

# Parameter estimation summary

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# Parameter estimation

- Data analysis needs:
  - Probabilistic data modeling
  - Estimation of pdf parameters
- Pdf parameters to be estimated
  - Location and dispersion parameters
- Maximum Likelihood Parameter Estimation
  - ML Estimation for Gaussian Distributions
  - ML Estimation for Laplacian Distributions
  - Robustness of arithmetic mean and median
- Maximum a Posteriori Probability Estimation

# Maximum Likelihood Parameter Estimation

- $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$  random samples following joint probability distribution  $p(\mathbf{x}; \boldsymbol{\theta})$ .
- $\mathcal{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\}$ : set of the  $N$  data samples.
- Assuming statistical independence between the different samples:

$$p(\mathcal{X}; \boldsymbol{\theta}) \equiv p(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N; \boldsymbol{\theta}) = \prod_{k=1}^N p(\mathbf{x}_k; \boldsymbol{\theta}).$$

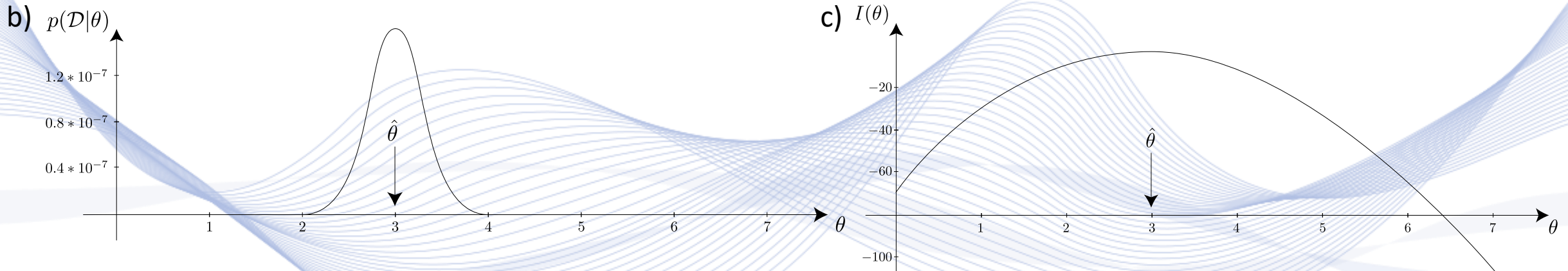
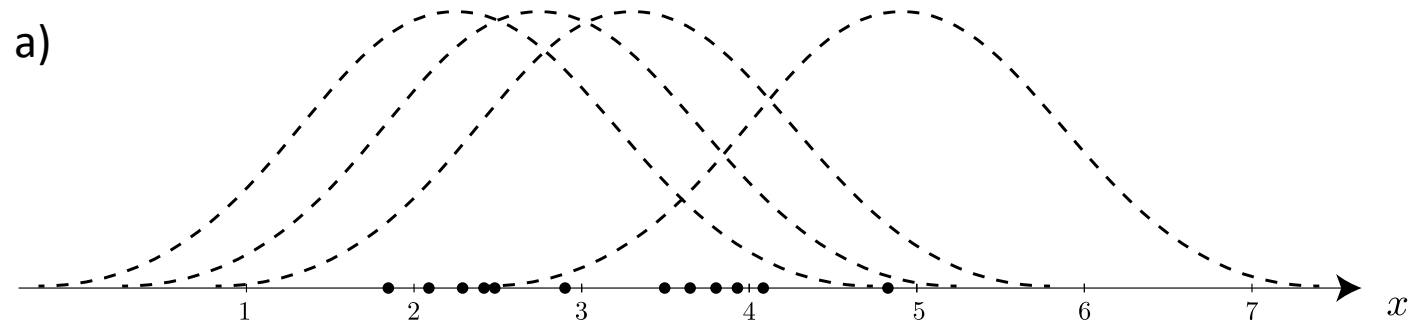
# Maximum Likelihood Parameter Estimation

*Maximum likelihood (ML) parameter estimation:*

- Pdf parameter vector  $\theta$  is estimated so that the likelihood function is maximized:

$$\hat{\theta} = \operatorname{argmax}_{\theta} \prod_{k=1}^N p(\mathbf{x}_k; \theta).$$

# ML Estimation for Gaussian Distributions



a) Pdf of unknown location and various data samples. b) Likelihood function; c) Log-likelihood function.

# 1D Propability Distributions

- Normal (Gaussian) distribution  $N(0,1)$ :

$$f_X(x) = \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{x^2}{2}\right\}.$$

- Uniform distribution  $U(0,1)$ :

$$f_X(x) = 1, \quad x \in [0,1].$$

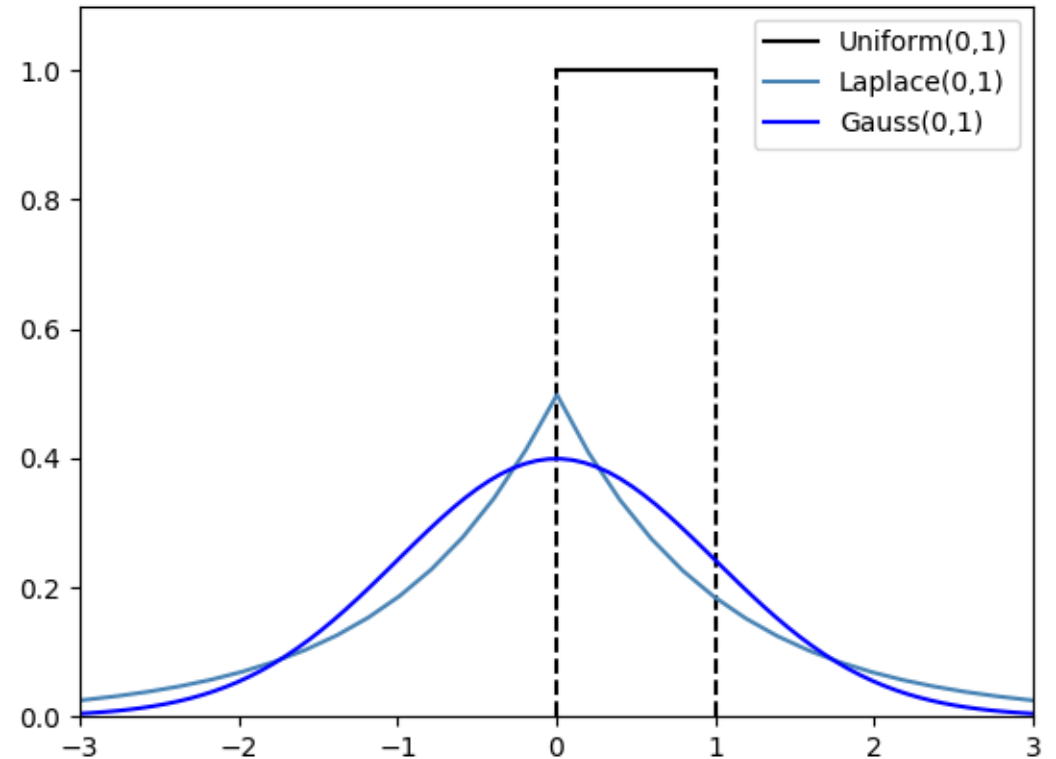
- Laplacian distribution:

$$f_X(x) = \frac{1}{2} e^{-|x|}.$$

# 1D Propability Distributions

- 1D probability distributions:
  - Uniform (short tailed)
  - Gaussian
  - Laplacian (short tailed)

Gauss-Laplace-Uniform Distributions



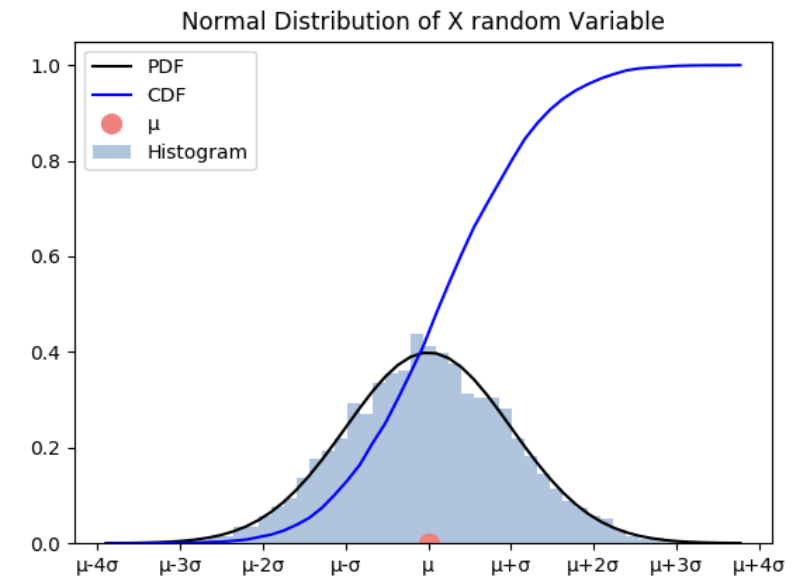
# 1D Propability Distributions

- Normal (Gaussian) distribution  
 $N(m, \sigma)$  :

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma}} \exp \left\{ -\frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 \right\}.$$

- 1D Laplacian probability distribution:

$$f_X(x) = \frac{1}{2} e^{-|x-a|}.$$





# Multidimension Gaussian distribution

- Multidimension Gaussian distribution:

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{\frac{n}{2}} \det(\mathbf{C})^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \mathbf{m})^T \mathbf{C}^{-1} (\mathbf{x} - \mathbf{m}) \right\}.$$

- $\mathbf{C}$ : covariance matrix.
- $\det(\mathbf{C})$ : determinant of  $\mathbf{C}$ .

# Location and dispersion estimation

Typically, probability distributions are characterized by their:

- Location and
- Dispersion

Data samples  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$  are used to estimate the respective parameters.

- In 1D Gaussian distribution, the parameters to be estimated are:  $m, \sigma$ .
- In multidimensional Gaussian distribution, the parameters to be estimated are:  $\mathbf{m}$  ( $n$  parameters),  $\mathbf{C}$  ( $n^2$  parameters).

# ML Estimation for Gaussian Distributions

- In making estimation for Gaussian Distributions, we can discern two cases.
- Unknown mean value  $\mathbf{m}$ .
- Unknown mean value  $\mathbf{m}$ , and covariance matrix  $\mathbf{C}$ .
- There is also the case of estimator biases.

# ML Estimation for Gaussian Distributions

- The ML estimation for the mean value should satisfy

$$\sum_{k=1}^N \mathbf{C}^{-1} (\mathbf{x}_k - \mathbf{m}) = \mathbf{0}.$$

- By multiplying with the covariance matrix, we get:

$$\hat{\mathbf{m}} = \frac{1}{N} \sum_{k=1}^N \mathbf{x}_k.$$

# ML Estimation for Gaussian Distributions

- *Unknown mean value and covariance matrix*
- We do not know  $\mathbf{m}$ ,  $\mathbf{C}$  and assume that their  $n + n^2$  unknown parameters form parameter vector  $\boldsymbol{\theta}$ .
- The case for a single variable will be examined having two unknowns:
  - Location parameter  $m$ .
  - Dispersion parameter  $\sigma^2$ .

# ML Estimation for Gaussian Distributions

- In the above conditions,  $\hat{\theta}_1$  and  $\hat{\theta}_2$  are the ML estimations for  $\theta_1$  and  $\theta_2$  respectively.
- By substituting  $\hat{\theta}_1$  with  $\hat{m}$  and  $\hat{\theta}_2$  with  $\hat{\sigma}^2$ , we get the following ML estimations:

$$\hat{m} = \frac{1}{N} \sum_{k=1}^N x_k, \quad \hat{\sigma}^2 = \frac{1}{N} \sum_{k=1}^N (x_k - \hat{m})^2.$$

# ML Estimation for Gaussian Distributions

- For multiple variable estimations, the formulae adapt to the new conditions:

$$\hat{\mathbf{m}} = \frac{1}{N} \sum_{k=1}^N \mathbf{x}_k, \quad \hat{\mathbf{C}} = \frac{1}{N} \sum_{k=1}^N (\mathbf{x}_k - \hat{\mathbf{m}})(\mathbf{x}_k - \hat{\mathbf{m}})^T$$

- Once again, the ML estimation for the mean value, is just the average sample value.

# ML Location Estimation for 1D Laplacian Distribution

- Now suppose the samples  $x_i, i = 1, \dots, N$  come from an 1D Laplacian probability distribution:

$$p(x; \theta) = \frac{1}{2} e^{-|x-\theta|}.$$

- The log-likelihood function  $L(\theta)$  has the form:

$$L(\theta) = -2 \ln 2 - \sum_{i=1}^N |x_i - \theta|.$$



# Robustness of arithmetic mean and median

For  $N$  data samples  $x_i, i = 1, \dots, N, N = 2\nu + 1$ :

- The arithmetic mean is given by:

$$\mu = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i$$

and the median  $x_{(\nu+1)}$ .

- Any outlier  $c \gg x_i, i = 1, \dots, N$  or  $c \ll x_i, i = 1, \dots, N$ :
  - influences significantly the arithmetic mean.
  - the median remains robust if less than  $\nu$  outliers occur.

# Maximum a Posteriori Probability Estimation

- We will consider  $\theta$  as a random vector.
- Estimate its value on the condition that  $N$  data samples  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$  are known.
- Starting point is:  $p(\theta|\mathbf{X})$ .
- From Bayes theorem:

$$p(\theta)p(\theta|\mathbf{X}) = p(\theta|\mathbf{X})p(\mathbf{X}) \text{ or } p(\theta|\mathbf{X}) = \frac{p(\theta)p(\mathbf{X}|\theta)}{p(\mathbf{X})}$$

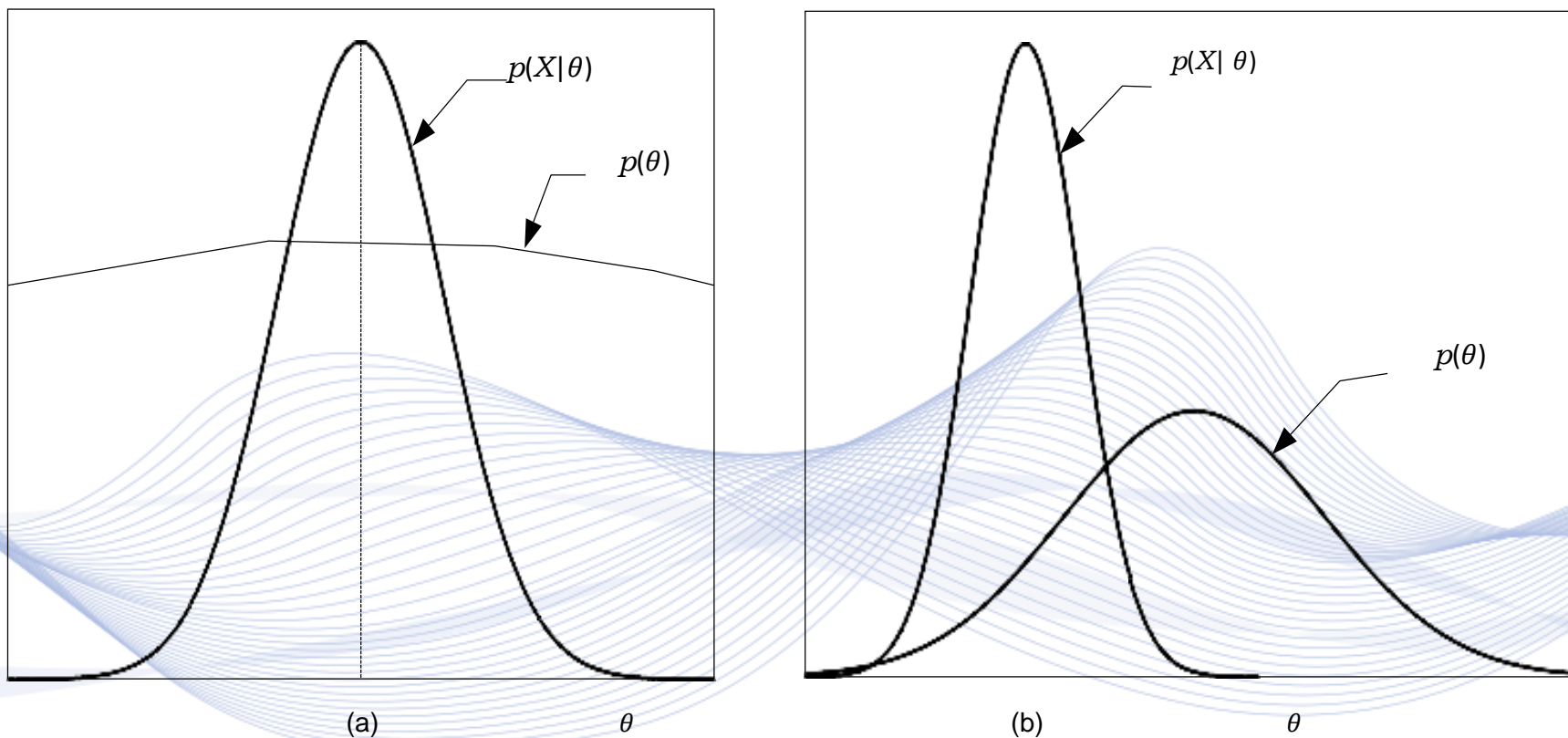
# Maximum a Posteriori Probability Estimation

- The maximum a posteriori probability (MAP) estimate  $\hat{\theta}_{MAP}$  is defined at the point where  $p(\theta|\mathbf{X})$  becomes maximum.

$$\nabla_{\theta} p(\theta|\mathbf{X}) = \nabla_{\theta} (p(\theta)p(\mathbf{X}|\theta)) = \mathbf{0}.$$

- The difference between the ML and the MAP estimates lies in the involvement of  $p(\theta)$ .
- If it is assumed that  $p(\theta)$  is uniform distribution, ML and MAP of  $\theta$  are identical.

# Maximum a Posteriori Probability Estimation



# Parameter estimation uses

- Use in Bayesian Learning
- Use in Hypothesis Testing:
  - Whether a data point belongs to a certain pdf
  - Whether a data point belongs to one of two pdfs
  - Whether two pdfs are identical.

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# Q & A

**Thank you very much for your attention!**

**More material in  
<http://icarus.csd.auth.gr/cvml-web-lecture-series/>**

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