D}$ as inor out-of-distribution for each task.





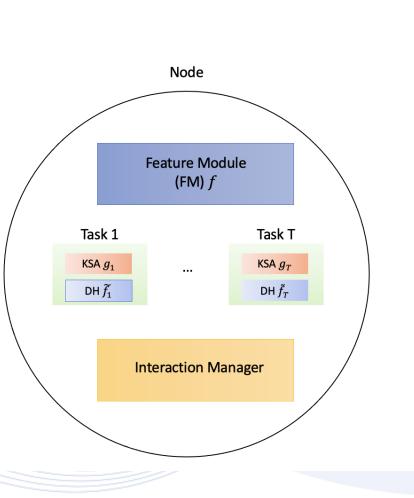
- The KSA module is used to automatically detect the Decision Head j out of \tilde{f}_i , $i = 1, \dots, T$ that will be used for LENC node decision making.
- The decision minimizes:

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 $argmin_j(g_1, \cdots, g_T).$

• Decision Head \tilde{f}_j has been trained on sample data that are similar to current input **x**.



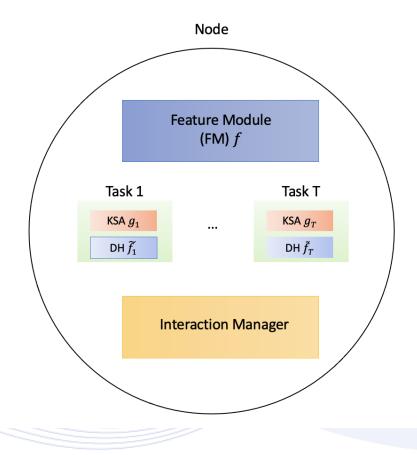


Decision Heads

- There are *T* Decision Heads \tilde{f}_i , $i = 1, \dots, T$ (one per task).
- S_i , \mathbf{w}_i , $i = 1, \dots, T$: DH structure description and parameter vector.
- LENC Node Decision is made by concatenating FM and DH inference:
 - $\mathbf{f} = f(\mathbf{x}; \mathbf{w}_s), \tilde{y}_j = \tilde{f}_j(\mathbf{f}; \mathbf{w}_j), \\ j = argmin(g_1, \cdots, g_T).$

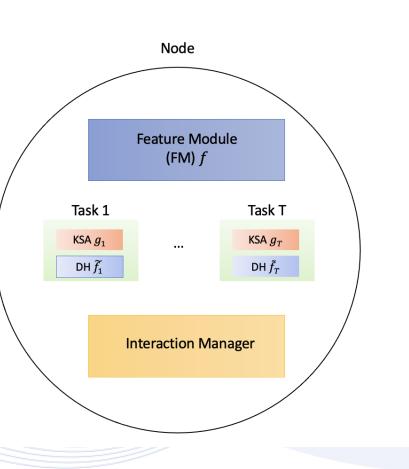
x: input vector.





Interaction Manager handles:

- Inter-node communications.
- Communications between the nodes and the external environment.
- Communication of LENC nodes components, such as data, activations, weights and structure.





Key Interaction Manager Functions for LENC node *k*:

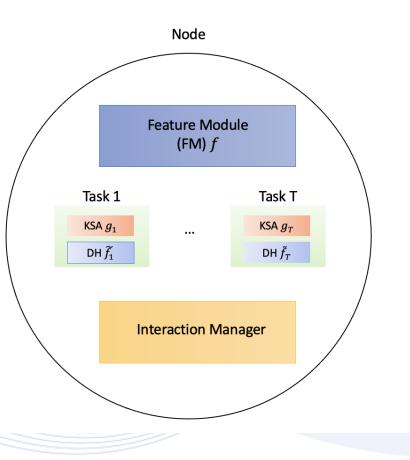
- It receives data sets $\ensuremath{\mathcal{D}}$ from the environment.
- It transmits data sets \mathcal{D}^\prime to other nodes and receives their responses:

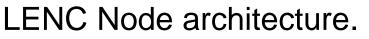
 $\mathcal{D}' = \{q_i, i = 1, \cdots, N, i \neq k\}.$

- $q_k = 0$, if the node is not aware of the task or,
- q_k is a scalar number measuring its knowledge on the task.

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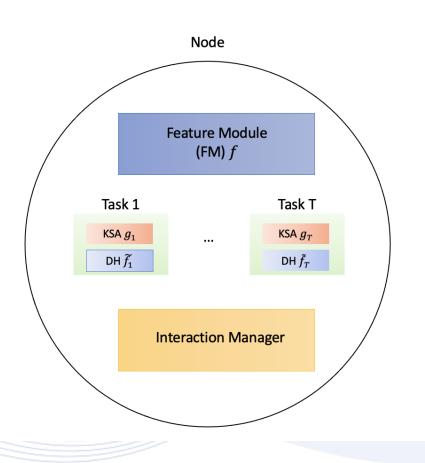






Policies to compute q_k for teacher selection when the k^{th} node is aware about the task:

- **Accuracy**: q_k can be the optionally stored average classification accuracy a_i^n .
- **ODD score**: q_k can be a function of an ODD score g_j internally computed by the j^{th} KSA module of the k^{th} node given \mathcal{D}' .
- **Disagreement**: q_k can be a scalar measure of the disagreement between the current Student LENC node and the k^{th} LENC node.



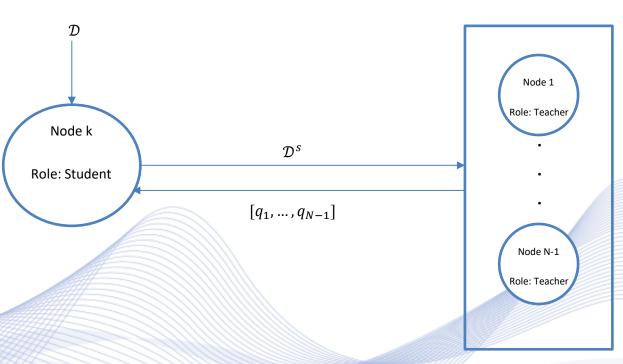






LENC Teacher selection.

- The External Environment sends an input data set \mathcal{D} to LENC student node k.
- Its KSA Module checks if the data distribution is known.
- If not, the data stream is sent to other nodes.
- The nodes respond with q_i , $i = 1, \dots, N, i \neq k$.
- The student selects one (best) or more teachers, based on the scalar metric q_i measuring their performance on \mathcal{D} .



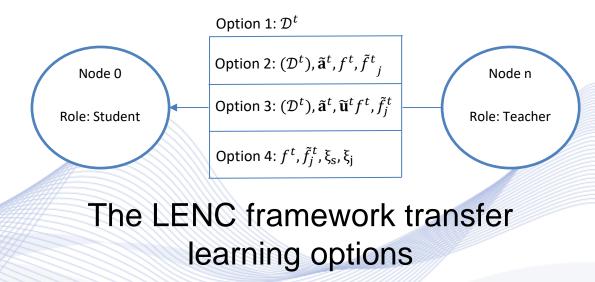
LENC Teacher selection.



LENC Student node training (option 1):

Training Data Transmission.

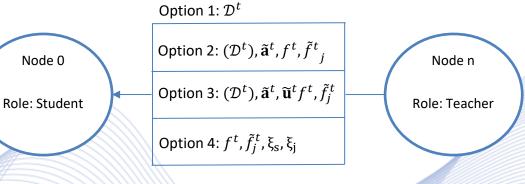
- The Teacher LENC node sends its related training data set \mathcal{D}^t to the Student LENC node.
- The Student LENC uses these training data to learn the new task.





LENC Student node training (option 2): Soft-Output Activation Transmission.

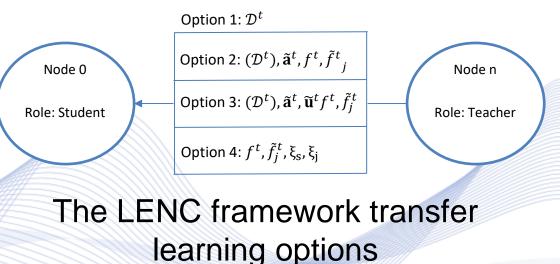
- The Teacher LENC Node sends its training data set \mathcal{D}^t , its soft-output activations \tilde{a}^t and its FM structure \mathcal{S}_s (for and DH structure \mathcal{S}_j for the task j.
- The Student LENC node uses KD to for training using Teacher LENC node
 guidance.





LENC Student node training (option 3): Feature Activation Transmission.

- LENC Teacher node sends its training data set D^t, its soft-output activations ã^t, its feature activations ũ^t and its structure S_s and S_i for the task j.
- Student LENC node uses KD to for training using the teacher's guidance.



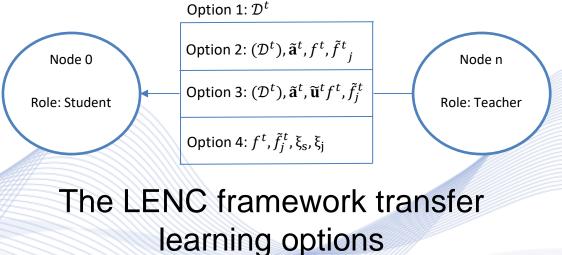




• LENC Student node training (option 4):

DNN weights transmission.

- Teacher LENC node sends its FM and DH structures S_s, S_j and its FM and DH weights w_s, w_j for the task j.
- The Student LENC node just copies of the Teacher model f^t and f^t_i.



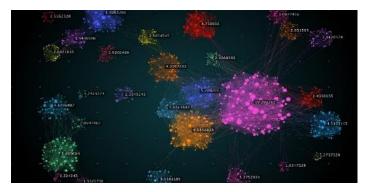




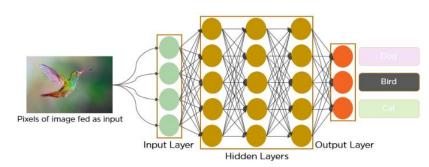
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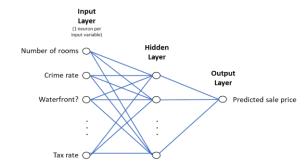




Clustering.



Classification.



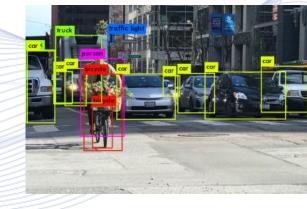
Regression.



Image segmentation.

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Object detection.



Federated Learning: Training a global DNN model across decentralized nodes, while keeping data on-device.

- **Privacy Preservation**: Data remain on local devices, ensuring privacy.
- **Communication efficiency**: No large data volume transfer to a central server is needed.
- Scalability: Large-scale diverse data sources can be accomodated.
- Adaptability: Non-identically distributed data can be supported.
- **Distributed** rather than decentralized DNN FL computing.





Federated Learning

- One LENC node is the master node (aggregator).
- All LENC nodes have the same structure *S* and are trained using their local data.
- The master node uses training option 4 to receive the weights of all other nodes with the same structure within the community.
- The master node aggregates the weights of all participating nodes.
- The process is repeated until convergence.



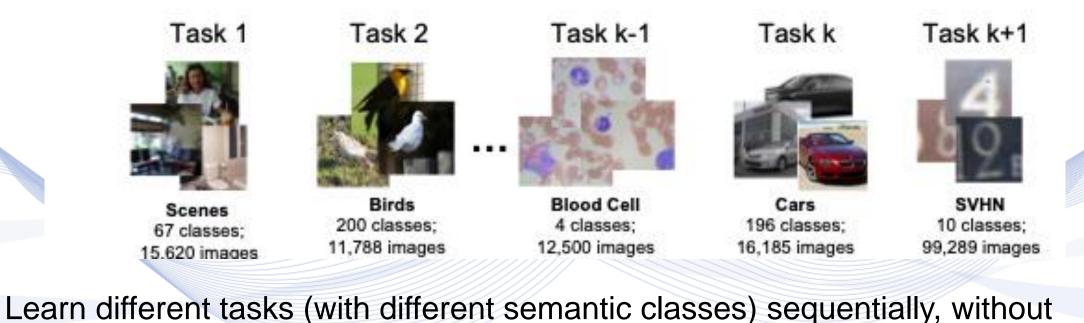
Peer-to-Peer Learning

- LENC node training options 1-4 constitute forms of Peer-to-Peer Learning.
- Nodes act exclusively to enhance their knowledge.
- No need for a central server.
- Retaining knowledge within the node community.





Continual Learning



forgetting.

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Edge Computing – Decentralized Inference

- Raw data is processed locally on LENC nodes.
- Nodes use real-time inference on their data.
- Lightweight training of Decision Modules is done directly on nodes.
- A master node (server) can be defined to aggregate inference results.
- Inference can local without centralized decision-making.





DNN performance Reproducibility - Privacy

- DNN node 1 is the model of a published paper.
- DNN node 2 wants to replicate the model and the experiments.
- Using variations of Options 1-4 DNN node 2 can replicate the initial DNN model behavior and also consider possible privacy constraints.
- Private weights, architecture, training dataset, etc.





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Collaborative Knowledge Distillation (CKD) **Experiment**.

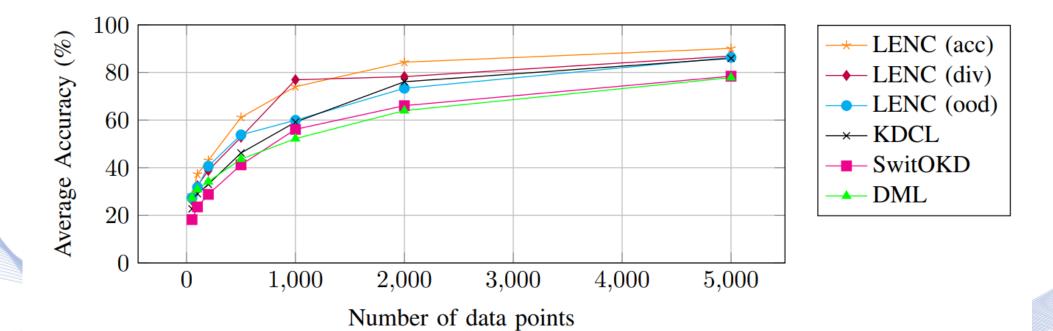
- Four LENC nodes are initialized.
- One of them (Teacher LENC node) is pretrained on a *classification* dataset (CIFAR10, SVHN, MNIST, FashionMNIST).
- Each node (including the Teacher) takes the LENC Student role exactly once every *education cycle*.
- All Student LENC nodes use the LENC framework option 2 (Knowledge Distillation).
- After 5 education cycles, we observe the results.



Average test classification accuracy (%) of the 3 student LENC nodes and of competing CKD methods, for incoming data sets D^t having 1000 or 5000 samples (from C10 or C100 CIFAR).

Dataset	Students	Stream Size	DML	KDCL	SwitOKD	LENC (proposed)	
C10	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	1000	52.20 ± 0.52 51.17 ± 0.71	$\begin{array}{c} 62.23 {\pm} 0.15 \\ 62.09 {} {\pm} {} 0.21 \end{array}$	56.15 ± 0.73 57.85 ± 0.80	$76.93{\pm}0.71$ $70.16{\pm}0.82$	
	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	5000	$\begin{array}{c} 77.85{\pm}0.31 \\ 75.56{\pm}0.82 \end{array}$	$\begin{array}{c} 85.76{\pm}0.07\\ 84.47{\pm}0.08\end{array}$	$79.08 {\pm} 0.70$ $78.79 {\pm} 0.68$	$\begin{array}{c} 86.31 {\pm}~0.32 \\ 87.12 {\pm}0.24 \end{array}$	
C100	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	1000	9.77 ± 0.25 6.12 ± 0.38	25.16 ± 0.12 27.59 ± 0.19	$\begin{array}{c} 13.71 {\pm} 0.57 \\ 14.72 {\pm} 0.61 \end{array}$	34.96±0.47 29.75±0.49	
	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	5000	31.53 ± 0.31 8.30 ± 0.16	58.70 ± 0.09 56.94 ± 0.12	35.31±0.29 37.27±0.45	65.02±0.13 58.18±0.17	





Average student LENC node classification accuracy (%) for varying *D^s* sizes in the CIFAR-10 dataset for 3 alternative LENC teacher selection policies against that of competing methods.



Experimental conclusions

- LENC framework outperforms existing CKD methods, when digesting un-labelled incoming data samples, under the assumption that the sole expert indeed knows data similar to the incoming ones.
- LENC proves to be the most tolerant to small batch sizes, thus showcasing its usability in an important real world use-case: when a node faces unknown current input data and needs to acquire relevant knowledge as soon as possible, in order to respond immediately.



CL Experiment

Continual Learning (CL) Experiment.

- Six LENC nodes are initialized for each dataset.
- Five of them (Teacher LENC nodes) are trained on a task of the *classification* datasets (SPLIT-MNIST, SPLIT-CIFAR-10 and SPLIT-CIFAR-100).
- For example for the SPLIT-MNIST dataset: Node 1 knows classes {0,1}, Node 2 knows classes {2,3} etc.
- The Student LENC node encounters all tasks for a single education cycle and picks the correct teacher for each task.
- The Student LENC nodes use the LENC framework option 2 (Knowledge Distillation) and a *specialized CL loss* to learn new tasks without forgetting.
- After 5 education cycles, we observe the results.



CL Experiment

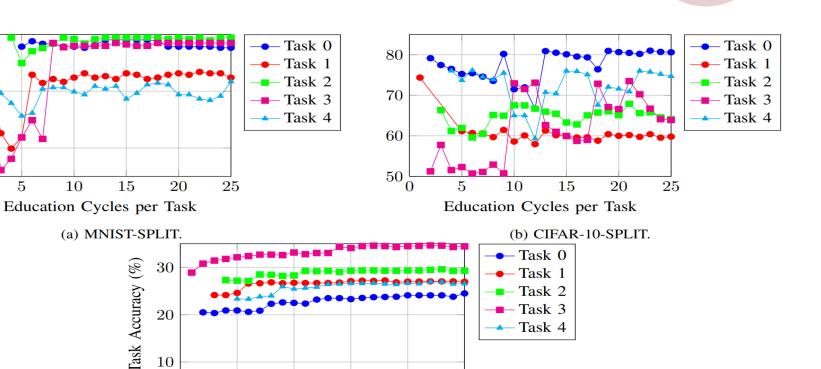
10

20

10

0





25

- Task 3

---- Task 4

Student classification accuracy per task for a) SPLIT-MNIST, b) SPLIT-CIFAR-10 and c) SPLIT-CIFAR-100.

20

15

10

Education Cycles per Task

 $\mathbf{5}$

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100

98

96

0

5

Task Accuracy (%)

VML

CL Experiment



Experimental conclusions.

• The LENC framework can achieve continual learning and adaptation with only a few randomly sampled batches.



Federated Learning Experiment (VML

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- Decentralized DNN (D-DNN) Consensus Inference Experiment
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Federated Learning Experiment (VML

Federated Learning Experiment Setup

- 1 master LENC node (aggregator), 2 student LENC nodes with unique datasets.
- Students are trained locally for 50 epochs and send output to Aggregator.
- Aggregator calculates the mean DNN model weights (global) and sends them to student nodes.
 - 4 FL rounds in total.



Federated Learning Experiment (VML 80 70 60 Accuracy 50 40 aggregator accuracy student1 accuracy after 10 epochs student2 accuracy after 10 epochs 30 2 З Current Run

Accuracy report (%) of the aggregator and the two students after each federated run on Cifar 10 test dataset.

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D-DNN Inference



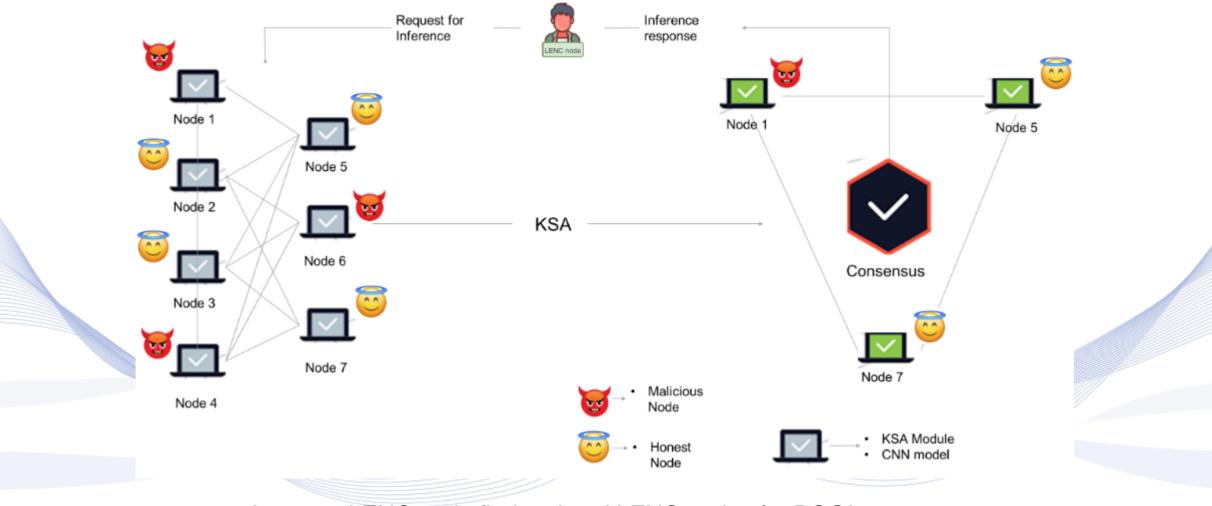
Decentralized DNN (D-DNN) Consensus Inference

- Any LENC (master) node can make a request to the LENC community to perform *Decentralized DNN* (D-DNN) *inference* by providing its own dataset.
- Through the KSA module, LENC nodes that are familiar with the master node data distribution are selected to carry out the inference.
- **Proof of Quality Inference** (POQI) Consensus Protocol, is used to establish consensus between the selected teachers regarding their DNN Inference outputs.
- Security and integrity of the inference results reported to the client are ensured by detecting and excluding malicious DNN nodes.

D-DNN Inference

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A master LENC node finds related LENC nodes for POQI consensus.

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D-DNN Inference



Dataset	Faulty Nodes	Method	Accuracy (%)						
			N1	N2	N3	N4	N5	N6	N7
Cifar-10	0	Weighted Average Majority Voting PoQI	95.12 95.05 95.27						
Cifar-10	1	Weighted Average Majority Voting PoQI	16.40 94.63 94.99	15.87 94.86 94.99	15.92 94.76 94.99	16.24 95.02 94.99	15.35 94.72 94.99	16.11 94.56 94.99	- - -
SVHN	1	Weighted Average Majority Voting PoQI	15.27 93.21 93.42	15.41 93.36 93.42	15.37 93.17 93.42	15.33 93.12 93.42	- -	15.13 93.04 93.42	15.52 93.77 93.42
SVHN	3	Weighted Average Majority Voting PoQI	- -	11.14 92.56 93.18	11.40 93.12 93.18	- -	11.16 92.94 93.18	11.36 91.82 93.18	- - -

LENC node N1-M7 classification accuracy (%) comparison in the presence of 1-3 malicious nodes.





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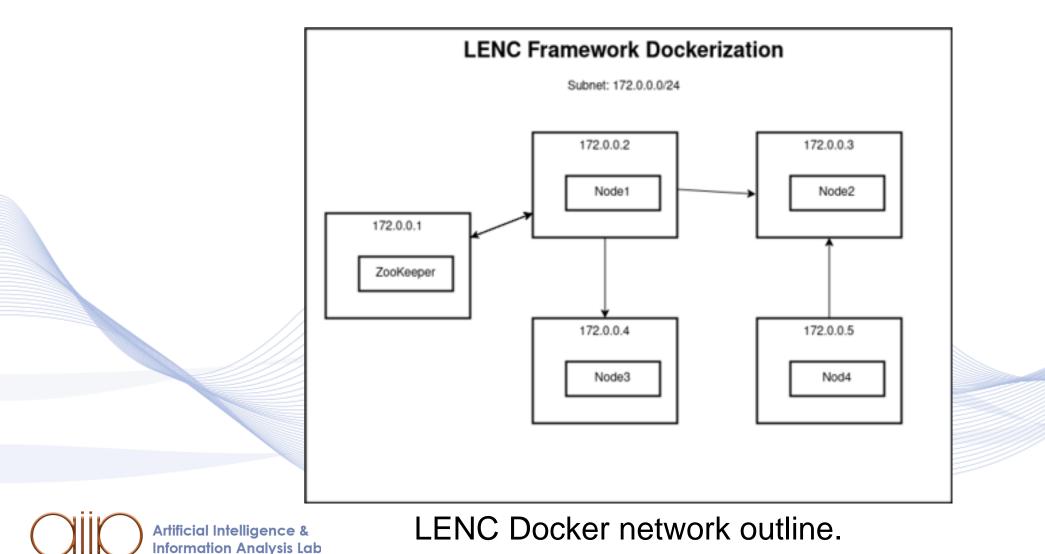
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- We implement the LENC framework on multiple devices by using *Docker* and *Zookeeper*.
- Now each LENC node is physically located in a single terminal.
- The LENC nodes use the Zookeeper for "online" node discovery and receive the IP addresses of all "online" LENC nodes.



- Each LENC node occupies one *Docker container*.
- Zookeeper-like instance for service discovery and coordination.
- Environment simulation using Docker network capabilities:
 - The network has a predefined IP mask (172.0.0.0/24).
 - Each container has its own virtual IP address (172.0.0.1-.256).
- All communications (including file sharing) use sockets:
 - Each node acts both as a server and client.
 - All listening on port 60.000.
 - Zookeeper webservice listens on port 8080.





VML

LENC Architecture Implementation

Dockerized LENC training procedure

- Teacher LENC nodes download datasets and teach their underlying DNNs by creating new tasks.
- A Student LENC node with a novel dataset can search for the most suitable Teacher by sending "EVAL" requests, along with the dataset to all available LENC nodes.
- They test the dataset to their networks and return the resulting accuracy score to the Student LENC node.
- The Student LENC node picks the best teacher, e.g., the one with the max recognition score.

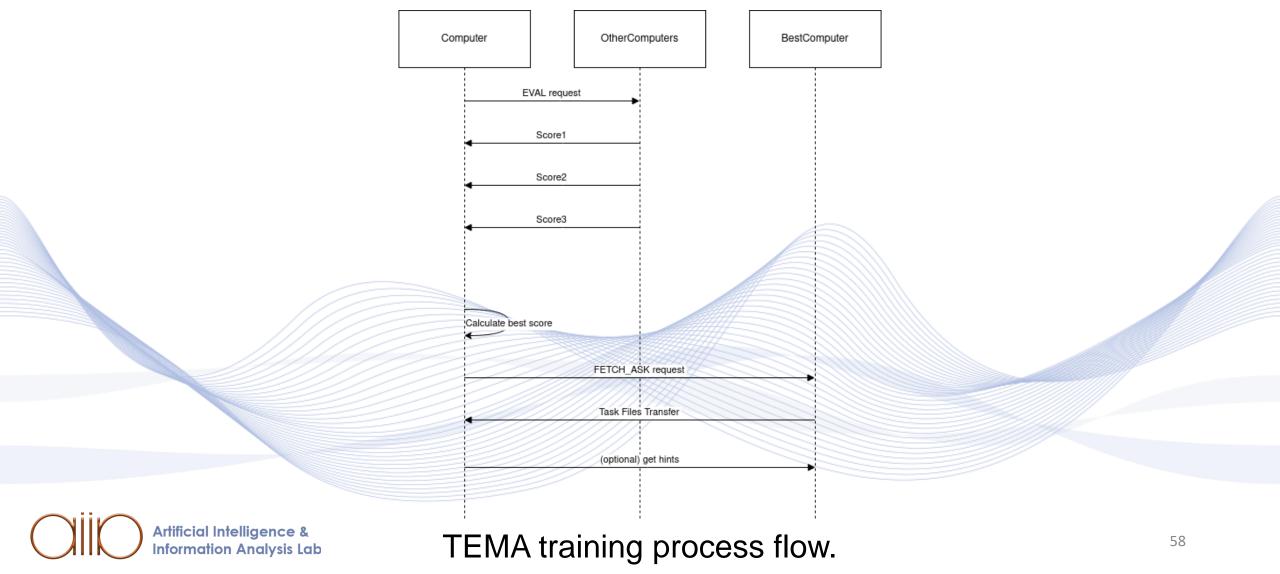




- The Student LENC node requests the files needed according to the option configuration (FETCH TASK request) from the picked potential Teacher LENC node.
- Files are '.bin' for datasets and '.pth' for teacher soft-output activation, weights and structure.
- The Student LENC node uses the received files to train a new Decision Head, but without forgetting the previous tasks learned.







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Thank you very much for your attention!

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