

# Hidden Markov Models summary

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# Hidden Markov Models

- **Markov Chains**
- Hidden Markov Chains
- HMMs applications
  - Speech recognition
  - Name-entity recognition
  - Human Action Recognition
  - Gesture recognition

# Markov chain

A **Markov chain** is a stochastic model describing a sequence of possible events in which the probability of each event depends only on the state attained in the previous one.

**Markov chains** are distinguished from the fact that no matter how the process arrived at its present state, the possible future states are fixed.

# Markov chain

The distribution over states can be written as  $\mathbf{x}^{(n+1)} = \mathbf{x}^{(n)}\mathbf{P}$   
*where:*

- $\mathbf{x}$  is the state as stochastic row vector
- $\mathbf{P}$  is the probabilities as transition matrix
- $n$  is the current time period

# Markov chain

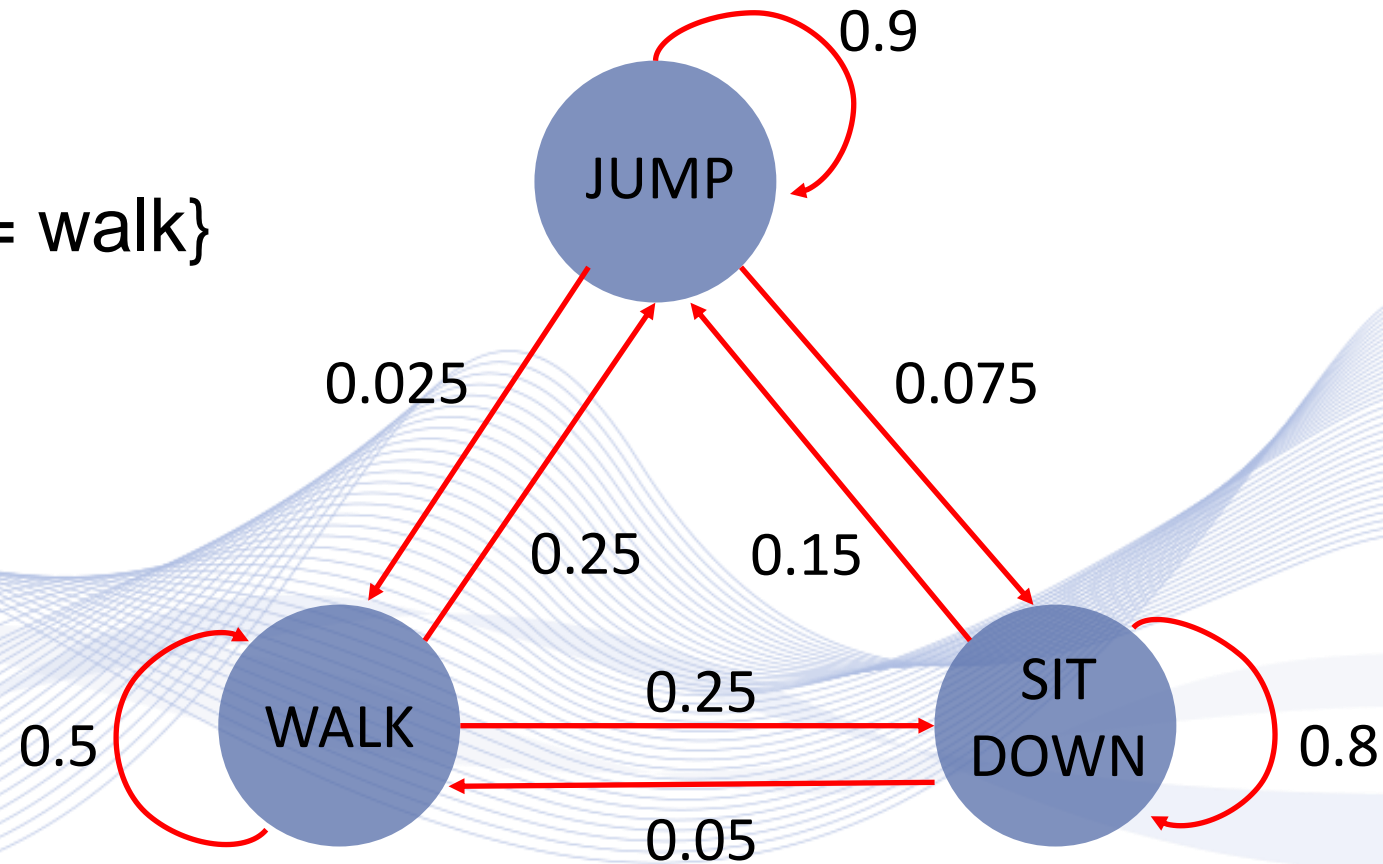
## Example:

Labeling the states

{1 = jump, 2 = sit down, 3 = walk}

the transition matrix is:

$$P = \begin{bmatrix} 0.9 & 0.075 & 0.025 \\ 0.15 & 0.8 & 0.05 \\ 0.25 & 0.25 & 0.5 \end{bmatrix}$$



Markov Chain representation

# Hidden Markov Models

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# Hidden Markov Models

Markov chain introduces a non-deterministic process that generates output observation symbols in any given state.

This model is known as a **Hidden Markov Model** and can be defined as a double-stochastic process with an underlying stochastic process.

# Hidden Markov Models

More specifically:

**Hidden Markov Models** (HMMs) are a class of probabilistic graphical **model** that allows the prediction of a sequence of unknown (**hidden**) variables from a set of observed variables



# Hidden Markov Models

A Hidden Markov model is defined by:

1. A finite set of states  $\Omega = \{s_1, \dots, s_k\}$
2. A finite signal alphabet  $\Sigma = \{\sigma_1, \dots, \sigma_m\}$ .
3. Initial probabilities  $P(s)$  (for every  $s \in \Omega$ ) defining the probability of starting in state  $s$
4. Transition probabilities  $P(s_i | s_j)$  (for every  $(s_i, s_j) \in \Omega^2$ ) defining the probability of going from state  $s_j$  to state  $s_i$
5. Emission probabilities  $P(\sigma | s)$  (for every  $(\sigma, s) \in \Sigma \times \Omega$ ) defining the probability of emitting symbol  $\sigma$  in state  $s$

# Hidden Markov Models- Viterbi



Given a model  $\Phi$  and a sequence of observations, what is the most likely state sequence in the model that produces the observations?

# Hidden Markov Models- Viterbi



*This problem is solved through the Viterbi algorithm.*

Optimal state sequence:

$$viterbi(i, s) \Leftrightarrow \max_{s'} P(\sigma_1, \dots, \sigma_i, s_{i-1} = s', s_i = s)$$

$$viterbi(1, s) = P(s)P(\sigma_1|s)$$

$$viterbi(i, s) = \max_{s'} viterbi(i-1, s')P(s|s')P(\sigma_i|s)$$

$$\max_s viterbi(n, s) = \max_{s_1, \dots, s_n} P(\sigma_1, \dots, \sigma_n, s_1, \dots, s_n)$$

# Hidden Markov Models- Forward-backward algorithm



Given a model  $\Phi$  and a sequence of observations, what is the probability of the model that generates the observations?

# Hidden Markov Models-

## The training problem

Training problem answers the question: Given a model structure and a set of sequences, find the model that best fits the data.

- For this problem the following 3 algorithms can be used:
  - MLE (maximum likelihood estimation)
  - Viterbi training(DO NOT confuse with Viterbi decoding)
  - Baum Welch = forward-backward algorithm

# Hidden Markov Models- Baum-Welch algorithm



The Baum-Welch algorithm works in the following way:

→ For each sequence in the training set of sequences:

- Calculate forward probabilities with the forward algorithm
- Calculate backward probabilities with the backward algorithm
- Calculate the contributions of the current sequence to the transitions of the model & the contributions of the current sequence to the emission probabilities of the model.

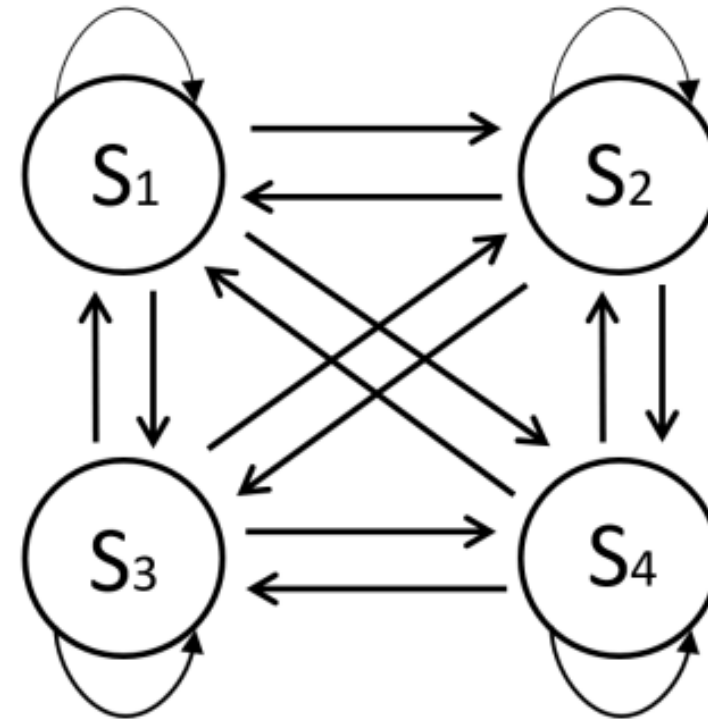
# Hidden Markov Models- Baum-Welch algorithm



- Calculate the new model parameters (start probabilities, transition probabilities, emission probabilities)
- Calculate the new log likelihood of the model
- Stop when the change in log likelihood is smaller than a given threshold or when a maximum number of iterations is passed.

# The HMMs topologies-ergodic

The ergodic model has no restrictions on the transition matrix. Each state is accessible from any other state with a simple transition

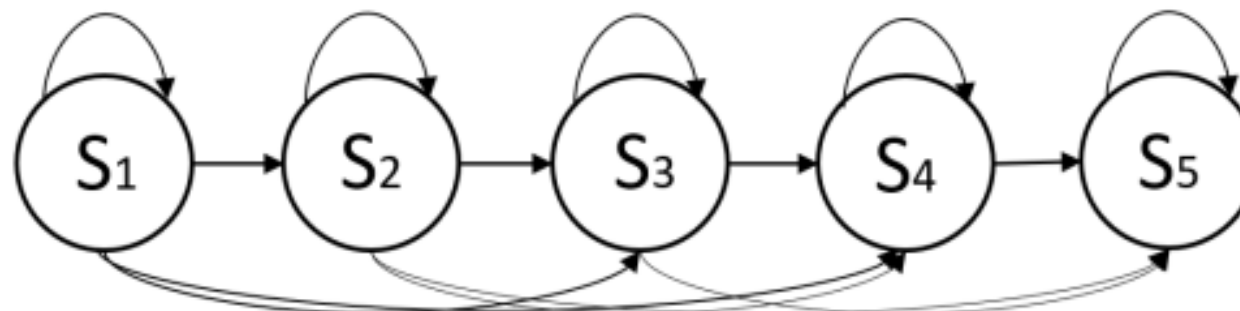


Ergodic topology



# The HMMs topologies-left-to-right

The left-to-right models are used to depict processes characterized by variable properties over time, such as human voice signals.

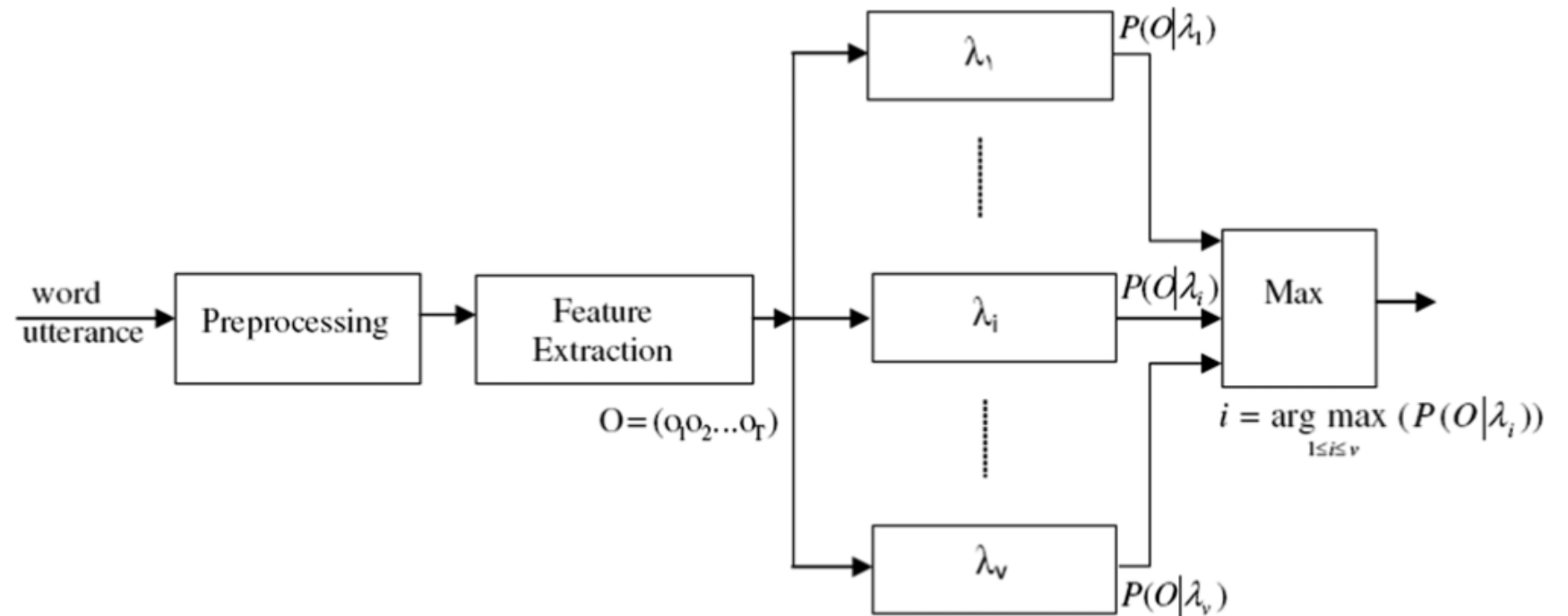


Left-to-right topology

# Hidden Markov Models

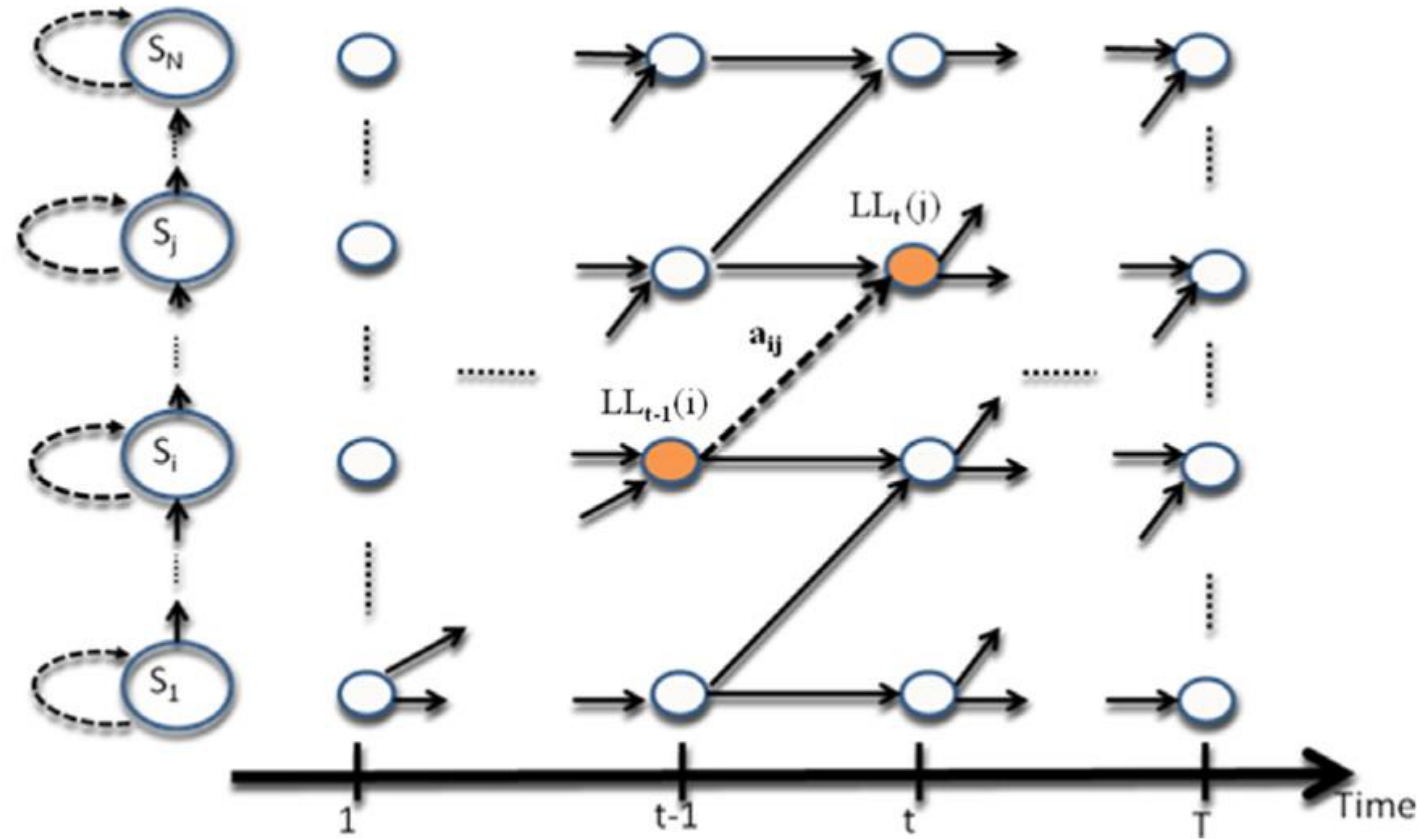
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# HMMs for speech recognition



The overall block diagram of an automatic speech recognition system [NAJ2010]

# HMMs for speech recognition

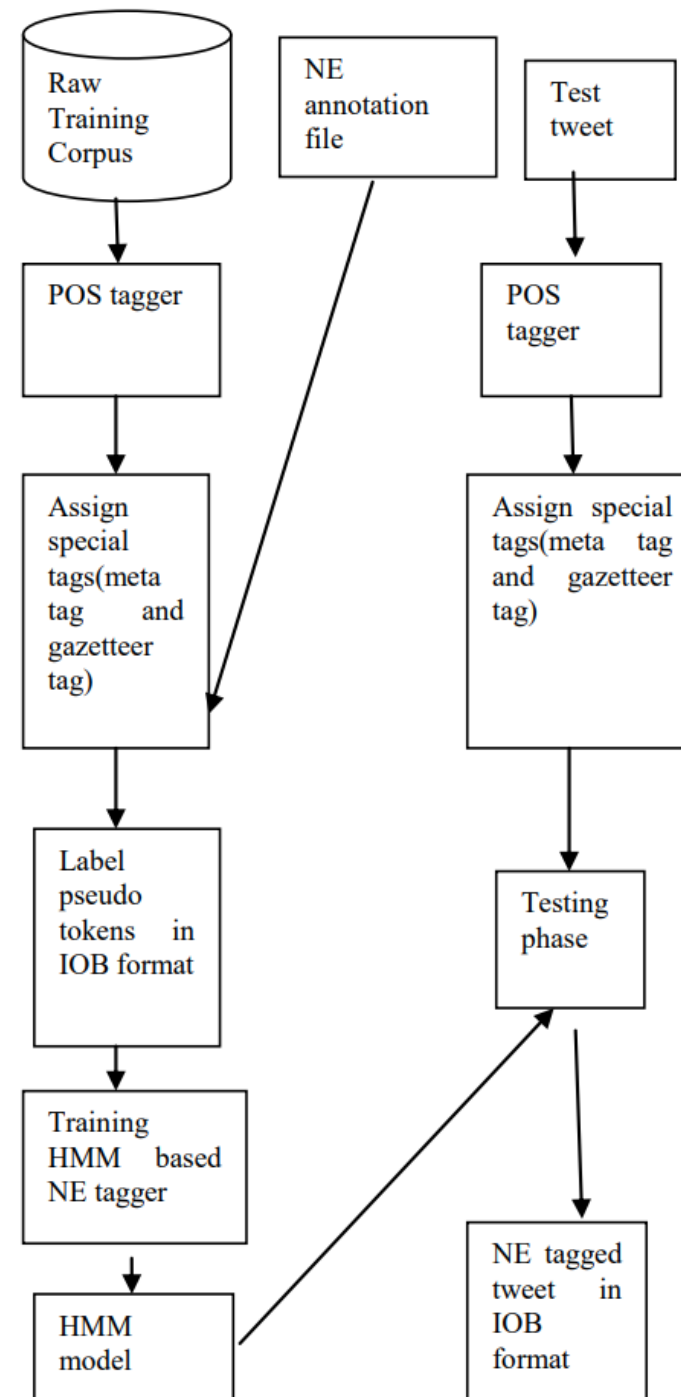


A Viterbi trellis diagram [NAJ2010]

# HMMs for Name-entity recognition



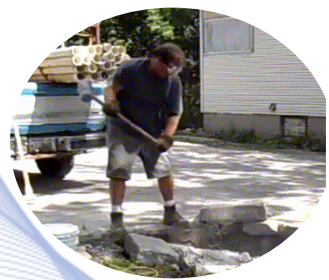
Architecture for an HMM based NE extraction system [SAR2015]



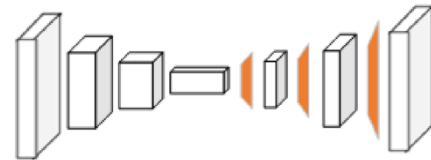
# Human Action Recognition with HMMs



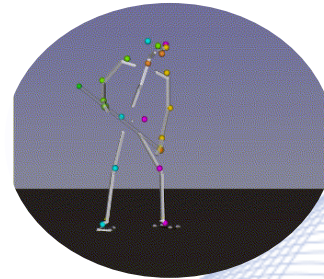
## RGB videos to time series conversion



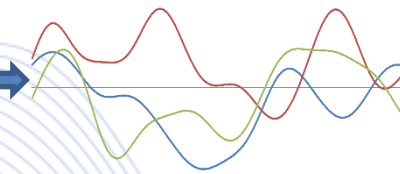
RGB videos



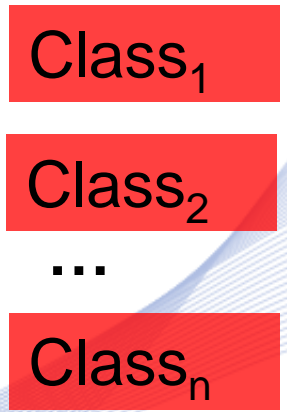
Pose estimation model



2D/3D skeletons



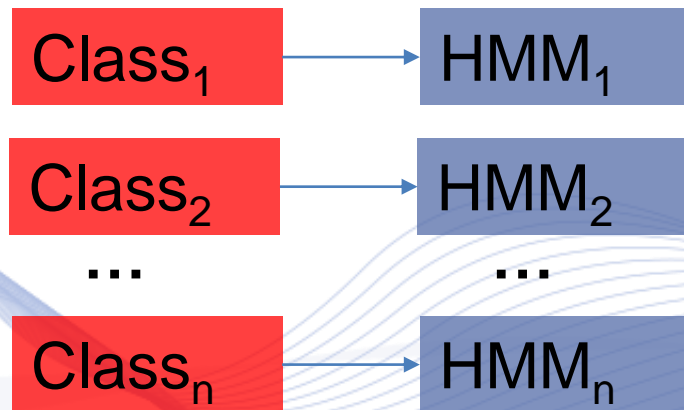
Time series



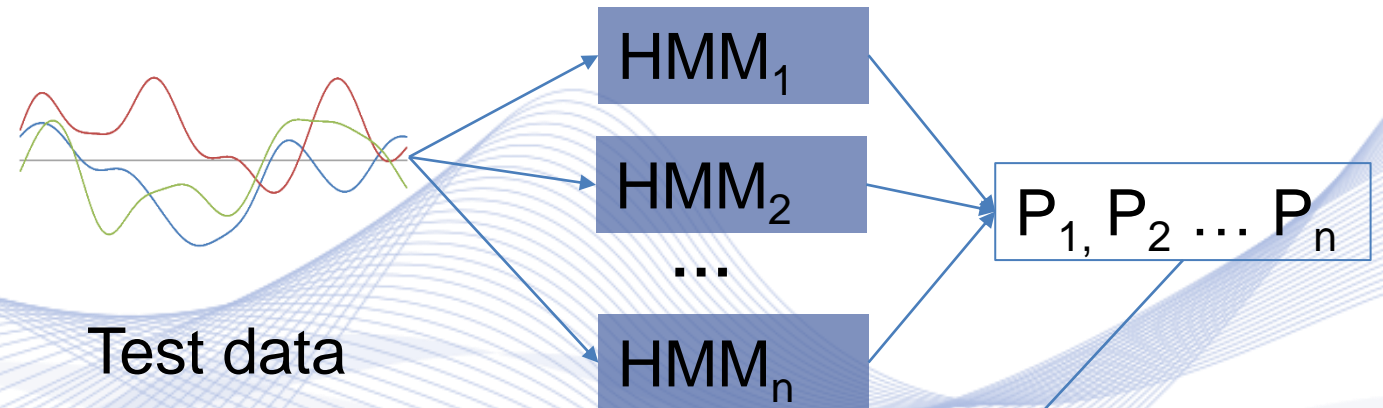
# Human Action Recognition with HMMs

## Supervised learning

### Training

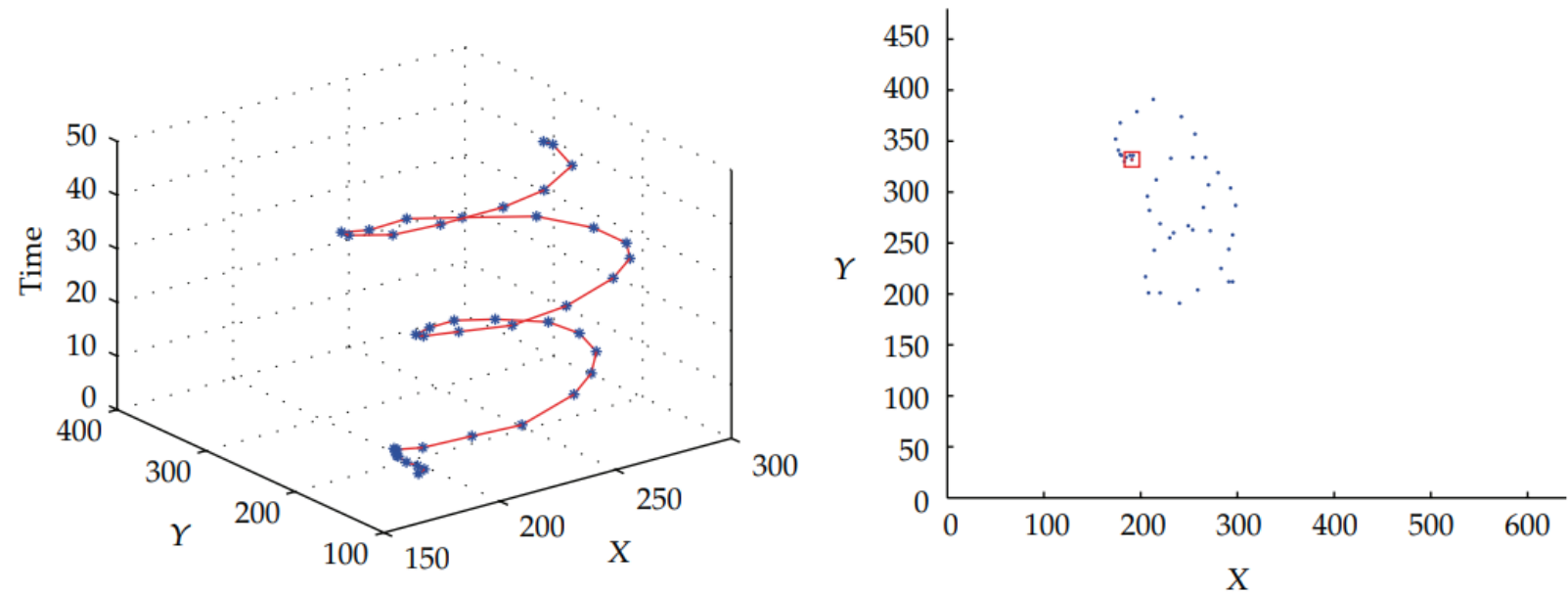


### Testing



Choose model with the highest **probability**

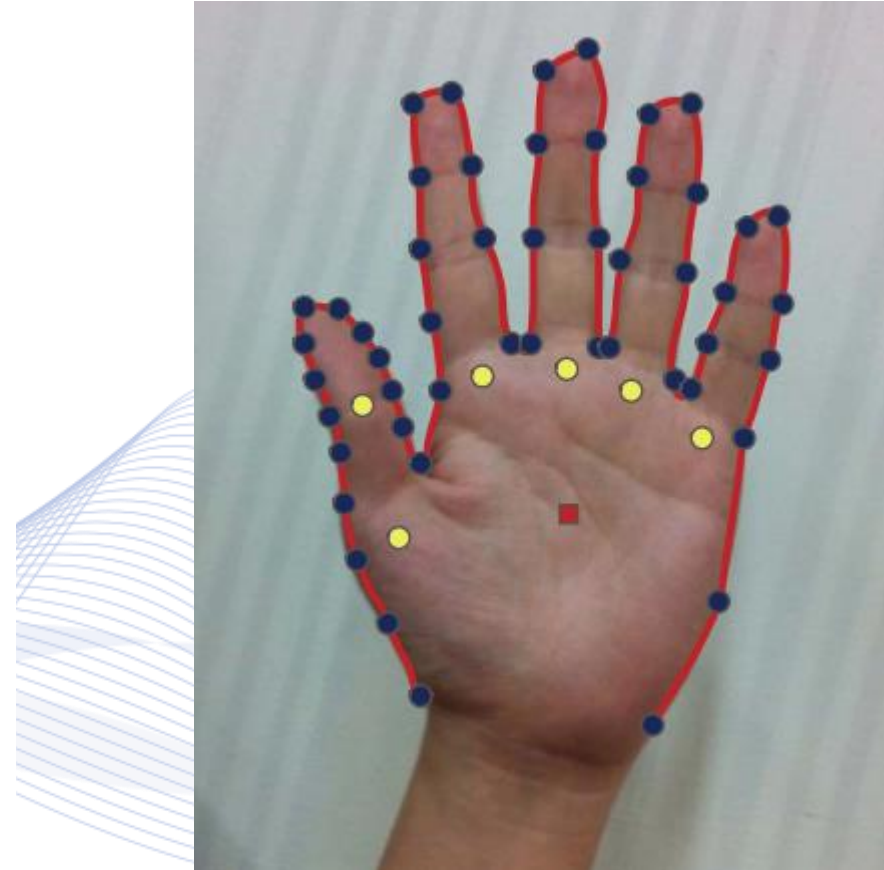
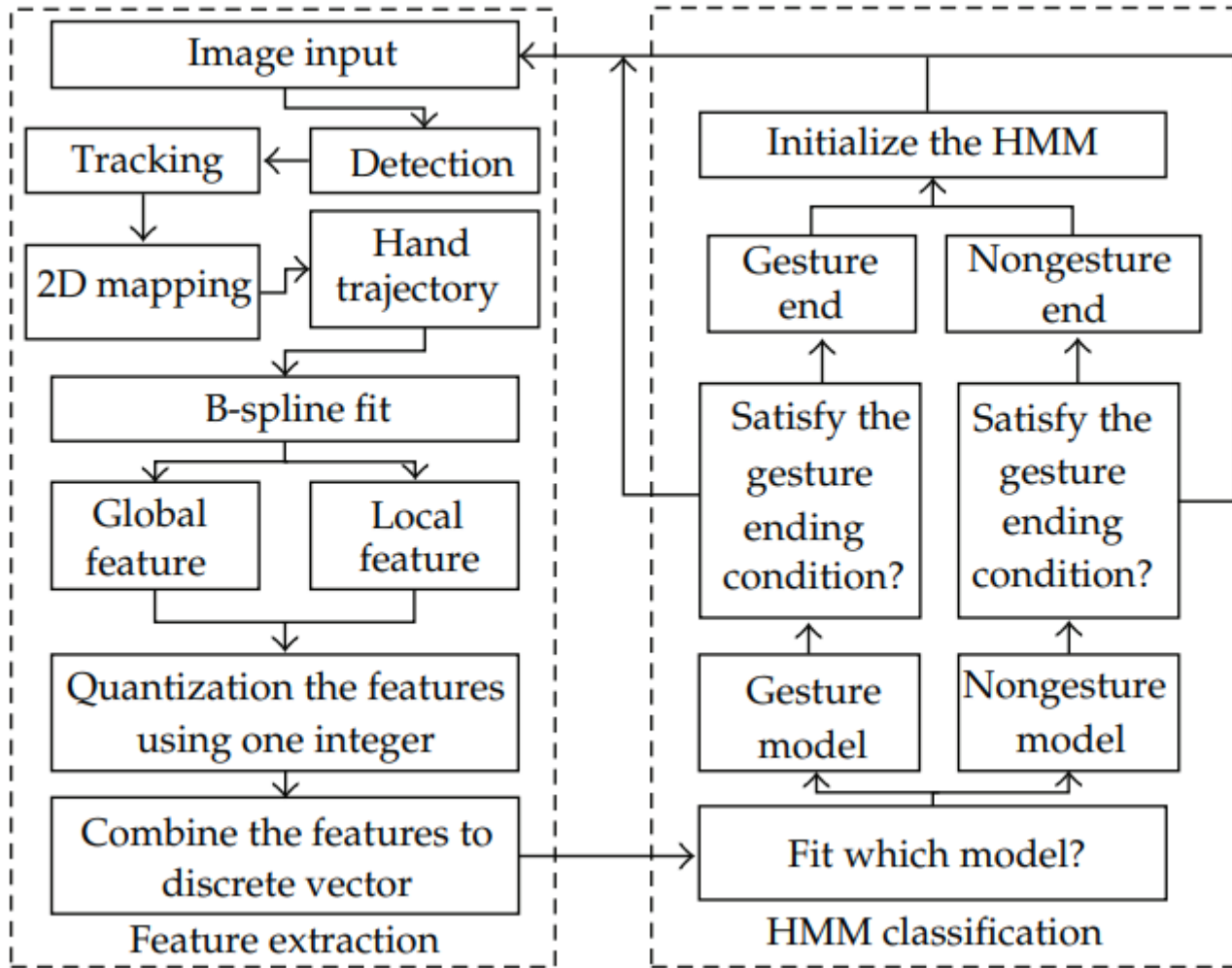
# HMMs for gesture recognition



A dynamic gesture instance [WANG2012]



# HMMs for gesture recognition



Overview of the hand gesture recognition process [WANG2012]

Hand contour [WANG2012]

# Q & A

**Thank you very much for your attention!**

**More material in  
<http://icarus.csd.auth.gr/cvml-web-lecture-series/>**

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