

# 2D Object Detection and Tracking summary

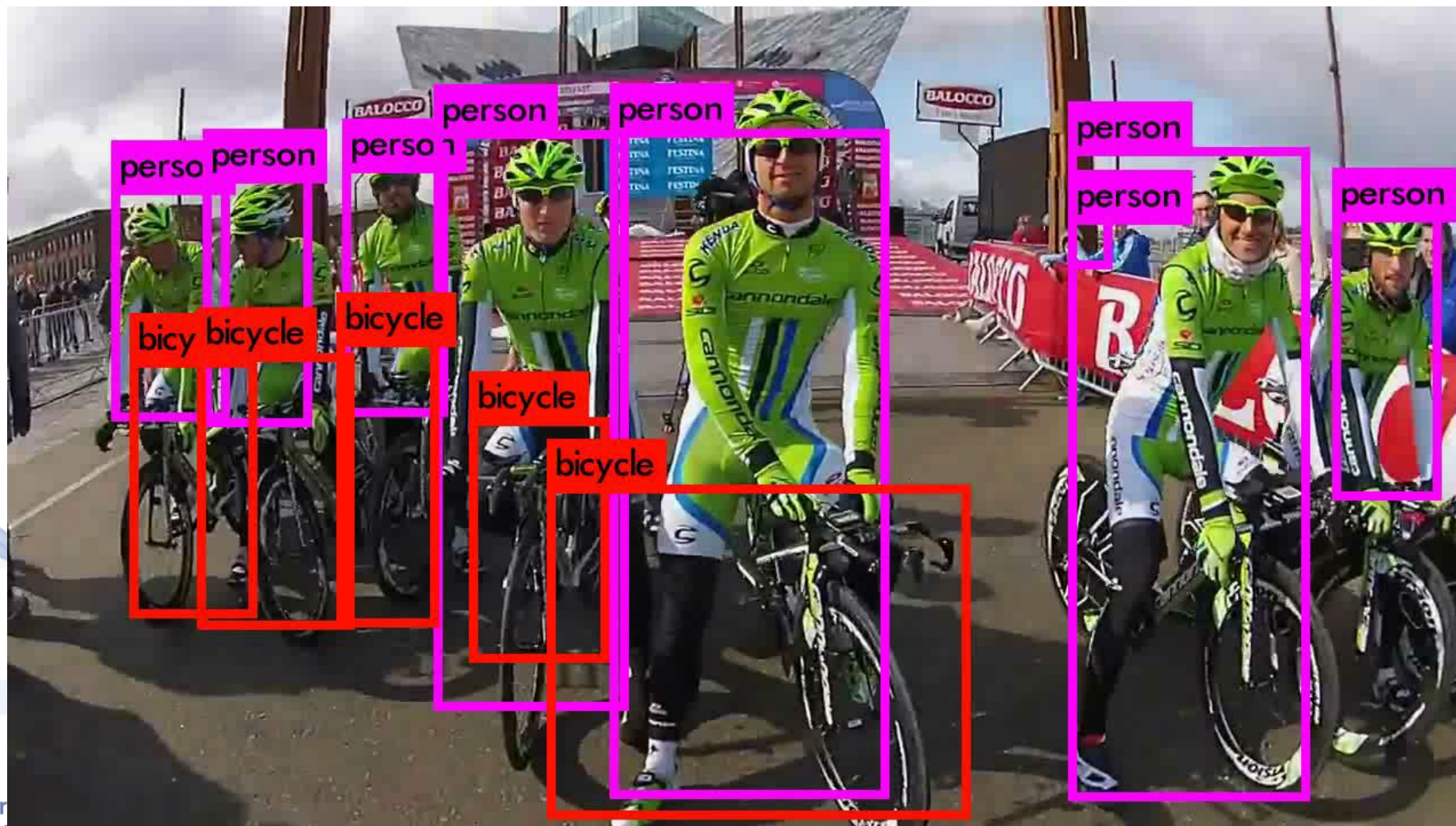
V. Nousi, I. Karakostas, Prof. Ioannis Pitas  
Aristotle University of Thessaloniki  
[pitass@csd.auth.gr](mailto:pitass@csd.auth.gr)  
[www.aiia.csd.auth.gr](http://www.aiia.csd.auth.gr)  
Version 2.5.1

# Object Detection





# Object Detection



# Object Tracking





# 2D Object detection and Tracking



- **Object Detection and Forward Tracking**
- Object Forward-Backward Tracking

# 2D Object detection and Tracking



- Video tracking is the process of locating a moving object (or multiple objects) over time using a camera.
- Variety of uses:
  - human-computer interaction
  - security and surveillance
  - video communication and compression
  - augmented reality and video editing
  - traffic control
  - medical imaging.
- Video tracking can be a time consuming process due to the amount of data that is contained in video.



# Object Detection and Tracking

1<sup>st</sup> frame



6<sup>th</sup> frame



11<sup>th</sup> frame



16<sup>th</sup> frame



- Problem statement:
  - To detect a target/object (e.g. human face) that appear in each video frame and localize their **Region-Of-Interest (ROI)**.
  - To track the detected object over the video frames.

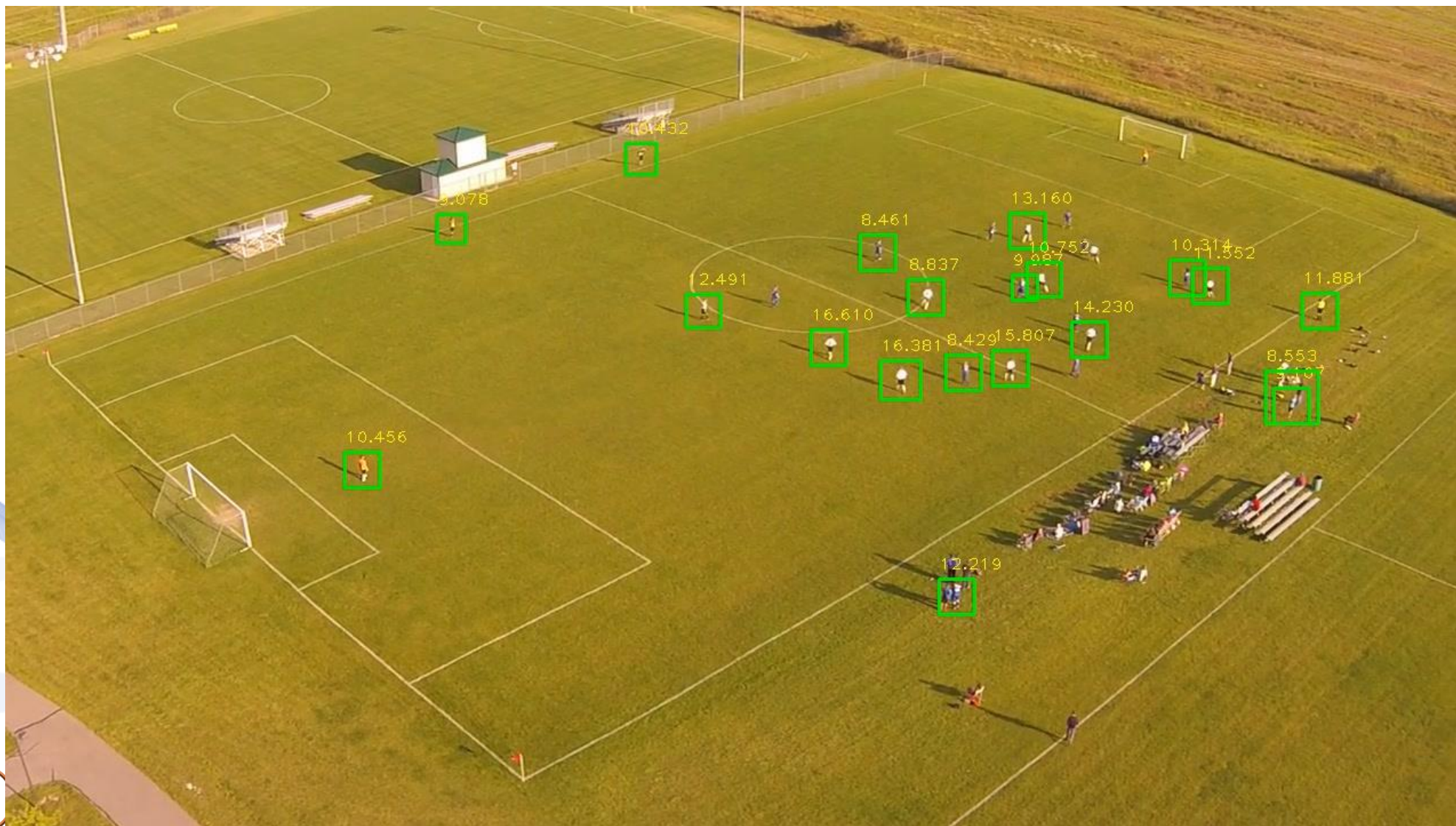
# Object Detection and Tracking



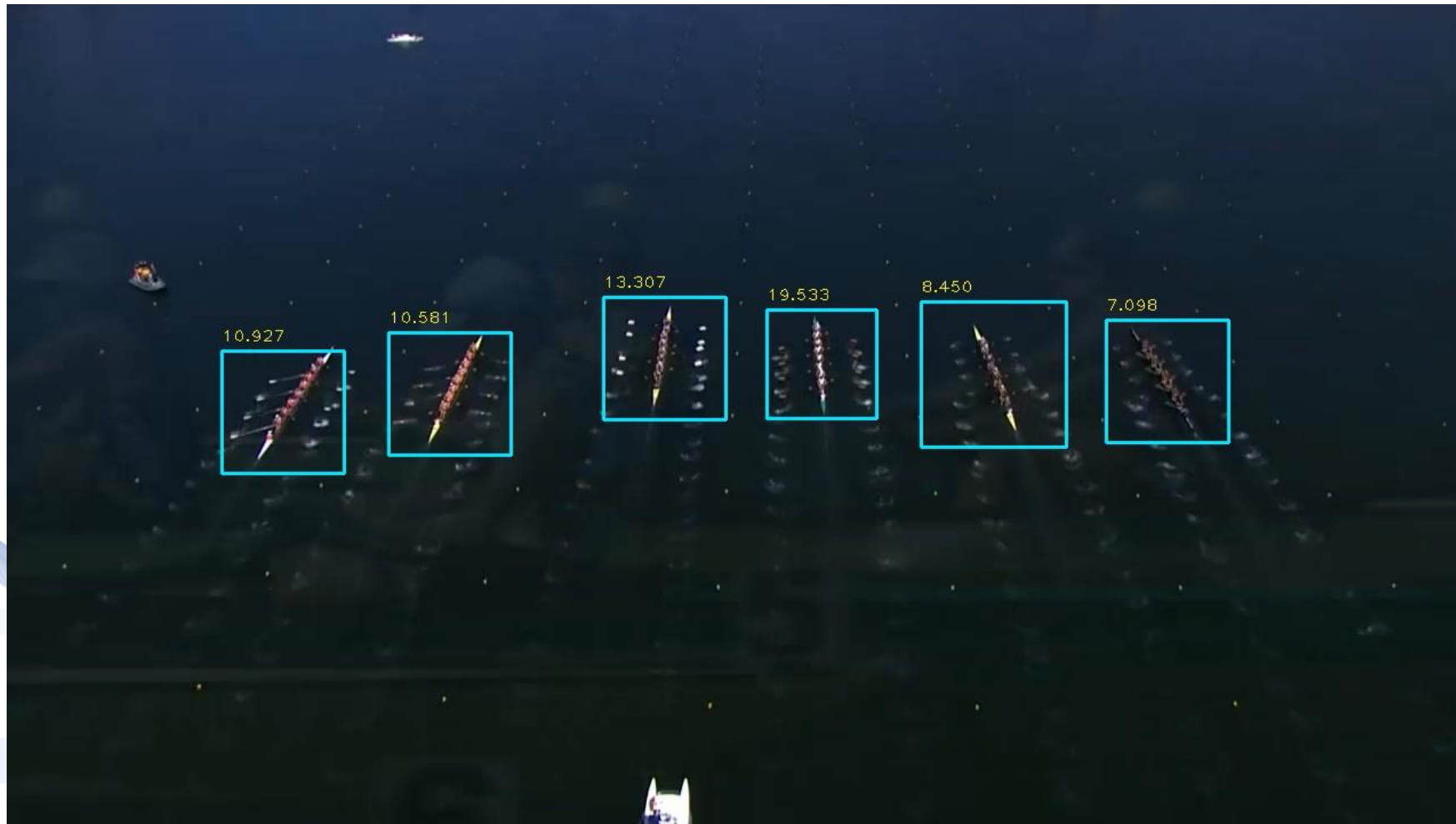
- **Periodic object re-detection** can be applied to account for new objects entering the camera's field-of-view.
- **Forward and backward tracking**, when the entire video is available.



# Football player detection



# Boat detection

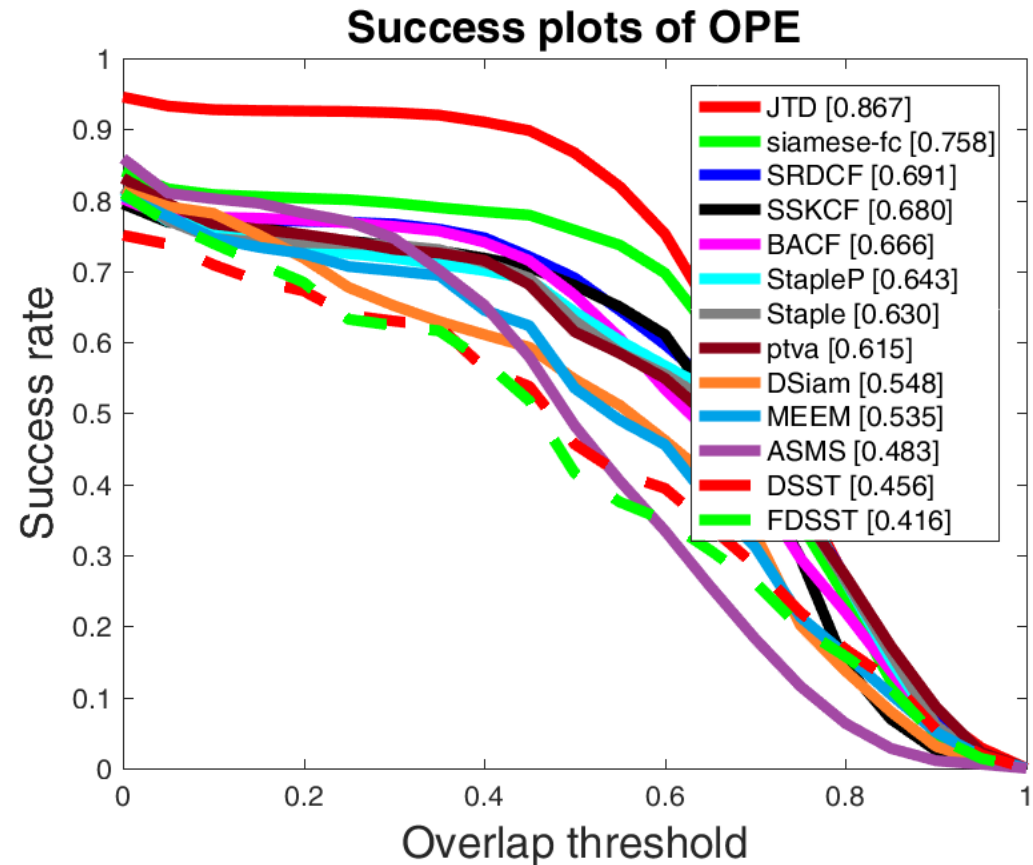


# Joint Detection & Tracking

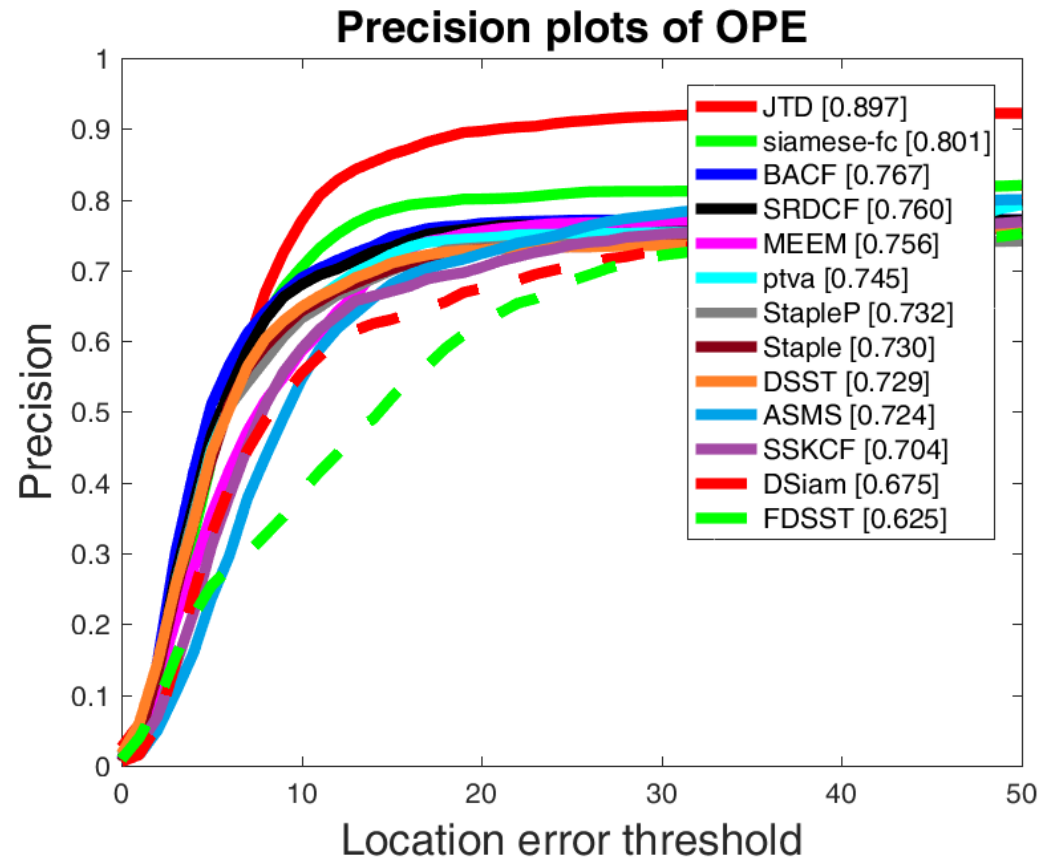
- **Tracker node:** Given the initialized position of a target, the tracker  $T$  is responsible for estimating the bounding box of the target in the subsequent frames.
- **Detector:** Given a bounding box defining the target in specific frame produced by the tracker, the detector  $D$  is responsible for verifying this result, and then provide the appropriate feedback to the system.
- **Master Visual Analysis:** If the verification from  $D$  fails, Master Visual Analysis is responsible for the re-initialization of the tracker  $T$  with the corrected bounding box.



# Joint Detection & Tracking (JTD)

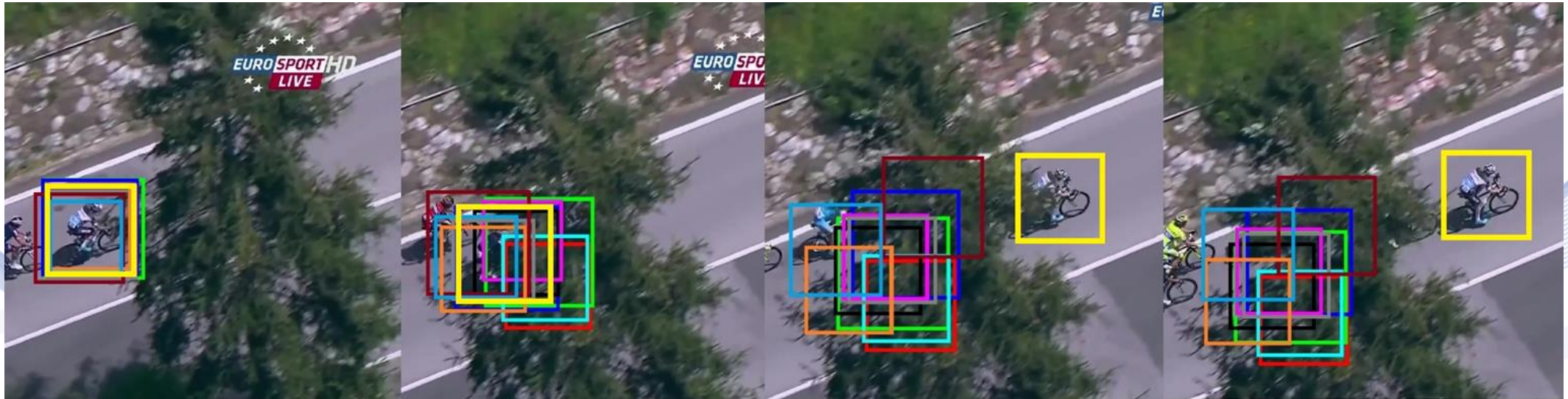


# Joint Detection & Tracking (JTD)



# Joint Detection & Tracking

- Target re-initialization by the detector in hard tracking cases when tracking algorithms fail.





# Joint Detection & Tracking

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# 2D Object detection and Tracking



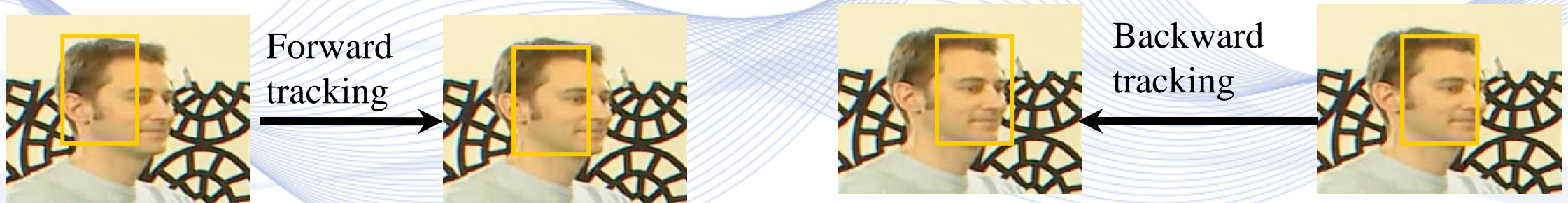
- Object Detection and Forward Tracking
- **Object Forward-Backward Tracking**

# Forward-Backward Tracking

## Motivation

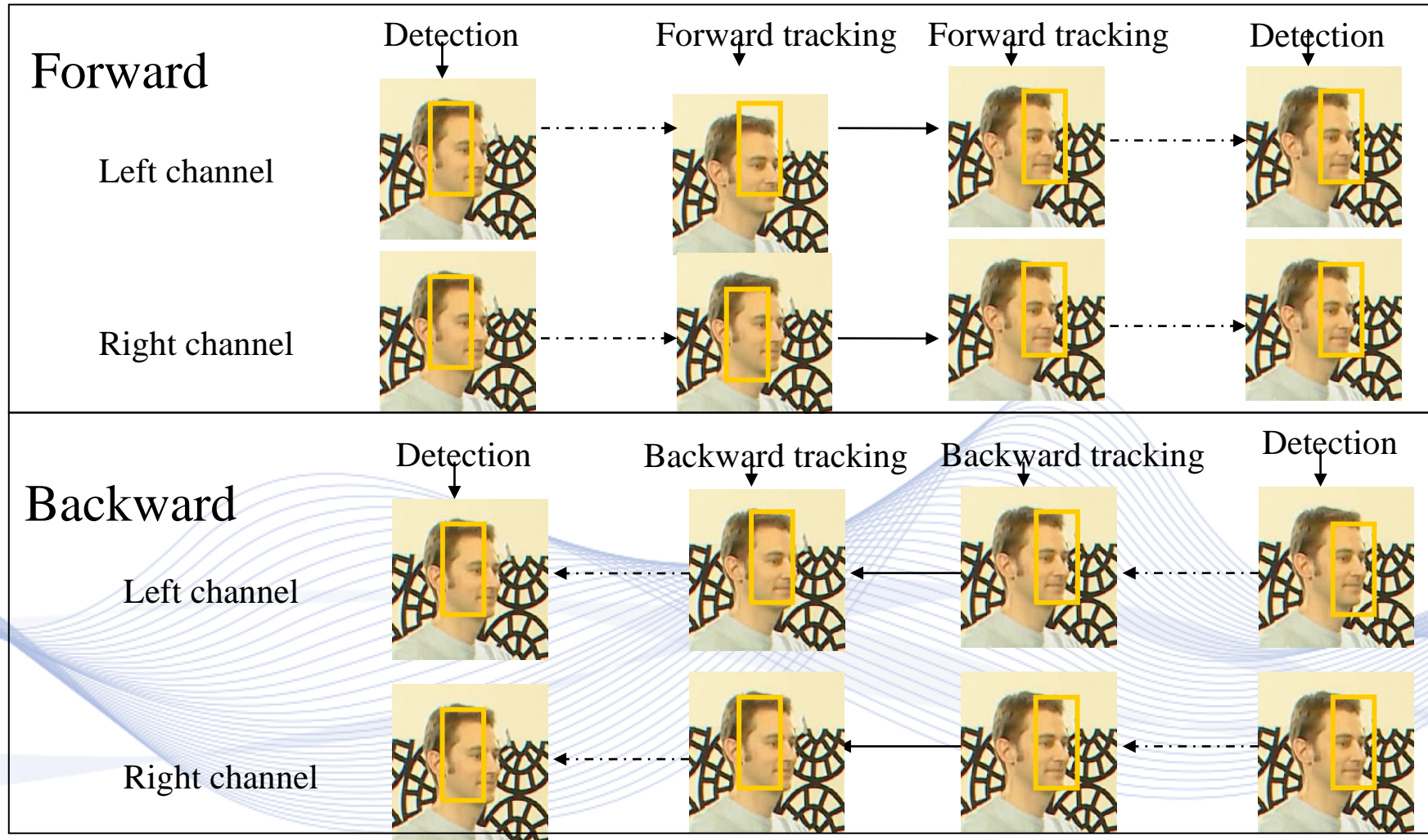


- Forward in time tracking: different results than backward in time tracking. One mode of tracking may succeed where the other fails
- The key point: post-process the results of a forward and a backward tracking jointly, in order to refine the tracking results
- Same reasoning for stereoscopic video: performing tracking on both channels of a video provides us with more information than using only one.





# F-BTracking in Stereo Video



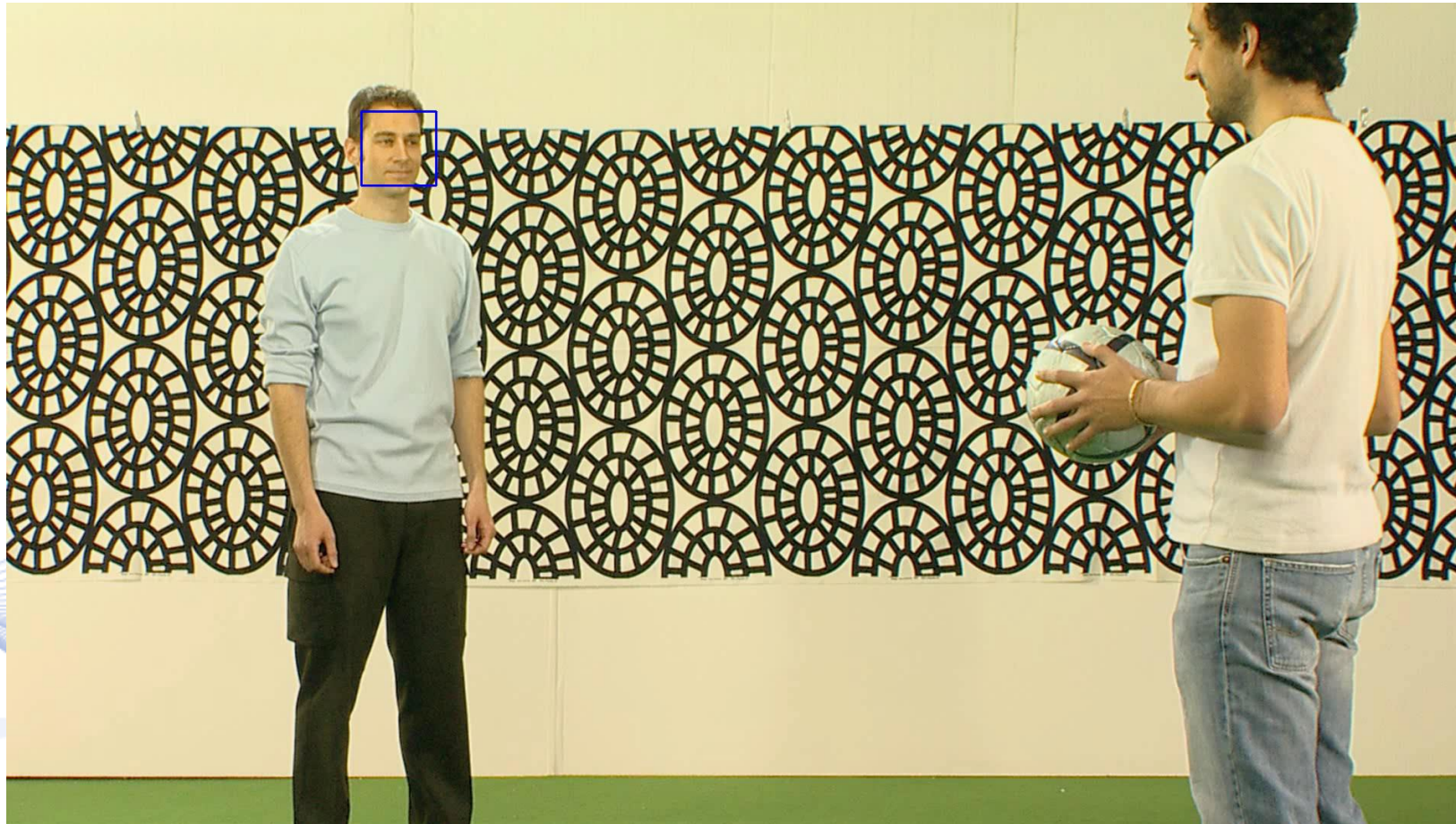
# Quantitative Results

Algorithm performance (ATA) using stereo data						
Name	Detection period	Foward	FP	FBP	FBSP	
Badminton	20	0.614	0.620	0.625	<b>0.634</b>	
	30	0.604	0.612	0.624	<b>0.630</b>	
	40	0.580	0.589	0.594	<b>0.601</b>	

- Bayesian post-processing algorithms:
  - Forward tracking (FP)
  - Forward and backward tracking (FBP)
  - Forward and backward tracking in stereo sequence (FBSP)



# Forward-Backward Stereo Tracking Results





# F-B tracking conclusions

- Combining information from forward, backward tracking in a stereoscopic video, leads to more accurate tracking results.
- In terms of ATA, accuracy is increased proportionally to tracking failures of the standard single channel algorithm
- However, in tracking failures, it seems that the extra channel information from stereo is not fully exploited

# Bibliography

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- [NIK2000] N. Nikolaidis and I. Pitas, “3D Image Processing Algorithms”, J. Wiley, 2000.
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# Q & A

**Thank you very much for your attention!**

**Contact: Prof. I. Pitas**  
**[pitass@csd.auth.gr](mailto:pitass@csd.auth.gr)**