# Introduction to Human Centered Computing

(VML

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## **Human Centered Computing**



- Semantic Video Content Analysis
- Face/object detection and tracking
- Multiview human detection
- Face detection obfuscation
- Face recognition
- Face clustering
- Label propagation on videos
- Face De-identification
- 3D face reconstruction
- Facial expression recognition
- Facial feature detection
- Visual speech detection
- Shot type characterization



- Human body posture and pose estimation
- Activity/gesture recognition
- Athlete Motion Analysis
- Soccer Video Analysis
- Semantic video content description/annotation

#### Semantic Video Content Analysis & Description

- Video content can be described through state and state transitions of individuals, interactions or communication between humans and physical characteristics of humans:
  - human presence (face, head body),
  - movement,
  - activity/gesture,
  - facial expressions,
  - face/body pose,

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- number of people in a video shot,
- which people are in the shot (face recognition)
- Anthropocentric (human-centered) approach
  - humans are the most important video entity.
- Characteristics and behavior of other foreground entities such as objects can be also used for semantic description

## **Examples**



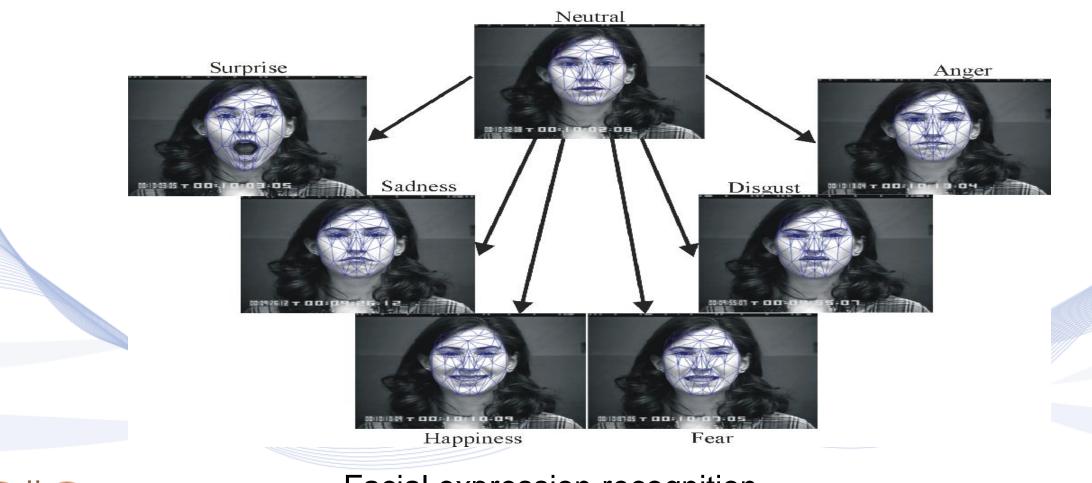


Face detection and tracking.



## **Examples**





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#### Facial expression recognition.

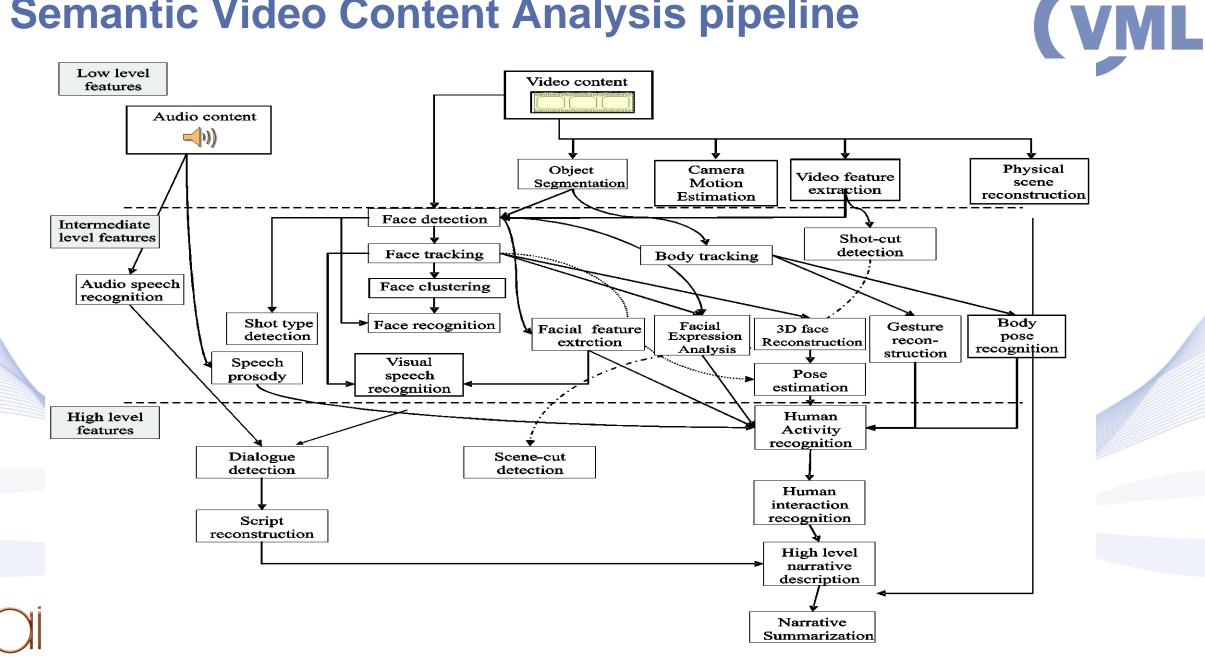
# **Relation between HCI operations**

- All these HCI operations are related.
- The outputs of some of them are used as input to some other.



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#### **Semantic Video Content Analysis pipeline**





#### Semantic Video Content Analysis & Description

#### **Applications:**

- Surveillance
  - Biometrics, behavior analysis
- Video content search (e.g., in professional video archives or YouTube)
  - Semantic annotation of video
  - Video archival, indexing and retrieval
  - Film and games postproduction:
    - Matting, 3D reconstruction



# Semantic Video Content Analysis Tasks

- Face/object detection and tracking
- Face clustering
- Face recognition
- 3D face reconstruction
- Facial expression recognition





# Semantic Video Content Analysis Tasks

- Multiview human detection
- Eye detection
- Visual speech detection
- Activity/gesture recognition
- Field size (shot type) characterization
- Semantic video content description/annotation



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## **Face Detection and Tracking**



 1st frame
 6th frame
 11th frame
 16th frame

 Image: Strain St

Problem statement:

- To detect the human faces that appear in each video frame and localize their *Region-Of-Interest* (*ROI*).
- To track the detected faces over the video frames.



# Face Detection and Tracking

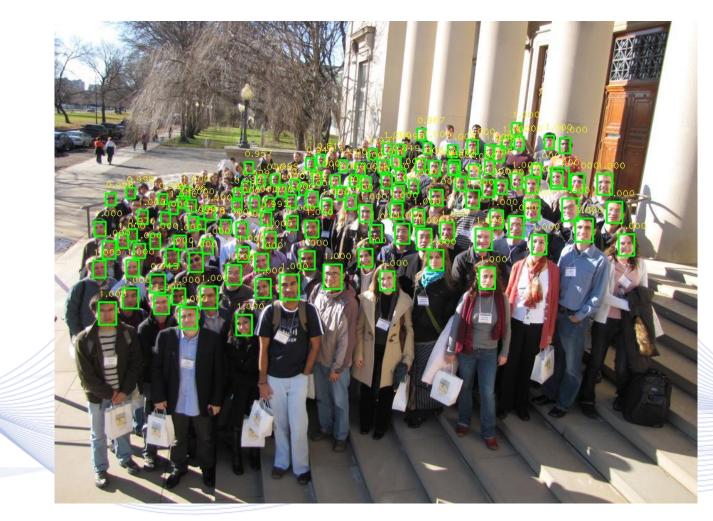


- Tracking associates each detected face in the current video frame with one in the next video frame.
- Therefore, we can describe the *facial ROI trajectory* in a shot in (x, y) coordinates.
  - Actor instance definition: face region of interest (ROI) plus other info
- Actor appearance definition: face trajectory plus other info



## **Face detection examples**







## **Face Detection and Tracking**



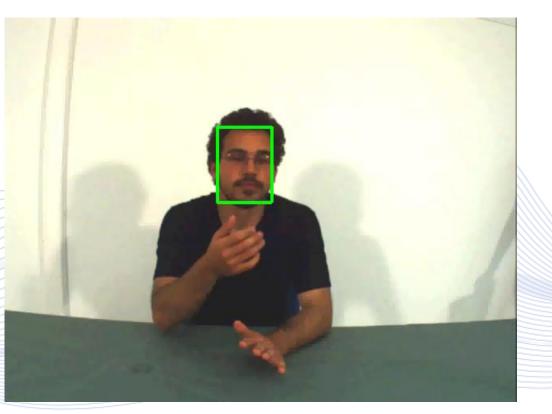
- Tracking failure may occur, i.e., when a face disappears.
- In such cases, face re-detection is employed.
- However, if any of the detected faces coincides with any of the faces already being tracked, the former ones are kept, while the latter ones are discarded from any further processing.
- Periodic face re-detection can be applied to account for new faces entering the camera's field-of-view (typically every 5 video frames).
- Forward and backward tracking, when the entire video is available.





## **Face/Object Tracking**

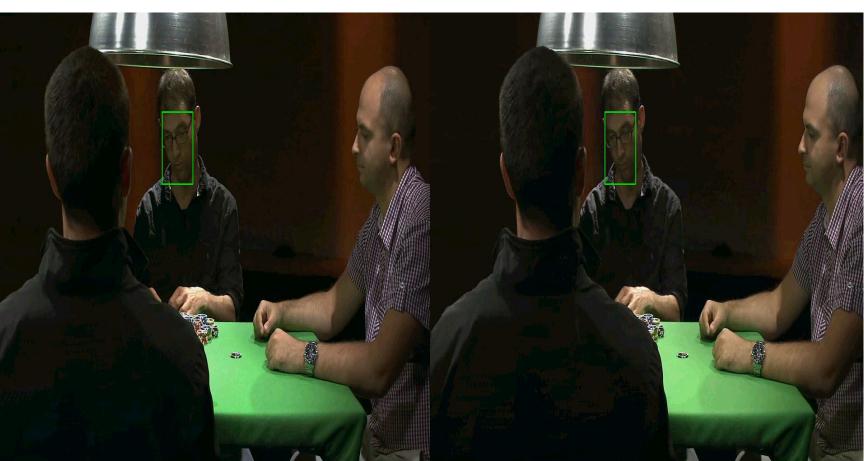
#### Experimental results





## Face Tracking in Stereo Videos

#### Experimental results



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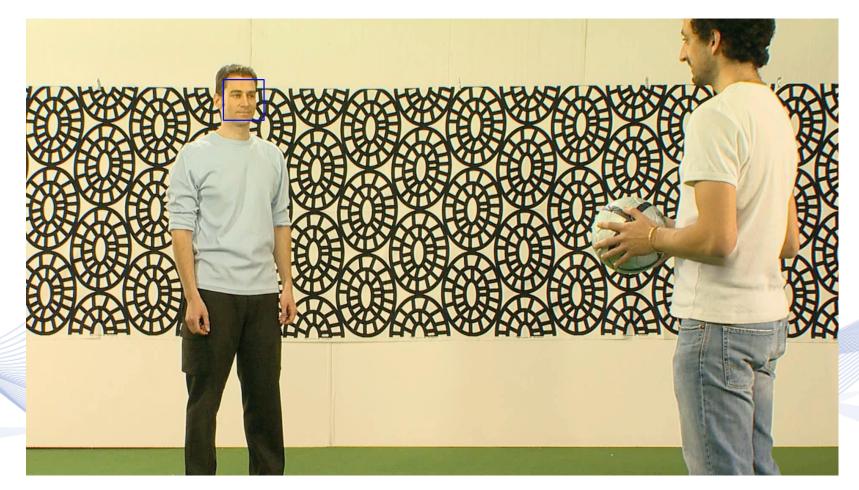
# Forward-Backward Tracking Motivation



- Forward in time tracking: different results than backward in time tracking.
   One mode of tracking may succeed where the other fails
- The key point: post-process the results of a forward and a backward tracking jointly, in order to refine the tracking results
- Same reasoning for stereoscopic video: performing tracking on both channels of a video provides us with more information than using only one.



# Forward-Backward Stereo Tracking ML Results



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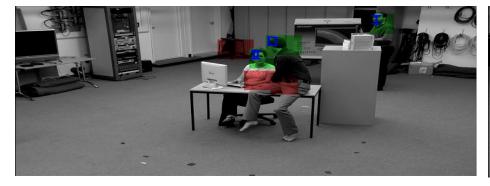
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#### **Problem statement:**

• Use information from multiple cameras to detect bodies or body parts, e.g. head.

Camera 6



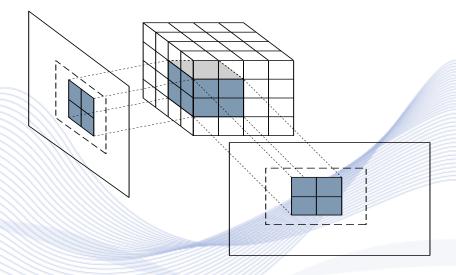
Applications: Camera 4

Human detection/localization in postproduction. Matting / segmentation initialization.





- Detected ROIs are projected back in the 3D space.
- •A "probability volume" is created collecting "votes" from individual ROIs.
- High probability voxels correspond to the most probable head/body VOIs.

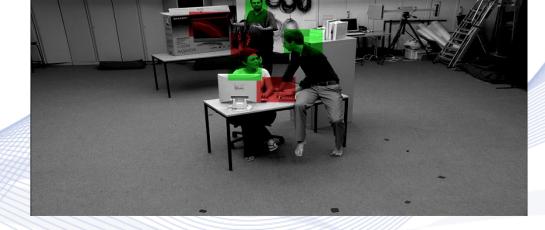






- The retained voxels are projected to all views.
- For every view we reject ROIs that have small overlap with the regions resulting from the projection.



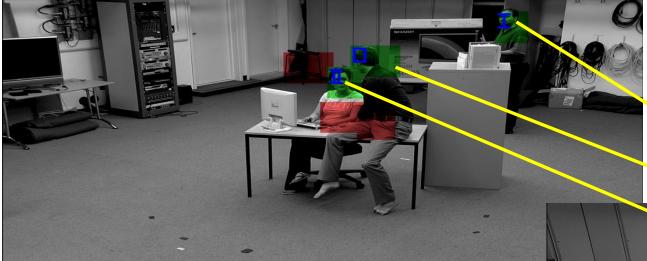


Camera 2

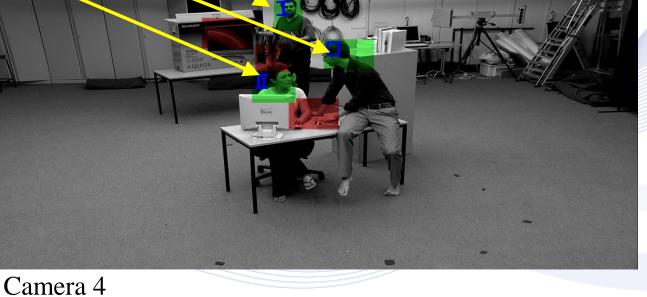








Camera 2





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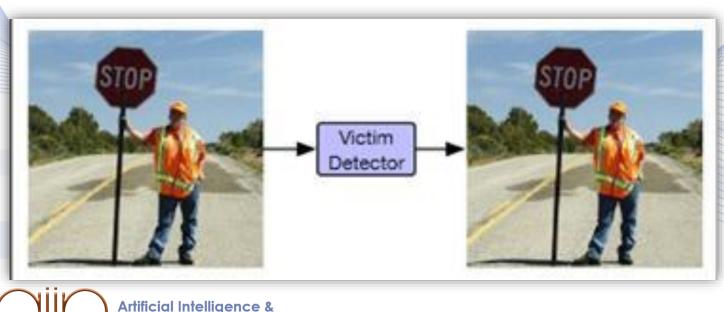
#### A completely different engineering problem

- Goal: The detector does not output correct facial ROIs.
- Relatively new area
- Different cases:
  - The detector does not detect faces;
  - The detector detects faces, but classifies them as something else;
  - The detectors detects too many faces, where they do not exist.
- It is a very useful privacy protection tool.



The detector does not detect faces (object-vanishing attack):

- all attacks against object detectors focus on objects with fixed visual patterns;
- do not take into account intra-class variety;
- adversarial patches can be used to fool person detectors;
- attack on targets with high level intra-class variety, like persons;
- detector does not detect any persons or objects
- "adversarial patch" used as a cloaking device to hide people from object detectors.



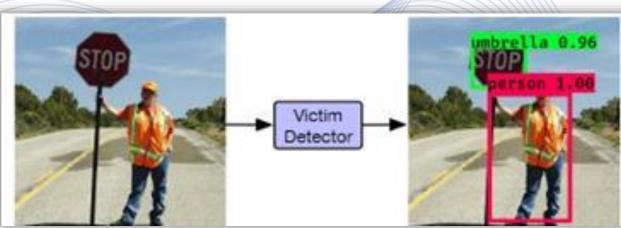
[24]. Object-vanishing attack. [CHO2020] K.-H. Chow, L. Liu, M. Loper, J. Bae, M.-E. Gursoy, S. Truex, W. Wei, Y. Wu, "Adversarial Objectness Gradient Attacks in Real-time Object Detection Systems", in *IEEE International Conference on Trust, Privacy and Security in Intelligent Systems and Applications (TPS-ISA), pp. 263-272, 2020.* 

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The detector detects faces, but classifies them as something else (objectmislabeling attack):

- generate adversarial examples without having access to any information about the network parameter values or their gradients.
- The only input their technique requires is the probabilistic labels predicted by the targeted model.
- adversarial attacks misleads the autoencoder to reconstruct a completely different image





The detector detects faces, but classifies them as something else (object-fabrication attack): the object-mislabeling attack fools the detector to mislabel detected objects (e.g., stop sign as an umbrella), which can result in disastrous consequences.



[26]. Object-vanishing attack. https://khchow.com/media/TPS20\_TOG.pdf



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## **Face Recognition**



Three general approaches:

- Deep Neural Networks (state of the art)
- Subspace methods
- Elastic graph matching methods.



## **Face Recognition**



#### **Subspace methods**

• The original high-dimensional image space is projected onto a lowdimensional one.

• Face recognition according to a simple distance measure in the low dimensional space.

 Subspace methods: Eigenfaces (PCA), Fisherfaces (LDA), ICA, NMF, Class Specific NMF (CSNMF).

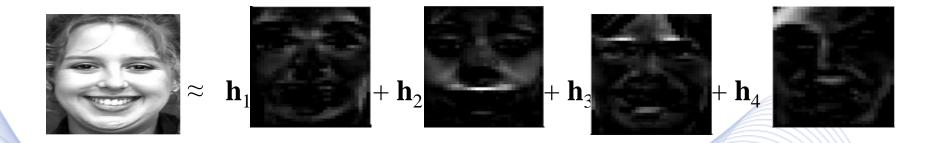
• Main limitation of subspace methods: they require perfect face alignment (registration).



## **Face Recognition - NMF**



- Original facial images are reconstructed using only additive combinations of the resulting basis images.
- Combination weights: coefficients in **H**.



 Consistent with the psychological intuition regarding the objects representation in the human brain (i.e. combining parts to form the whole).



## **Face Recognition**



#### Elastic graph matching (EGM) methods

- Elastic graph matching is a simplified implementation of the Dynamic Link Architecture (DLA).
- DLA represents an object by a rectangular elastic grid.
- A Gabor wavelet bank response is measured at each grid node.
- Multiscale dilation-erosion at each grid node can be used, leading to Morphological EGM (MEGM).





## **Face Recognition**



Output of normalized multi-scale dilation-erosion for nine scales.



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## **Face Clustering**

#### **Problem statement:**

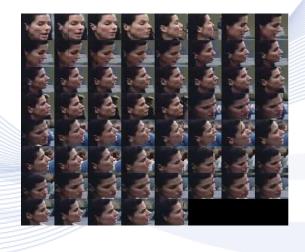
- To cluster a set of facial ROIs
- Input: a set of face image ROIs





- Output: several face clusters, each containing faces of only one person.
- Applications

Cluster actor images, even if they belong to different shots. Cluster various views of the same actor. Generate the cast of a movie. Semi automatic face recognition





### **Face Clustering**



A four step clustering algorithm is used:

- Face detection and/or tracking.
- Calculation of a similarity matrix in order to create a similarity graph.
   Similarity calculation between facial images using either mutual information or local steering kernels or any other similarity criterion.
- Application of face trajectory heuristics, to improve clustering performance.
- Similarity graph clustering.



# Facial image clustering in videos



- In videos facial images can result from the application of face detection and tracking algorithms
- This leads to "facial trajectories": series of facial images of (usually) the same person over time

n frames tracked



- Each such facial trajectory can be represented by any of the images included in it.
- Facial image clustering in videos: cluster facial trajectories by using their representative images



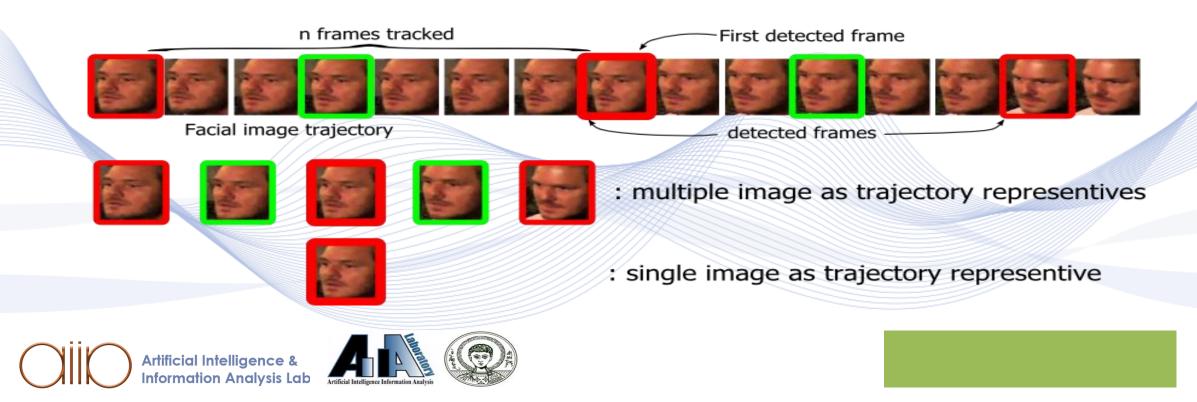


# Facial image trajectory representatives

- Two approaches to choose trajectory representative:
  - A single detected facial image

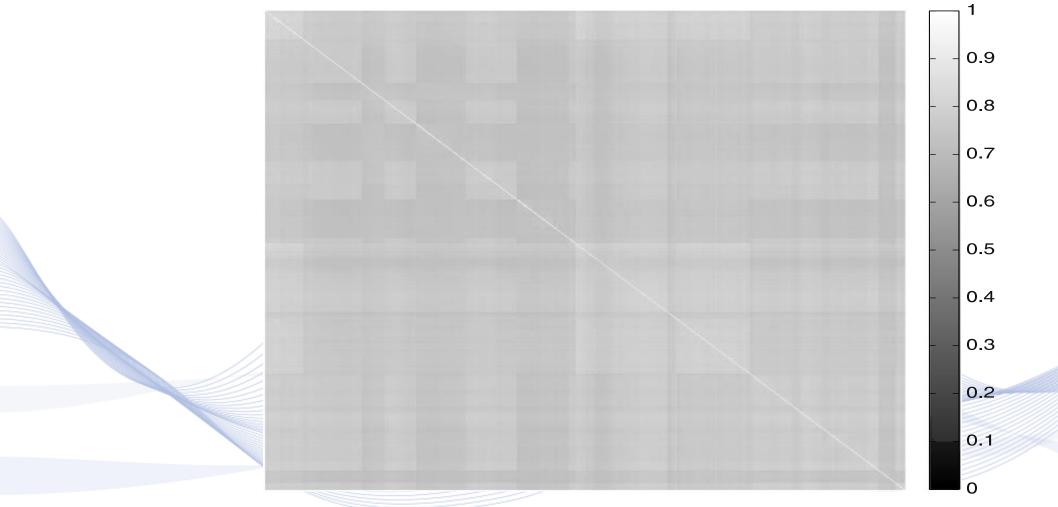
W

Multiple images from the trajectory



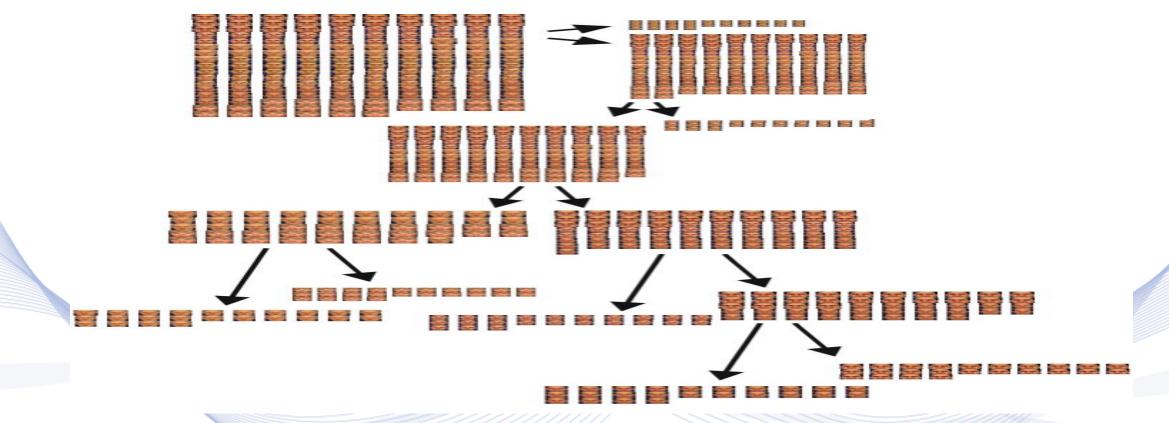
### **Face Similarity Matrix**





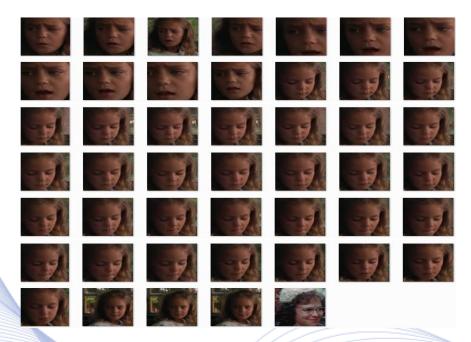
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### N-Cut Graph Clustering (2-way Partitioning) :

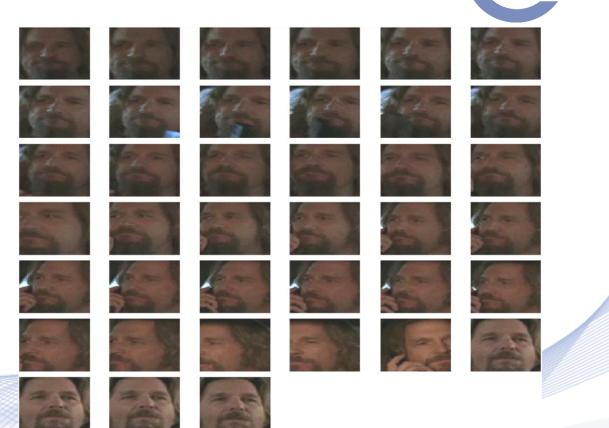




#### **Cluster Examples**



Images of different scales



Images of different illumination and poses



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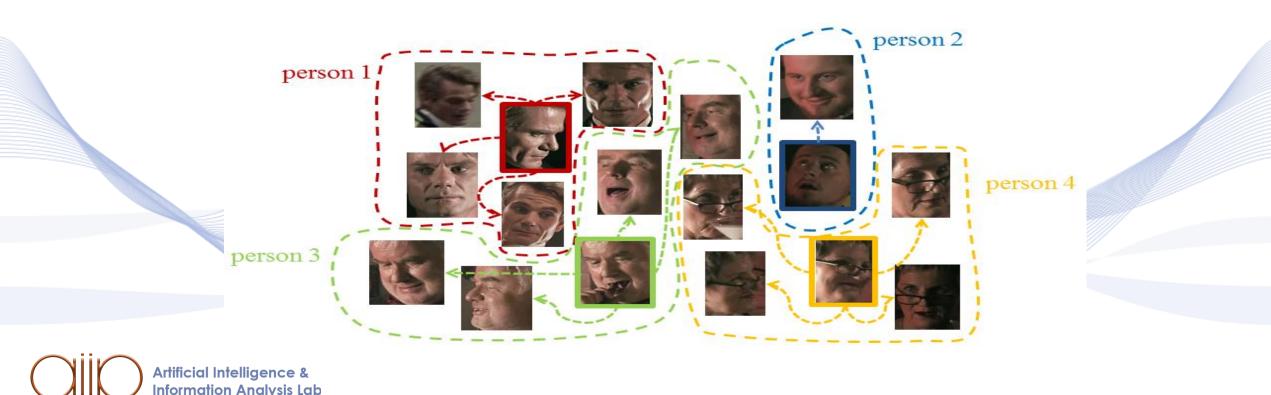


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# Label propagation on videos



• Label propagation is a label diffusion process from a small set of labeled data  $X_L = \{x_i\}_{i=1}^{n_l}$  to a larger set of unlabeled data  $X_U = \{x_i\}_{i=1}^{n_u}$ 



## Label propagation on videos



Label propagation algorithms satisfy the following conditions:

- They preserve the labels of the initially labeled data.
- They assign the same label to similar samples or to samples that lie in the same structure of the feature space.





# Label propagation on videos

 The performance of label propagation algorithms depends highly on The data representation method (the data graph construction)
 The selection of the initially labeled data set



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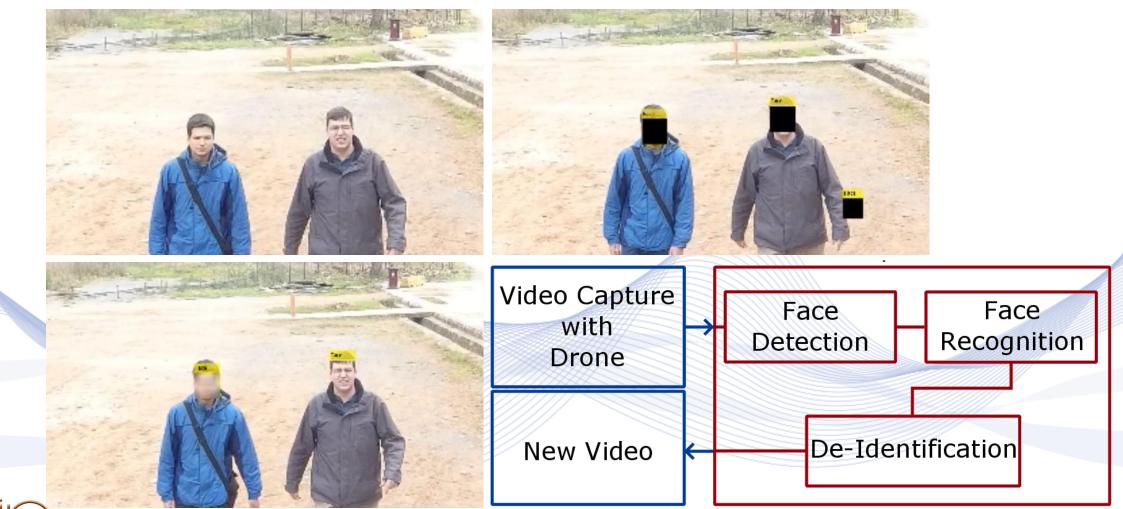
#### **Face De-identification**



- Face de-identification (Face recognizer obfuscation):
  - Corrupt the facial region so that deep NN face classifiers fail.
  - Developed methodology:
    - Simple/Naive approaches (additive noise, impulsive noise)
    - Reconstruction-based (SVD, PCA, hypersphere projections, auto-encoder-based) approaches.
    - Autoencoder face de-identification.
    - GAN face de-identification.
    - Adversarial face de-identification.

# Face De-identification on drone videos





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#### **Face De-Identification**

Model A



Adversarial Face De-Identification

First row: original image; Second row: de-identified image. Third row: adversarial perturbation absolute value (x10) [CHA2019].

#### **Problem statement:**





- Input: facial images or facial video frames, taken from different view angles, provided that the face neither changes expression nor speaks.
- Output: 3D face model (saved as a VRML file) and its calibration in relation to each camera. Facial pose estimation.
- Applications:
  - 3D face reconstruction, facial pose estimation, face recognition, face verification.



#### **Method overview**

- Manual selection of characteristic feature points on the input facial images.
- Use of an uncalibrated 3-D reconstruction algorithm.
- Incorporation of the CANDIDE generic face model.
- Deformation of the generic face model based on the 3-D reconstructed feature points.
- Re-projection of the face model grid onto the images and manual refinement.



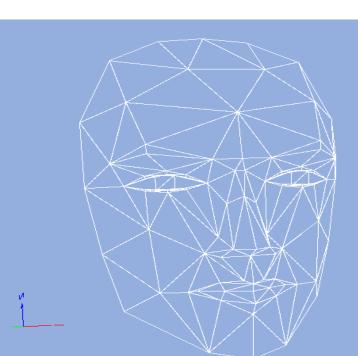


VML

Input: three images with a number of matched characteristic feature points.



- The CANDIDE face model has 104 nodes and 184 triangles.
- Its nodes correspond to characteristic points of the human face, e.g. nose tip, outline of the eyes, outline of the mouth etc.

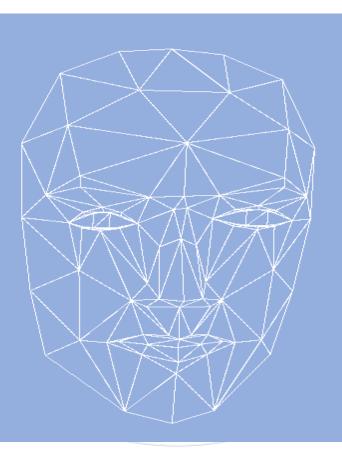


ML









VML





**Selected features** 



CANDIDE grid reprojection



3D face reconstruction



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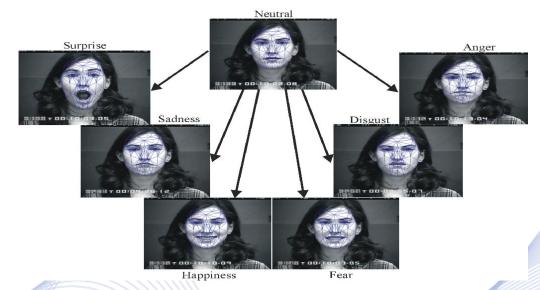
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## Facial Expression Analysis

#### **Problem statement:**

- To identify a facial expression in a facial image or 3D point cloud.
- Input: a face ROI or a point cloud
- Output: the facial expression label
- (e.g. neutral, anger, disgust, sadness, happiness, surprise, fear).







### Universal Facial Expressions



 Six universal facial expressions:

□ Anger

□ Fear

- Disgust
- HappinessSadness
- Surprise

#### Neutral















# Informative Content of Facial Expressions



- Human communication is mainly performed by nonverbal means (gestures and facial actions).
- Facial actions: important source for understanding human emotional state and intention.
- Key importance to various fields e.g. human behavior analysis, affective video content description, psychology, HCI, ambient intelligence, entertainment etc.



# Facial Expression Analysis



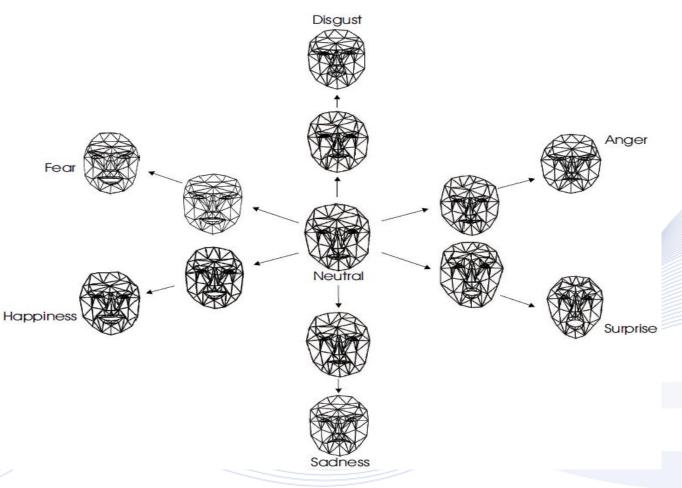
- Latent facial image data dimensionality
   Facial image space dimensionality is much higher than required.
   Necessitates the use of efficient dimensionality reduction methods.
   Reduce complexity and boost performance of expression analysis algorithms.
- Three popular approaches to handle facial expression data high dimensionality:
  - Deep Neural Networks (state of the art)
  - Grid-Based Methods.
  - Subspace Learning Methods.





#### **Grid-Based Methods**

- A facial grid is a parameterized face mask specifically developed for model-based coding of human faces.
- A popular facial wireframe model is the Candide grid.
- Facial expression information extraction is performed by facial feature point tracking.





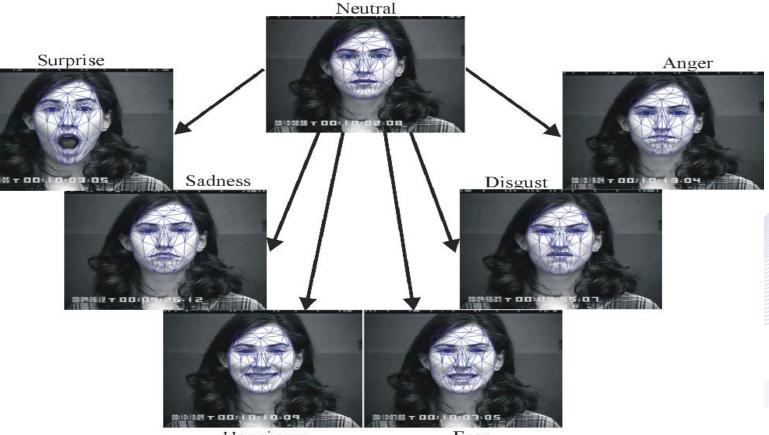
#### **Grid-Based Methods**



• Expression recognition:

Track geometric positions of the grid nodes corresponding to fiducial points on a face;

Grid nodes displacements are used as classification features.



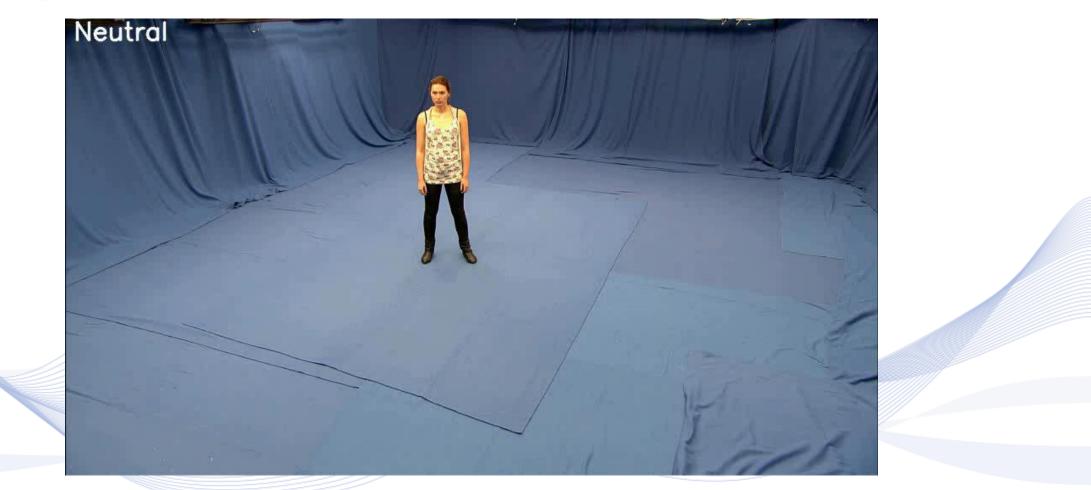
Happiness

Fear





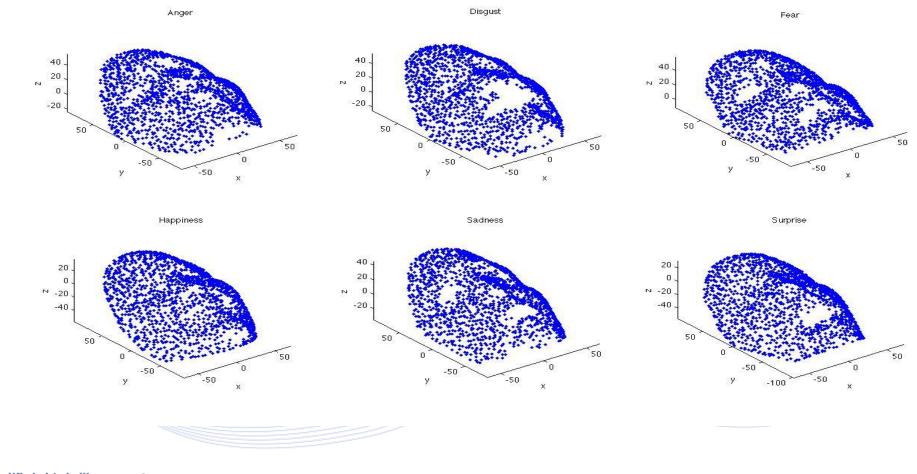
#### **Experimental Results**







• Use of 3D facial point clouds.



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# **3D Facial Expression Recognition**



- Tackling global geometric transforms: Rotation, translation, scaling.
- A new coordinate system is created:
   Origin: point cloud center of mass.
   Axes: principal axes found by Principal Components Analysis.
  - All points are projected in the new coordinate system.



# **3D Facial Expression Recognition**



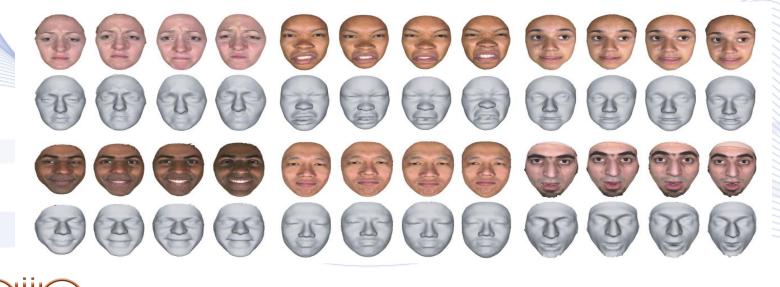
- A multi class SVM classifier is used for facial expressions recognition.
   Input: point clouds representation in the normalized PCA space.
- Correspondences between points in different clouds (faces) are required.
- The same method can be used for face recognition.



# **3D Facial Expression Recognition**

 Experiments on the BU-3DFE database 100 subjects.

6 facial expressions x 4 different intensities +neutral per subject.83 landmark points (used in our method).



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#### **Facial feature detection**





Face images having noted facial landmarks



111

#### Facial feature detection



#### **Eye Detection:**

• To detect eye regions in an image.



- Input: A facial ROI produced by face detection or tracking
- Output: eye ROIs / eye center location.
- Applications:

face analysis e.g. expression recognition, face recognition, etc

gaze tracking.

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## **Facial feature detection**

Training data



a) The left eye training images



b) The right eye training images



c) The length maps for the left image eye



e)The angle maps for the left eye image



d) The length maps for the right image eye

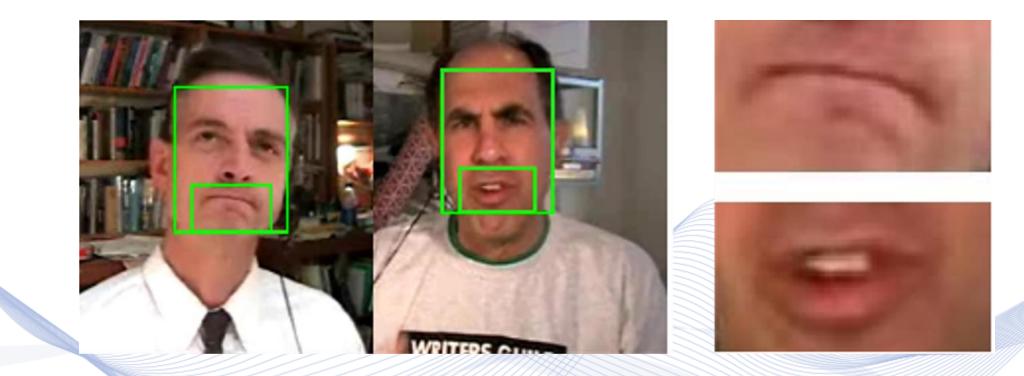


f) The angle maps for the right eye image



### **Facial feature detection**





Face and mouth within bounding boxes, and mouth of both persons extracted



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## **Visual Speech Detection**

#### **Problem statement:**

- To detect video frames where a persons speaks using only visual information
- Input: A mouth ROI produced by mouth detection
- Output: yes/no visual speech indication.
- The mouth is detected and localized by a similar technique to eye detection.







## **Visual Speech Detection**

• Applications

Detection of important video frames (when someone speaks) Lip reading applications Speech recognition applications Speech intent detection and speaker determination

- human--computer interaction applications
- video telephony and video conferencing systems.

Dialogue detection system for movies and TV programs





## **Visual Speech Detection**



(a) Face detector outcomes





STUDIO 1 ΚΕΡΔΗ ΚΑΙ ΖΗΜΙΕΣ ΑΠΟ ΤΟ "ΜΕΤΩΠΟ" ΠΑΙΔΕΙΑ

M. XPYEOXOIAHE

A. ZAFOPITHE



(a) Two active speakers

(b) One active speaker

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## **Shot Type Characterization**

- Problem statement: Classify a video shot into one of the predefined classes :
  - eXtreme Close Up shot (XCU),
  - Medium Shot (MS),
  - Long Shot (LS),
  - eXtreme Long Shot (XLS), etc.
  - Over The Shoulder (OTS)

Close up shot



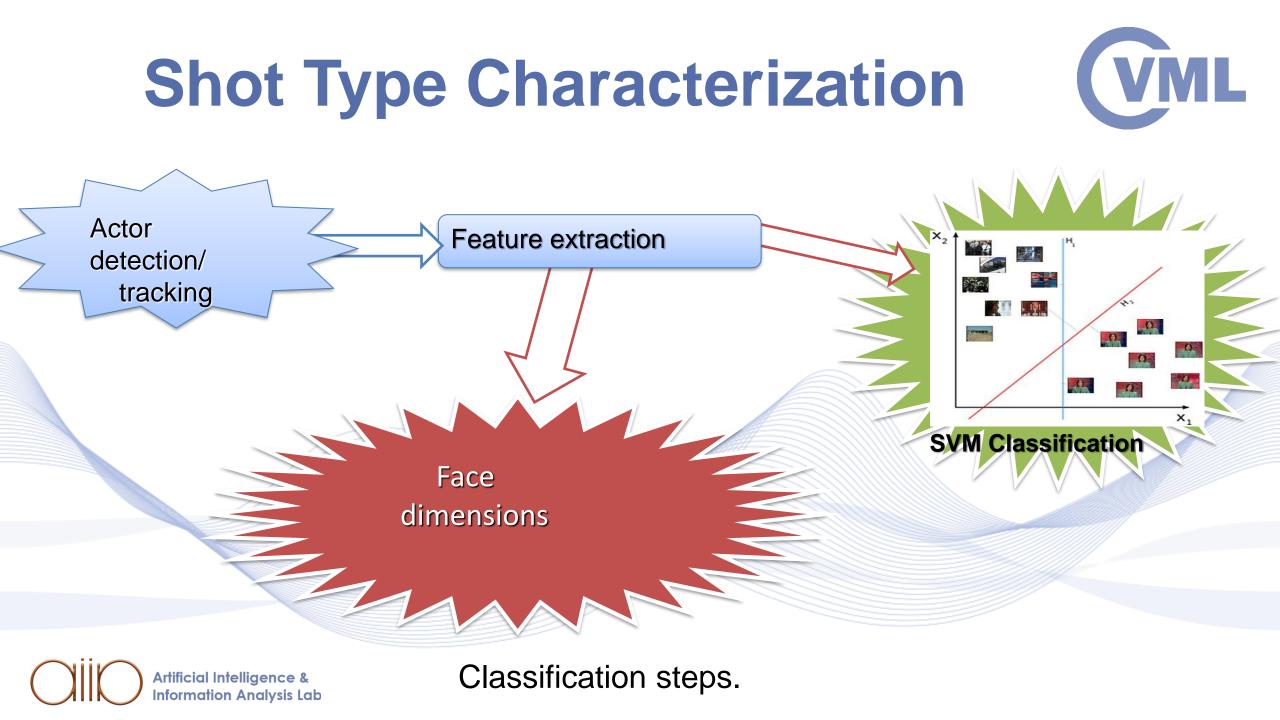
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### **Medium Shot**





Basic shot types



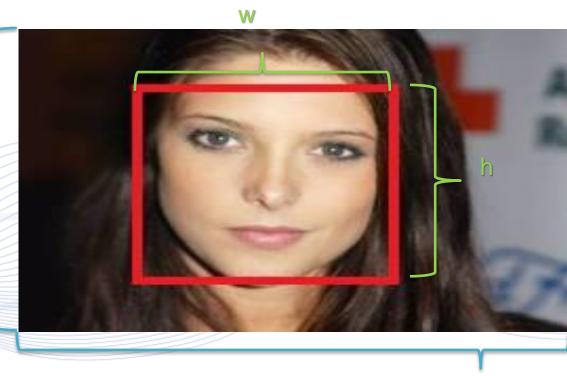
# **Shot Type Characterization**



#### Facial image features:

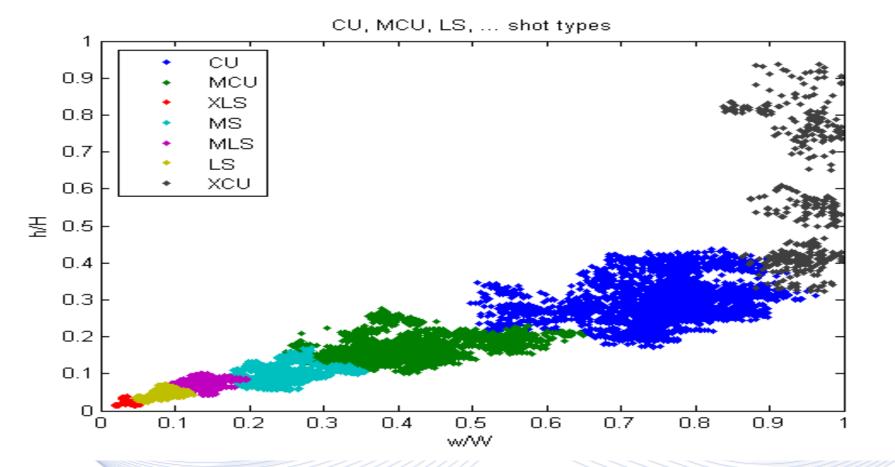
- Face dimensions in relation to video frame dimensions.
- Feature Vector:  $\mathbf{v} = \left[\frac{h}{H}, \frac{w}{W}\right]^T$ .

Н



## **Shot Type Characterization**

(VML

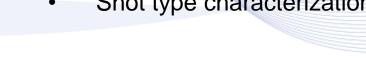


Shot type characterization using two image features.

## **Human Centered Computing**



- Semantic Video Content Analysis
- Face/object detection and tracking •
- Multiview human detection •
- Face detection obfuscation •
- Face recognition •
- Face clustering •
- Label propagation on videos •
- Face De-identification •
- 3D face reconstruction
- Facial expression recognition
- Facial feature detection
- Visual speech detection
- Shot type characterization



- Human body posture and pose estimation
- Activity/gesture recognition •
- Athlete Motion Analysis
- Soccer Video Analysis
- Semantic video content description/annotation

# 2D Human Body Posture Estimation



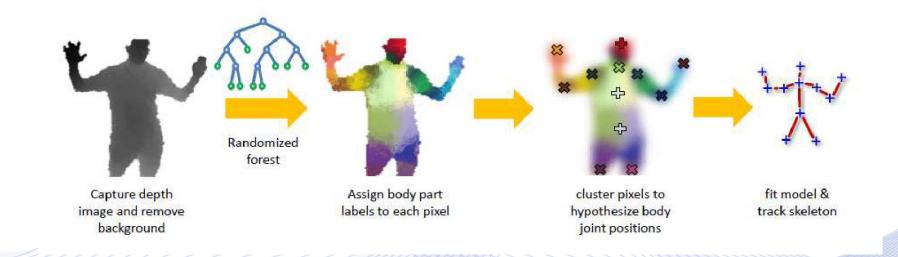
- **Posture** means an intentionally or habitually assumed position of the joints.
- Human key posture points include rich 2D appearance, angular point, and multi-point autocorrelation.
- In order to achieve the 2D Posture Model, first we need to detect the human body.



# 2D Human Body Posture Estimation



• Kinect sensors to get a skeleton sequence.



Kinect Skeleton Sequence. [SMIS2011]



## **3D Human Body Posture Estimation**

ESTIMATED

ESTIMATED



Video frames, ground truth and prediction. [RAY2018]







# Human Body Pose Estimation

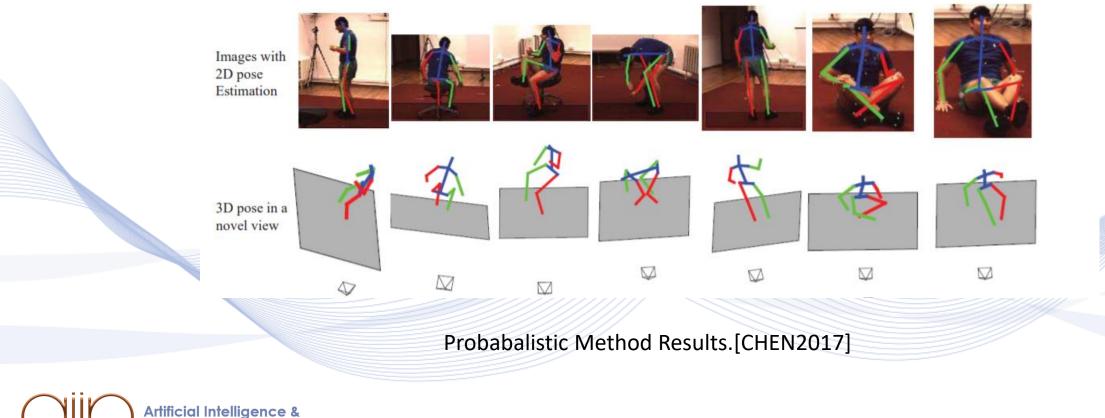
- Pose is the combination of position and orientation of an object vs the camera.
- It can be a considered as a regression problem
- Deep Learning Methods.



## **3D Human Body Pose Estimation**

• Probabilities:

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VML

## **Human Centered Computing**



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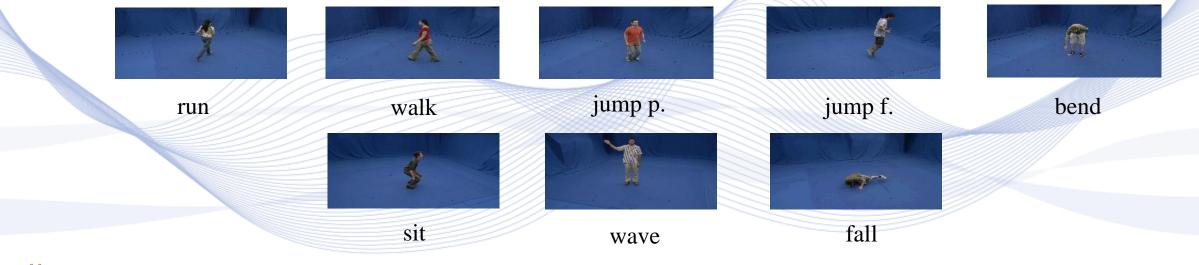
- Human body posture and pose estimation
- Activity/gesture recognition
- Athlete Motion Analysis
- Soccer Video Analysis
- Semantic video content description/annotation

# **Action Recognition**

**Problem statement:** 

# **VML**

- To identify the action (elementary activity) of a person.
- Input: a single-view or multi-view video or a sequence of 3D human body models (or point clouds).
- Output: An action label belonging to a set of N<sub>A</sub> action classes (walk, run, jump,...) for each frame or for the entire sequence.





### Action Recognition Applications:

# VML

### • Semantic video content description, indexing, retrieval.

- Video surveillance.
- Human Computer Interaction (HCI).



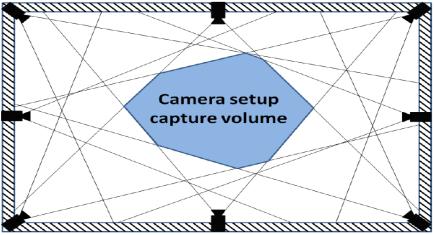


# Action Recognition Methods Categorization



- Single-view: methods utilizing one camera.
- Multi-view: methods utilizing multiple cameras forming a multi-camera setup.

An eight-view camera setup ( $N_c=8$ ).



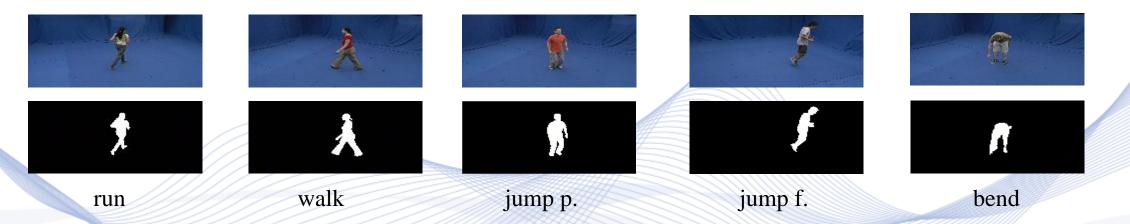
Single-view methods are special cases of multi-view ones, i.e., for



# Action Recognition on Video Data



 Input feature vectors: binary human body images resulting from coarse body segmentation on each video frame.



Segmentation techniques: background subtraction, chroma keying, motion detection.



## **Action Description**



• A series of successive human body poses.



Human body poses are represented by binary posture images.

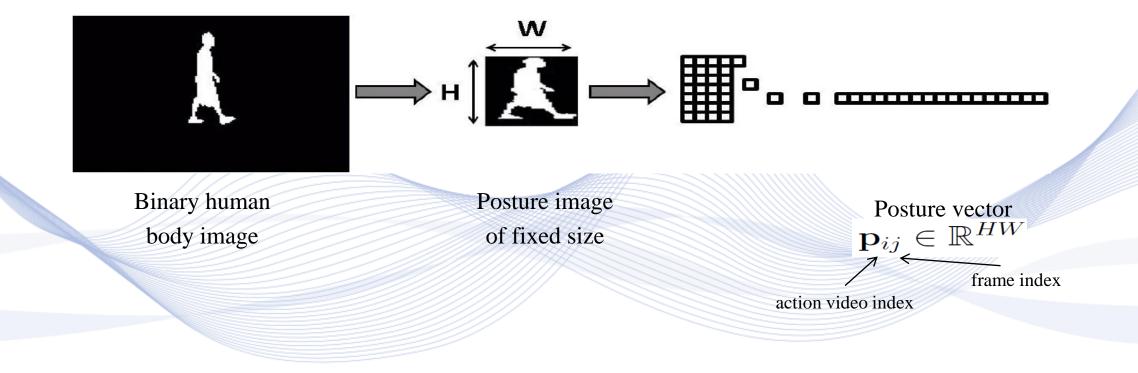
## AAAAI





## **Action Representation**

• Posture vectors creation.



## **Action Representation**



### Dyneme-based representative human body poses:

- Dynemes calculation: Cluster all the training posture vectors p<sub>ij</sub> in D clusters without exploiting the available action labels.
- Clustering techniques:
  - K-Means.
  - Self Organizing Map (SOM).

Dynemes can be considered as representative human body poses.

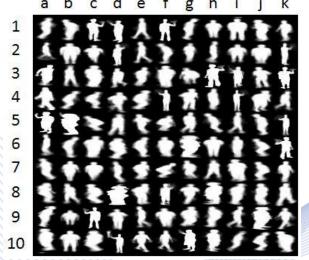


## **Dynemes Calculation**



K-Means: a fast clustering technique minimizing the intra-cluster variance.

D = 110 dynemes resulted by clustering the posture vectors of the i3DPost eightview database



Dynemes are evaluated as the mean vectors of the resulting clusters (cluster centres)  $v_k \in \mathbb{R}^{HW}$ 



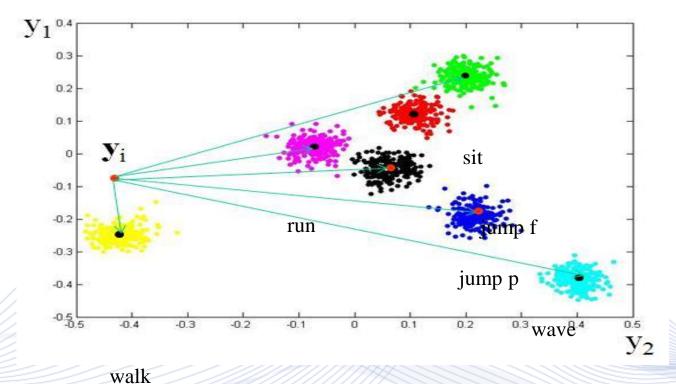
## **Action Classification**



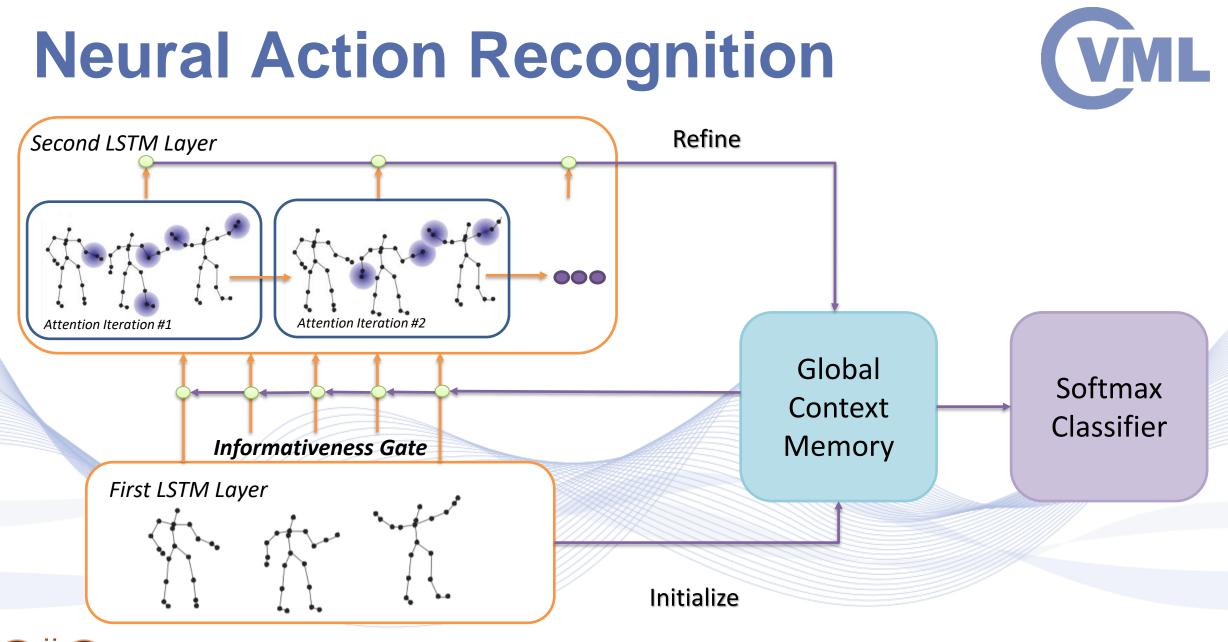
- Each action video is represented by the corresponding action vector.
- Various representation techniques can be used:
  - 2D or 3D CNN feature vectors
  - Dyneme-based feature vectors.
  - Action classification is reduced to the corresponding action vector classification problem.
  - Vector classification:
    - Deep Neural network techniques (2D/3D CNNs)
    - **Graph Convolution Networks**
    - Dimensionality reduction based classification.



## **Action Classification**



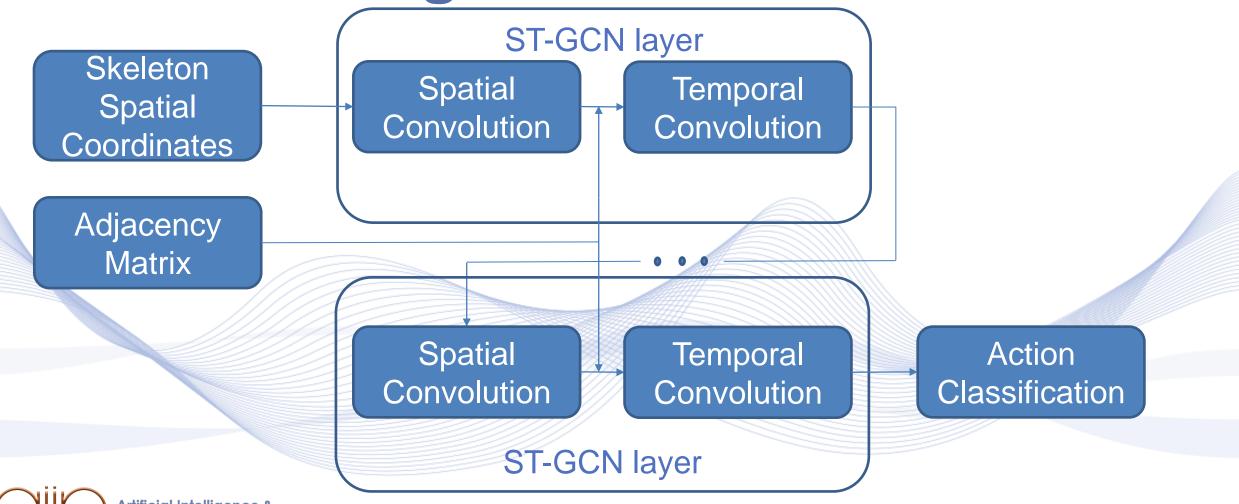
Classification based on the smallest Euclidean distance from all the mean action class vectors.



Artificial Intelligence & Information Analysis Lab LSTM skeleton-based human action recognition.

## Spatio-Temporal GCN Action Recognition ST-GCN layer



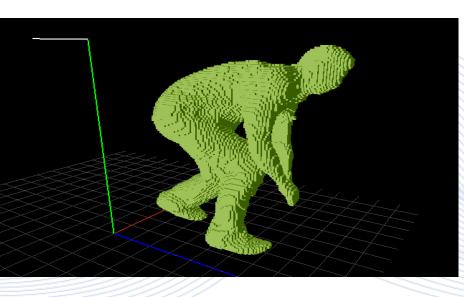


# **3D Action Recognition**



### Action recognition on 3D data

- Extension of the video-based activity recognition algorithm
- Input to the algorithm: binary voxel-based representation of frames

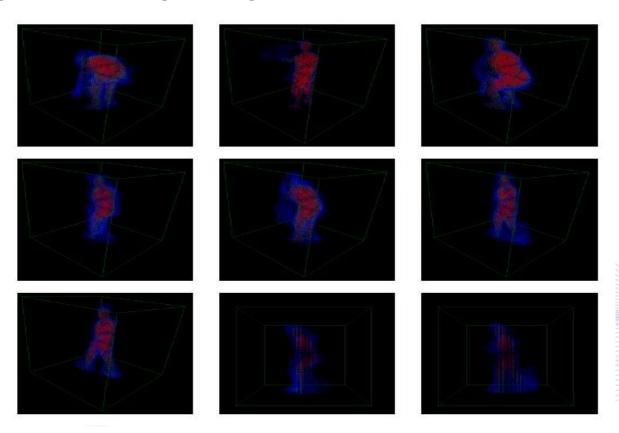




## **3D Action Recognition**



• 3D action characterization based on 3D "dynemes" (representative poses) derived through clustering along with LDA.





# Action Recognition Examples

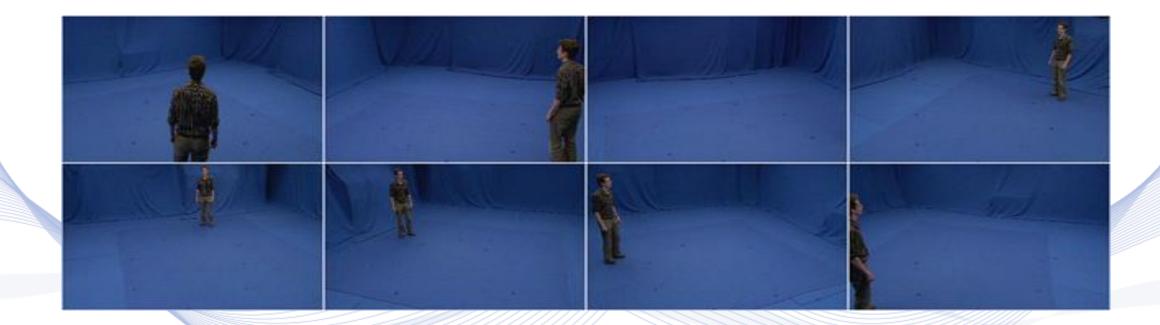




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# Action Recognition Examples





## **Human Centered Computing**



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- Human body posture and pose estimation
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- Athlete Motion Analysis
- Soccer Video Analysis
- Semantic video content description/annotation

## **Athlete Motion Analysis**

- Cameras
- Mechanical trackers



- Inertial trackers
- Electromagnetic devises
- Ultrasonic Trackers



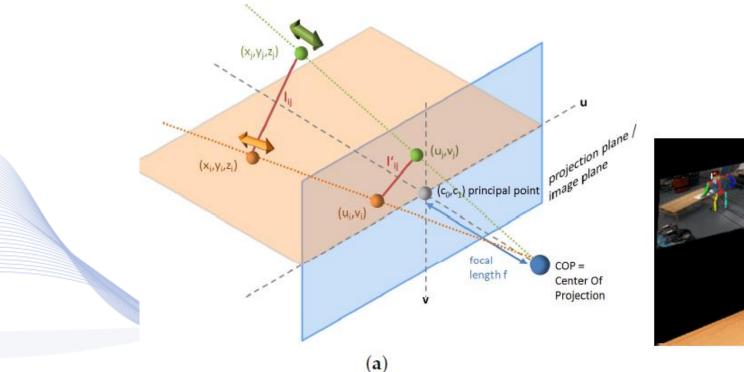


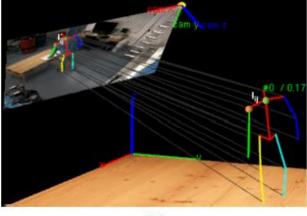






## **Athlete Motion Analysis**





(b)

**3D** Athlete Body Motion Estimation.



### **Human Centered Computing**



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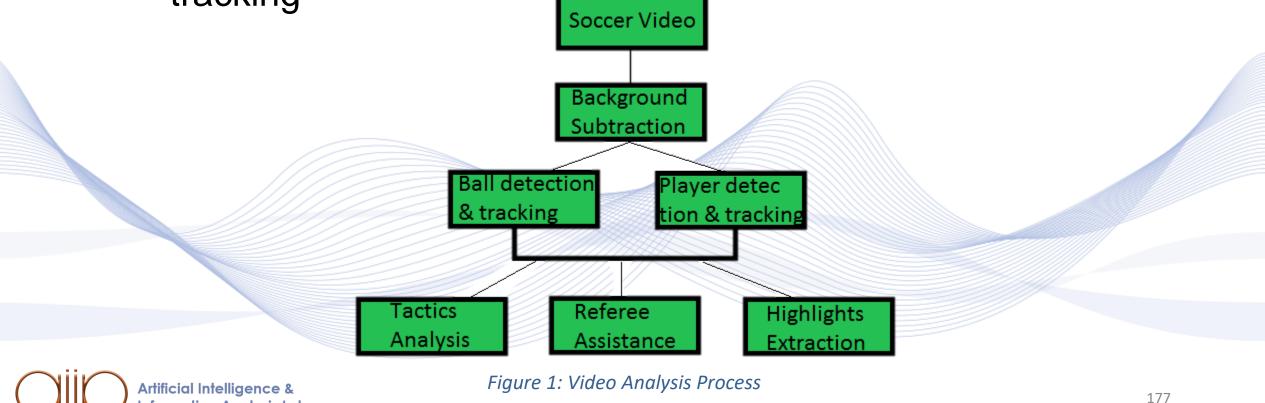


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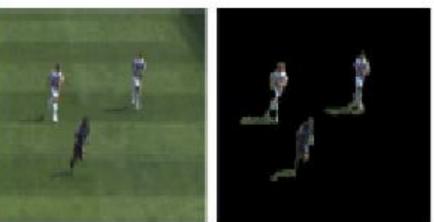
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 Background subtraction is required for objects detection and tracking





- Segmenting each frame into background and foreground.
- Background corresponds to the playfield.
- Binarized image: 0 for playfield, 1 for moving objects.



Playfield Detection.





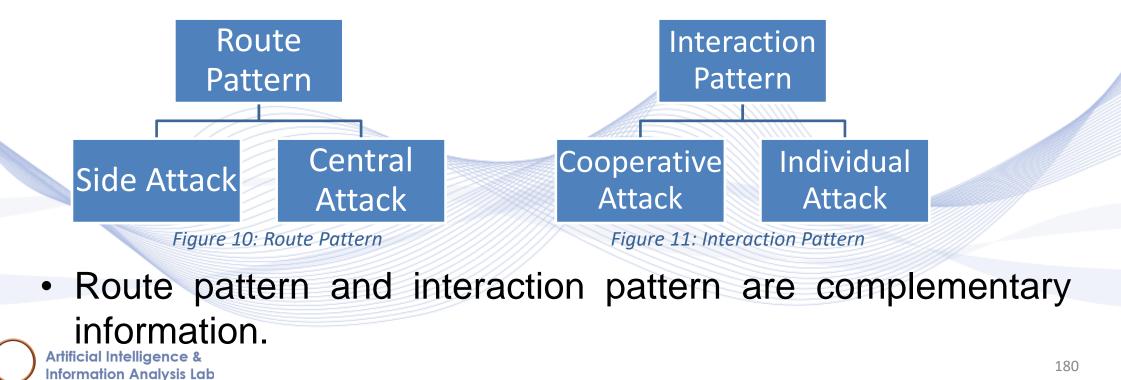




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• **Tactic Pattern Analysis:** Use of the extracted information (ball segments, dribbling segments, active play regions) to classify the attack events.



### **Human Centered Computing**



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#### **MPEG-7** standard



 Multimedia content semantic analysis results should be stored in a standardized, consistent & structured way

Reasons: exchange of information, ingestion in 3D content databases/archives/MAM systems.

- MPEG-7 standard defines a description framework for handling multimedia content annotation and description
- A considerable amount of effort has been invested over the last years to improve MPEG-7 ability to deal with semantic content description, resulting in various MPEG-7 profiles



#### Audio-Visual Description Profile (AVDP)



- Audio-Visual Description Profile (AVDP) is an MPEG-7 profile introduced to describe results of multimedia analysis algorithms:
  - Person identification, genre detection, keyframe extraction, speech recognition etc.
  - Several results can be described in multiple timelines.
- Recently standardized from the MPEG Committee.
  - Descriptions are in XML format, following the AVDP Schema Definition (XSD).



#### Audio-Visual Description Profile (AVDP)



- AVDP defines a subset of the MPEG-7 description tools needed for storing audiovisual content analysis results.
- AVDP also defines the semantics of some MPEG-7 description tools to suit audiovisual content description.
- AVDP was authored having in mind mainly single-view ("2D") video & mono/stereo audio
  - Its semantics do not include ways for dealing with certain aspects of 3D video / multichannel audio content description.



#### Audio-Visual Description Profile (AVDP)



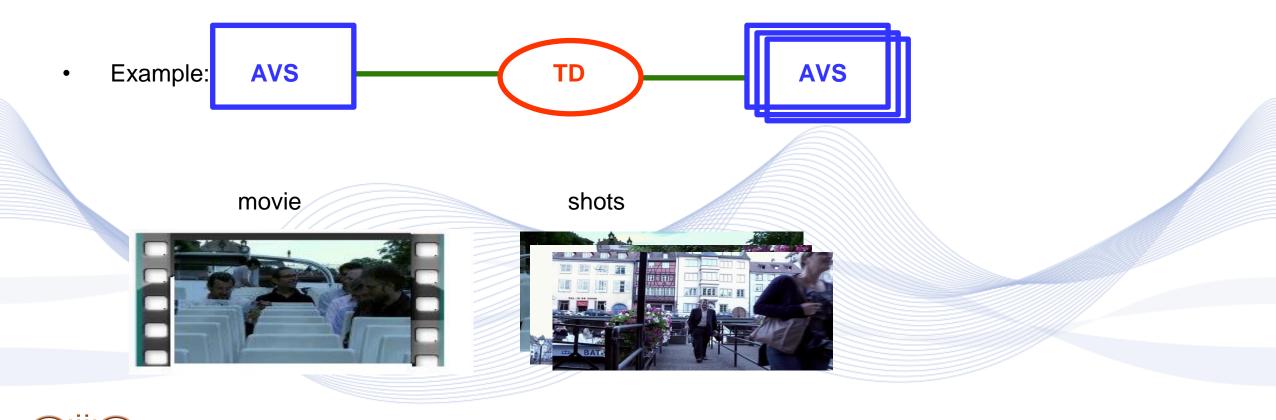
- A new framework for using the MPEG-7 AVDP profile for 3D content (e.g. 3DTV audiovisual content) description was proposed within European research project <u>3DTVS</u>
  - A subset of the description tools available in the AVDP has been selected
  - A description procedure that can be used to store 3D content analysis results has been defined.
- The framework also details procedures for storing 2D content annotations, not foreseen in the AVDP initial guidelines



#### **Useful AVDP/MPEG 7 Tools**



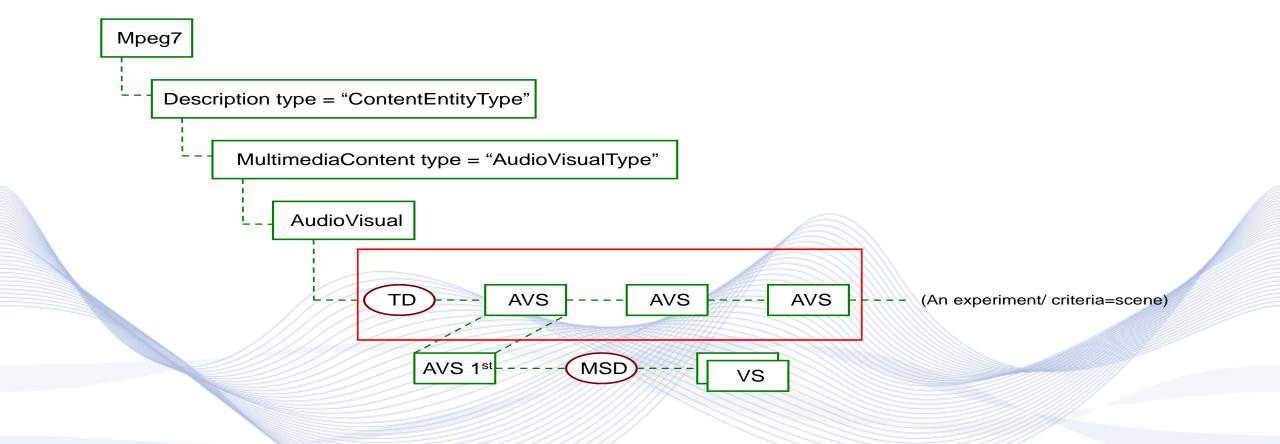
 TemporalDecomposition type (TD): decomposes a VideoSegment type (VS), AudioVisualSegment type (AVS), or AudioSegment type into temporal segments.



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#### **Scene/Shot Boundaries Detection**



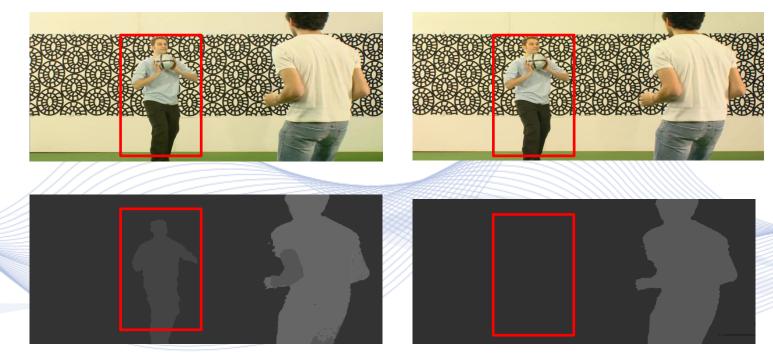




#### **Human/Object Detection**

VML

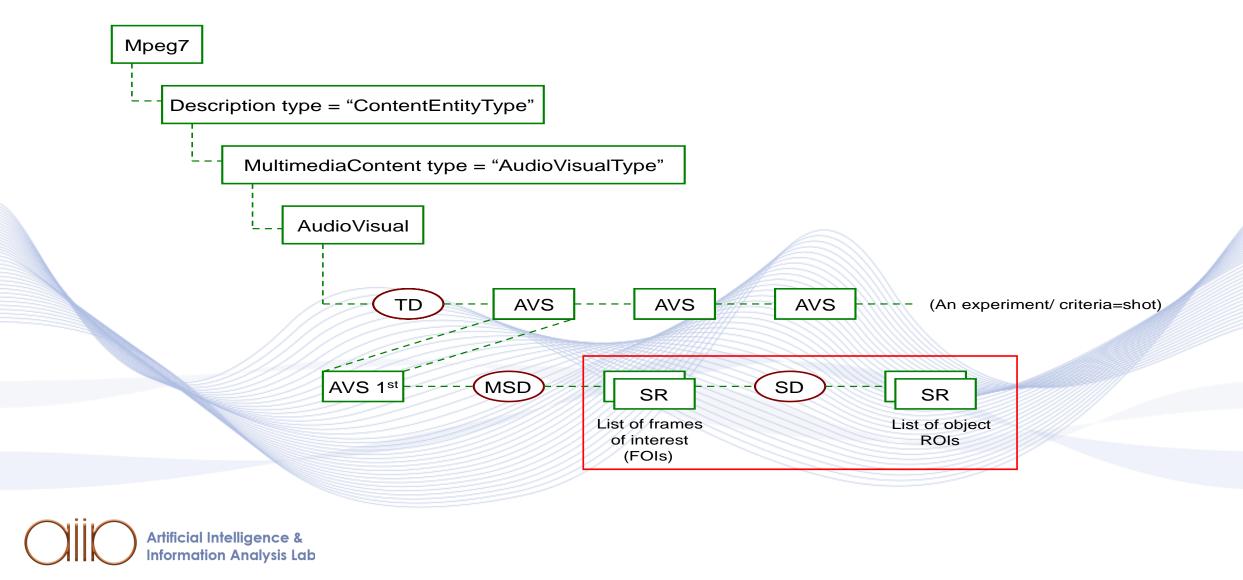
- Human/object detection: localizing this entity in a frame.
- Generates a bounding box that includes the detected entity.
- Results are stored in StillRegion types (at least) in the channel(s) where detection takes place.







#### **Human/Object Detection**





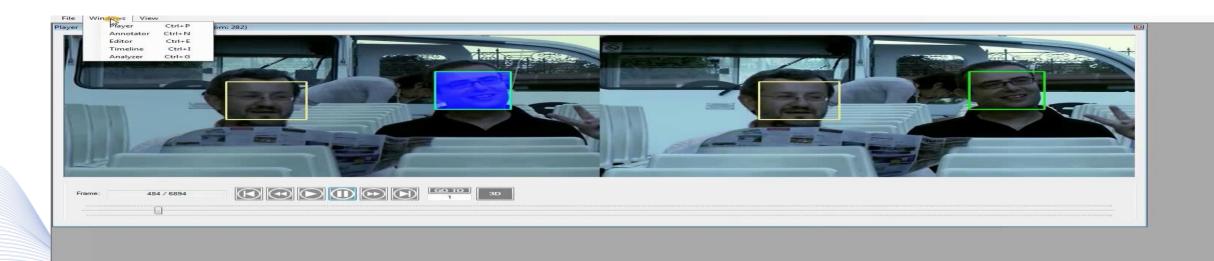
### Timeline

	Timeline							
		Channel:	Left Channel	-	Frame:	2816 / 3000		
ots & transitions								]
	Shots							
sons/objects	Cuts							
earances	Key Segments	Events	Static Objects	s Static H	lumans Mo	ving Objects	Moving Humans	
								A
	person_1							
ents								
	person_1							

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### Timeline





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#### Thank you very much for your attention!

# More material in http://icarus.csd.auth.gr/cvml-web-lecture-series/

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