

Introduction to Image Processing

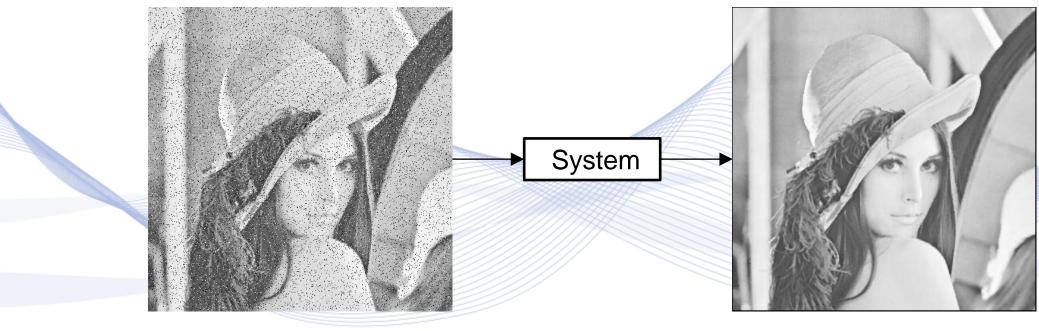
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Definition of image processing

Digital image processing system
 Input: image

Output: image





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Image Processing overview

- Image processing
- Image analysis
- Image data types
- Related disciplines





Image Processing overview

- Image acquisition
- Image filtering
 - Contrast Enhancement
 - Pseudocoloring
 - Image Halftoning
 - Image Interpolation
- Image compression





Digital image filtering









Image contrast enhancement





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Image pseudocoloring





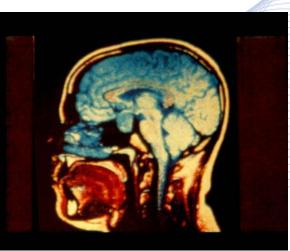
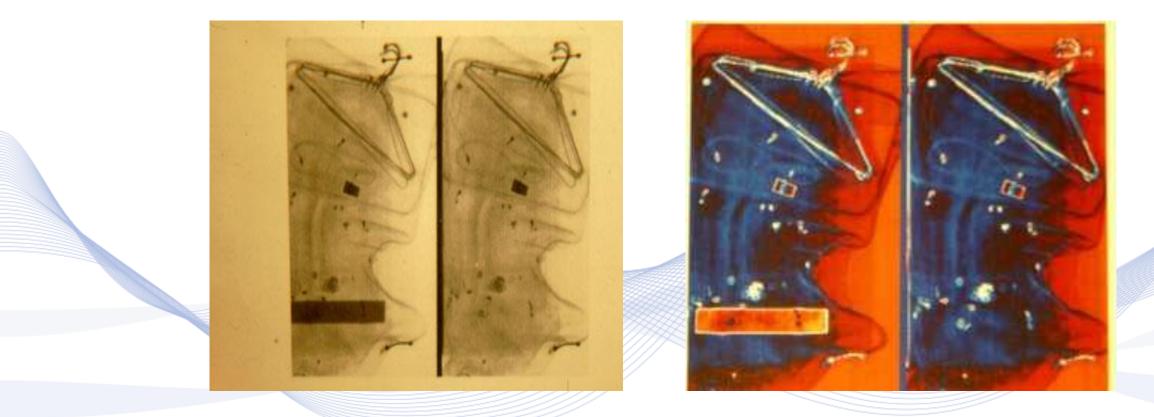






Image pseudocoloring



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Digital image halftoning

• Greyscale Binary Fonts





Original Image

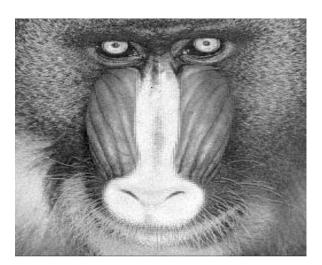
Original Image subsampled by a factor of 2 Halftoned Image using grayscale binary fronts

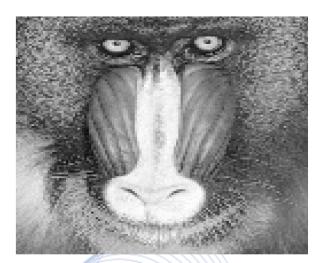




Image interpolation

BABOON image

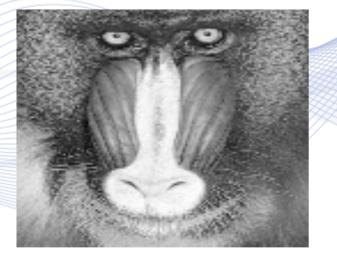




Output image after zero-order interpolation

Output image after linear interpolation

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Output image after cubic spline interpolation



Image compression

(a) Original image

(b) JPEG compressed image

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Image Processing overview

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Definition of image analysis



• Input: image

Output: symbolic description

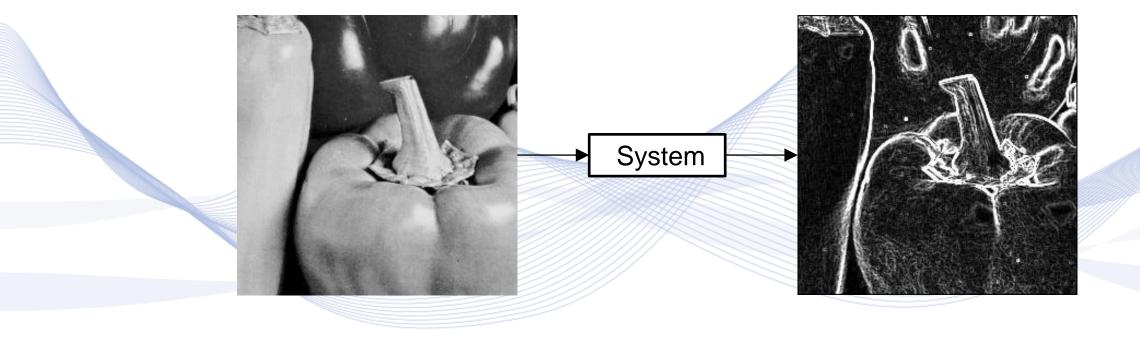




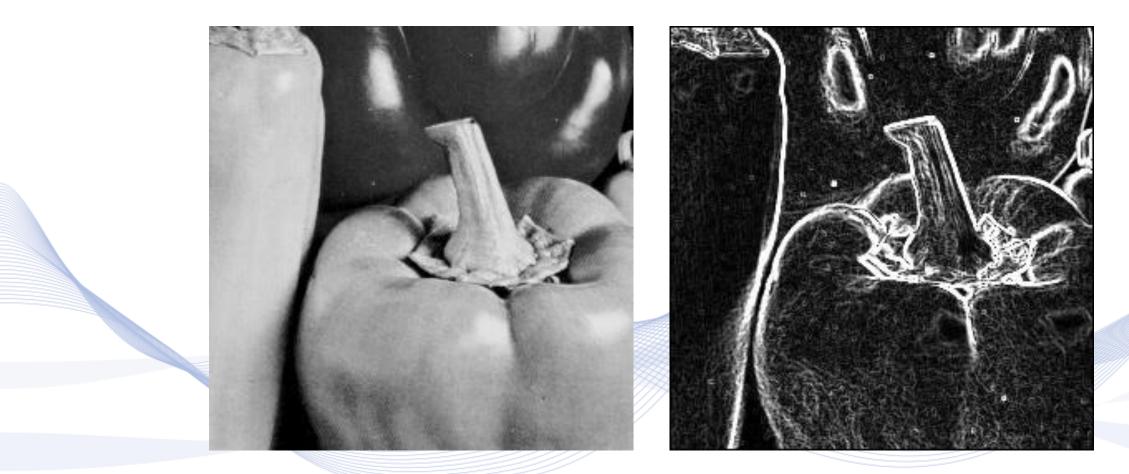
Image Analysis overview

- Region segmentation
- Edge detection
- Shape description
- Other terms used: 2D computer vision.





Edge detection







Region segmentation

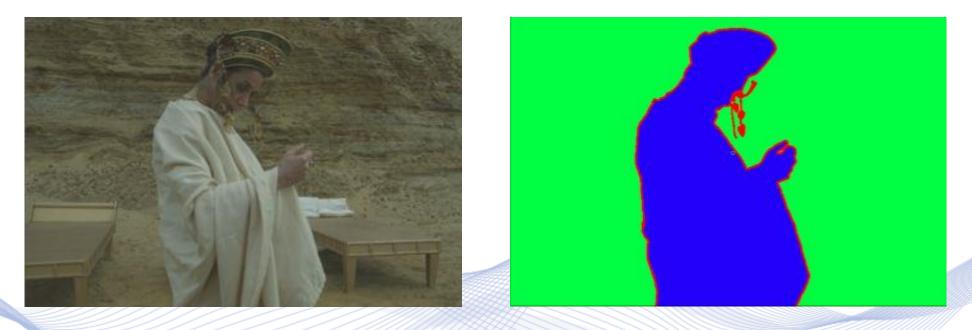


Image thresholding.





Region segmentation



Foreground and background segmentation.





Region segmentation

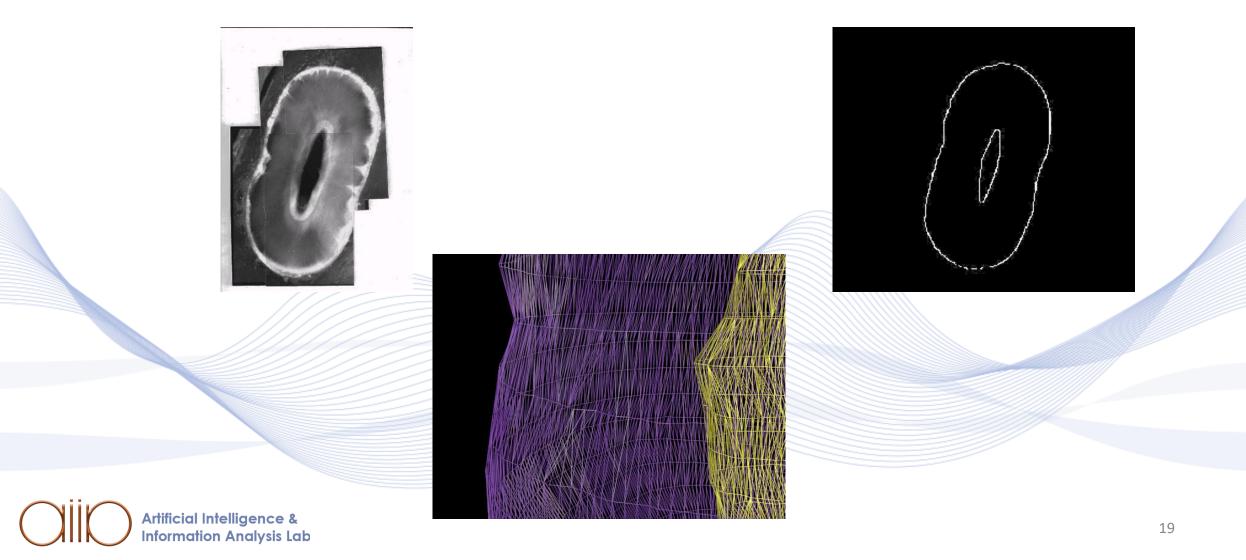


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Street scene segmentation [APOLLO].

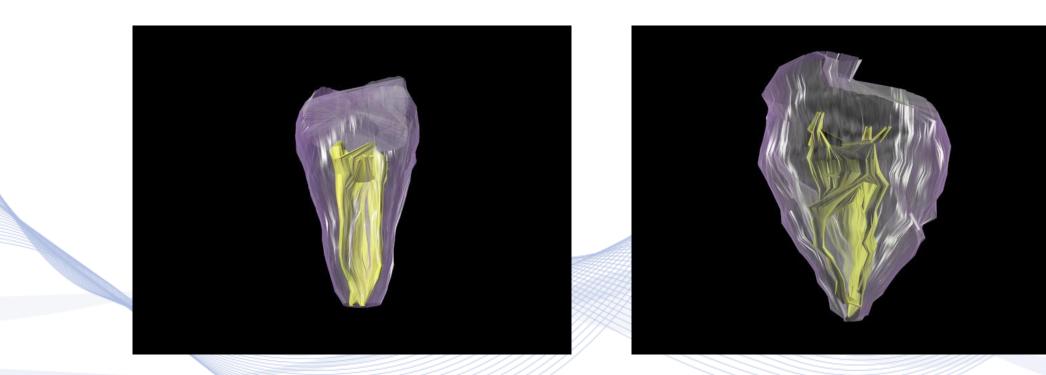


Contour following





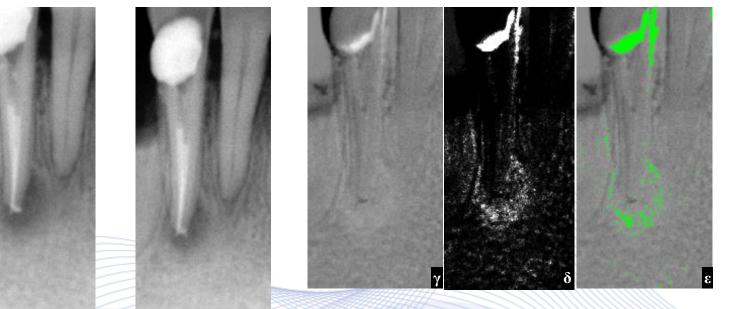
3D object modeling







2D Image registration

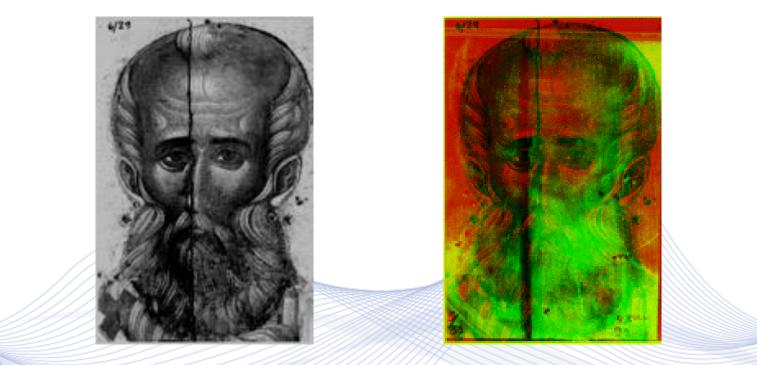


2D image registration and subtractive radiography.





2D Image registration



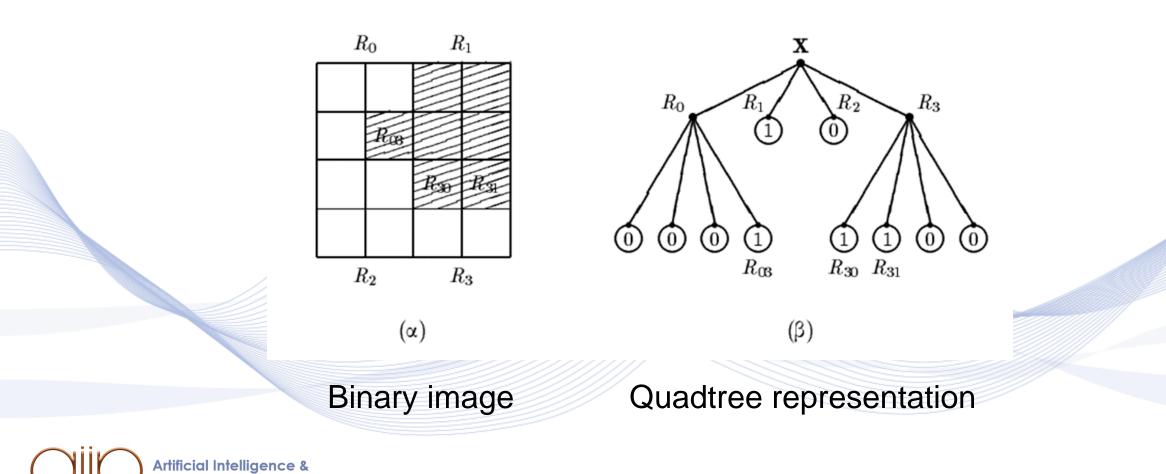
2D image registration: visible+xray painting image.





Shape description

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Image Processing overview

- Image processing
- Image analysis
- Image data types
- Related disciplines





1D data types: 1D signals

• 1D signals:

- temporal 1D signals of the form: $f(t): \mathbb{R} \to \mathbb{R}$, having:
 - domain \mathbb{R} and codomain \mathbb{R} .
- Audio signals, music signals,
- Biomedical signals: ECG. EEG, EMG
- 1D spatial signals of the form: $f(x): \mathbb{R} \to \mathbb{R}$
 - Traffic load along a street.





1D data types: 1D signals

Single variable functions are 1D signals:

• Sine/cosine functions/signals $\mathbb{R} \to \mathbb{R}$:

 $f(t) = \cos(\Omega t) = \cos(2\pi F t).$

• Complex-valued 1D signals $\mathbb{R} \to \mathbb{C}$:

 $f(t) = \exp(i\Omega t) = \cos(\Omega t) + i\sin(\Omega t).$

Multichannel signals have the form: $f(t): \mathbb{R} \to \mathbb{R}^n$

- Stereo music signal: $\mathbf{f}(t) = [f_l(t), f_r(t)]^T : \mathbb{R} \to \mathbb{R}^2$
- 7.1 surround music sound: $\mathbf{f}(t) = [f_0(t), \dots, f_7(t)]^T \colon \mathbb{R} \to \mathbb{R}^8$





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1D data types: 1D signals

- Multichannel biomedical recordings $f(t): \mathbb{R} \to \mathbb{R}^n$.
 - ECG, EEG recordings.

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Spatial coordinates x, y.



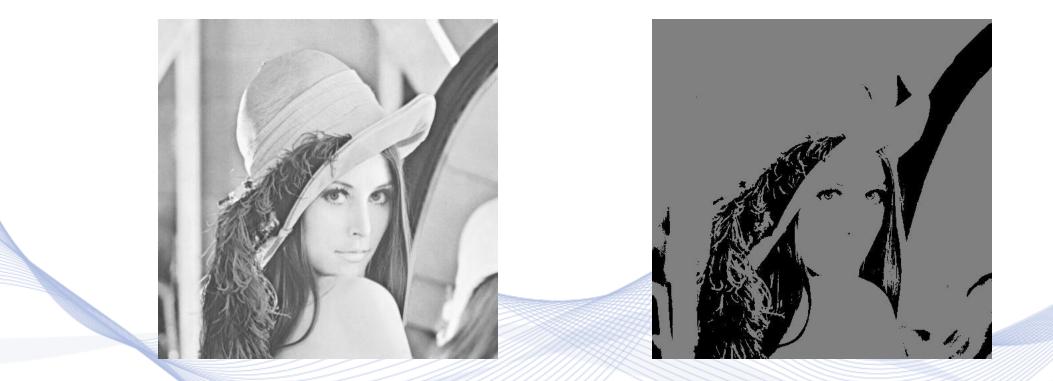


- Still images/pictures: spatial 2D signals of the form $f(x, y): \mathbb{R}^2 \to \mathbb{R}$, having:
 - domain \mathbb{R}^2 and codomain \mathbb{R} .
 - two spatial coordinates *x*, *y*.
- Image sampling/digitazation transforms continuous coordinates images to digital images:

 $f(n_1,n_2):\mathbb{Z}^2\to [0,\ldots,2^B-1].$







a) Grayscale image b) binary image.





- Digital images consist of *pixels* (picture elements).
- A *grayscale image* has *B* bits per pixel. If *B* = 8, each pixel has 256 gray shades:
 - 0 black, 255 'white'.
- Also called Black and white (BW) images.
- A binary image has 1 bit per pixel: black/white.





• Color digital images are multichannel (vectorial) images with three channels Red (R), Green (G), Blue (B):

 $\boldsymbol{f}(n_1, n_2) = [f_R(n_1, n_2), f_G(n_1, n_2), f_B(n_1, n_2)]^T \colon \mathbb{Z}^2 \to [0, \dots, 2^B - 1]^3.$







Color image.



3D data types: hyperpectral images



• *Multispectral/ multichannel images* have the form:

 $\boldsymbol{f}(\boldsymbol{x},\boldsymbol{y}): \mathbb{R}^2 \to \mathbb{R}^n.$

- color images (n = 3): f(x, y): $\mathbb{R}^2 \to \mathbb{R}^3$.
- digital color images (assigning 8 bits per color channel to each voxel):

$$f(n_1, n_2): \mathbb{Z}^2 \to \{0, \dots, 255\}^3.$$

• Hyperspectral images : $f(x, y, \lambda)$: $\mathbb{R}^3 \to \mathbb{R}$.

• λ wavelength.

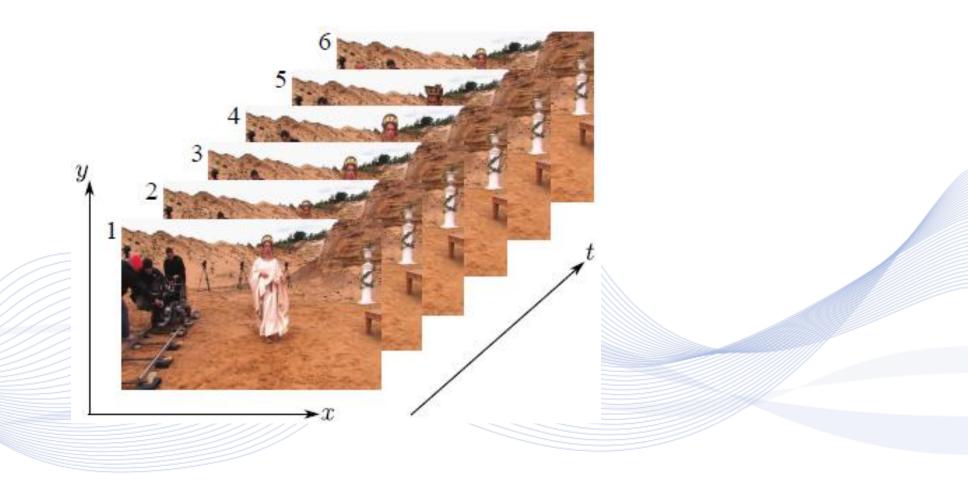
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3D data types: video





3D data types: video



- Moving images (videos) are spatiotemporal 3D signals of the form: f(x, y, t): $\mathbb{R}^3 \to \mathbb{R}$, having:
 - domain \mathbb{R}^3 and codomain \mathbb{R} .
 - the time *t* coordinate has a different nature than the spatial coordinates *x*, *y*.
- Video scanning: the process for obtaining an 1D analog
 video signal, by sampling video (luminance or RGB
 channels) along the vertical axis y and time t.



3D data types: video



- Analog video signal $f(x, j\Delta y, k\Delta t)$: $\mathbb{R} \times \mathbb{Z}^2 \to \mathbb{R}$.
 - discrete along y and t axes
 - continuous along *x* axis.
- **Digital video signal** $f(n_1 \Delta x, n_2 \Delta y, n_t \Delta t)$: $\mathbb{Z}^3 \to \mathbb{R}$.
- Spatial sampling intervals Δx , Δy define *image resolution*:
 - the smaller they are, the smaller the pixel size is.
- Temporal sampling interval Δt defines the video frame rate in frames per second (fps).



3D data types: volumetric images



- **3D** volumetric images: 3D signals of the form $f(x, y, z): \mathbb{R}^3 \to \mathbb{R}$.
- Discrete versions (defined on a Euclidean grid \mathbb{Z}^3) : $f(n_1, n_2, n_3): \mathbb{Z}^3 \to \mathbb{R}.$
 - $x = n_1 \Delta x$, $y = n_2 \Delta y$, $z = n_3 \Delta z$
 - $\Delta x, \Delta y, \Delta z$: **spatial sampling intervals** defining 3D image resolution.
 - Each voxel (volume element) is a real number.



3D data types : volumetric images



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3D data types



- *Multiview images* of an object or set are taken from different view points, typically using different cameras.
- Stereo images: a special multiview image case, employing only two cameras (left and right):

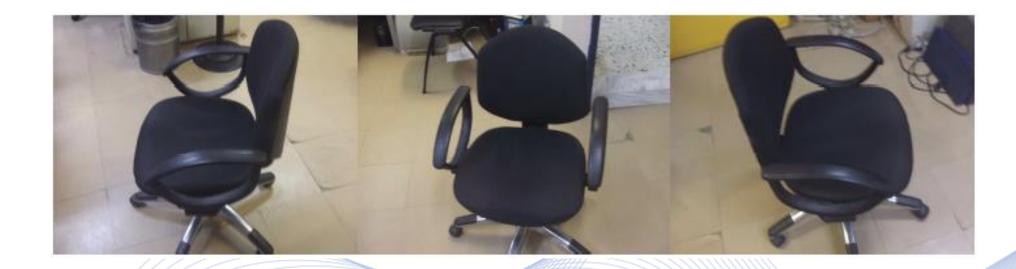
 $\boldsymbol{f}(n_1, n_2) = [f_l(n_1, n_2), f_r(n_1, n_2)]^T \colon \mathbb{Z}^2 \to [0, \dots, 2^B - 1]^2.$

- They both carry only implicit geometrical information about the visualized 3D object.
 - They are not 3D data.

• 3D object geometry can be derived using stereo or



3D data types



Multiview images.





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Related disciplines

- Digital signal processing (1D signals)
- Graphics (Digital image/animation synthesis)
- Machine Learning and Pattern Recognition
 - Application in image analysis.
- Artificial intelligence
- Social media

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- Image/video communication
- Multimedia data bases
- Digital media and television.

Bibliography



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[PIT2013] I. Pitas, "Digital Video and Television", Createspace/Amazon, 2013.
 [NIK2000] N. Nikolaidis and I. Pitas, "3D Image Processing Algorithms", J. Wiley, 2000.
 [PIT2000] I. Pitas, "Digital Image Processing Algorithms and Applications", J. Wiley, 2000.







Thank you very much for your attention!

More material in http://icarus.csd.auth.gr/cvml-web-lecture-series/

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