

### Deep Semantic Image Segmentation summary

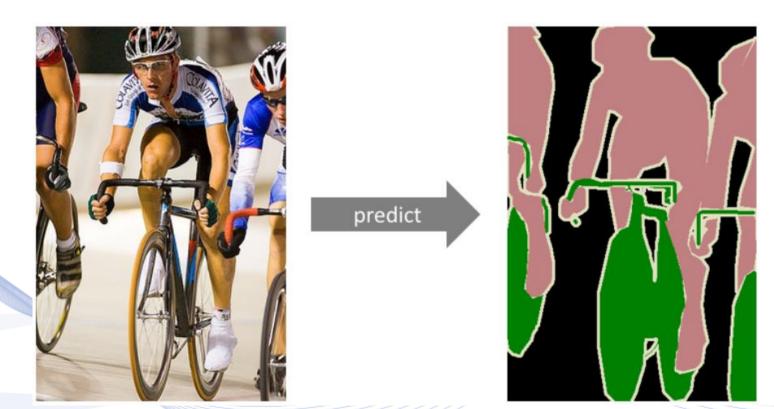
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- Introduction
- Classical image segmentation techniques.
- Deep semantic image segmentation.
- Applications







Person Bicycle Background

Semantic image segmentation of a sports event [EVE2011].



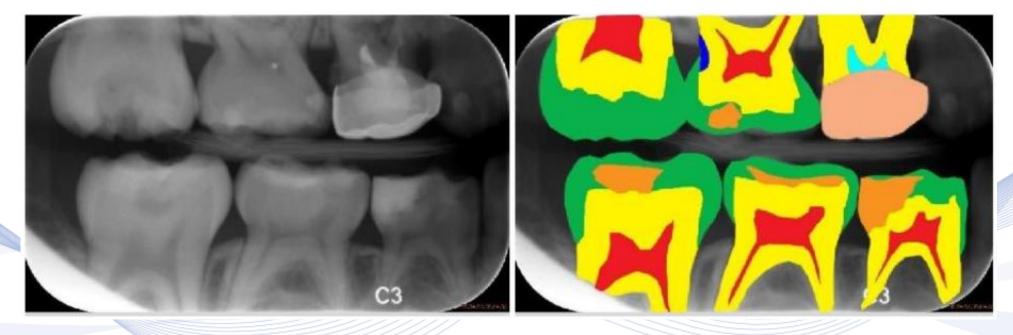
• Autonomous driving.







• Medical purposes.



**VML** 

Semantic dental Xray segmentation [TOR2014].





- An image domain  $\mathcal{X}$  must be segmented in N different regions  $\mathcal{R}_1, \ldots, \mathcal{R}_N$ .
- The segmentation rule is a logical predicate of the form  $P(\mathcal{R})$
- Image segmentation partitions the set X into the subsets  $\mathcal{R}_i$ , i
  - = 1, ..., N, having the following properties:

 $\begin{aligned} \mathcal{X} &= \bigcup_{i=1}^{N} \mathcal{R}_{i} ,\\ \mathcal{R}_{i} \cap \mathcal{R}_{j} &= \emptyset, \quad i \neq j, \\ P(\mathcal{R}_{i}) &= \text{TRUE}, \quad i = 1, \dots, N, \\ P(\mathcal{R}_{i} \cup \mathcal{R}_{j}) &= \text{FALSE}, \quad i \neq j. \end{aligned}$ 





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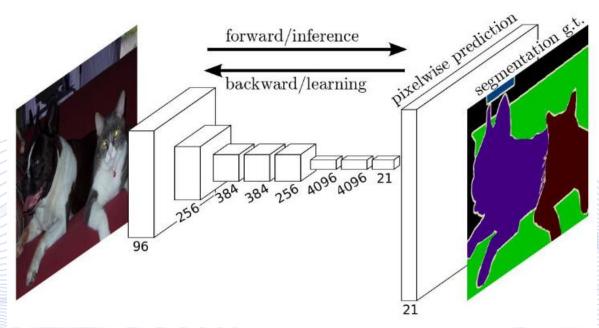


- Recent semantic image segmentation methods classify each pixel of an input image to an object class using DNNs.
- **Dense prediction**: DNN predictions are made at pixel level.





• Fully convolutional network for semantic segmentation.



End-to-end CNN training for semantic image segmentation [LON2015].



• However, as the encoder radically reduces the resolution of the input image the decoder fails to produce fine-grained segmentations.



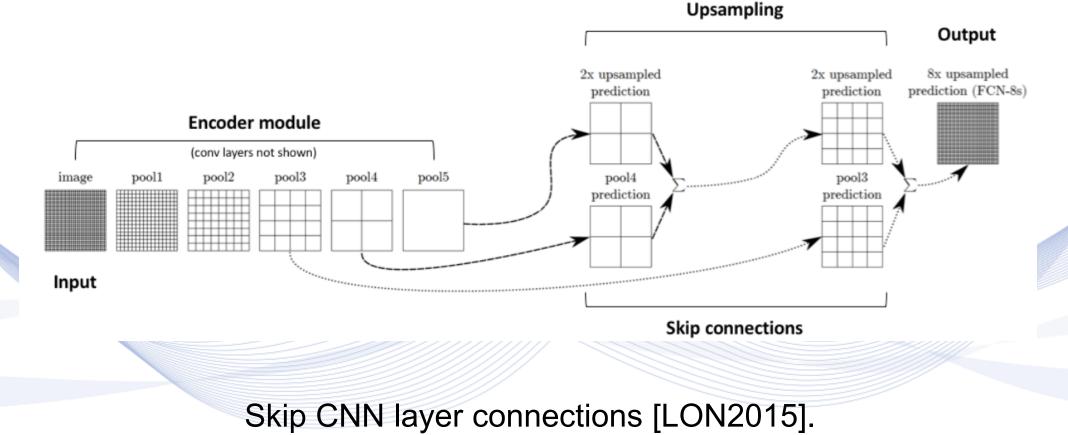
Ground truth target

Predicted segmentation





Coarse image segmentation [LON2015].



VML







Ground truth target



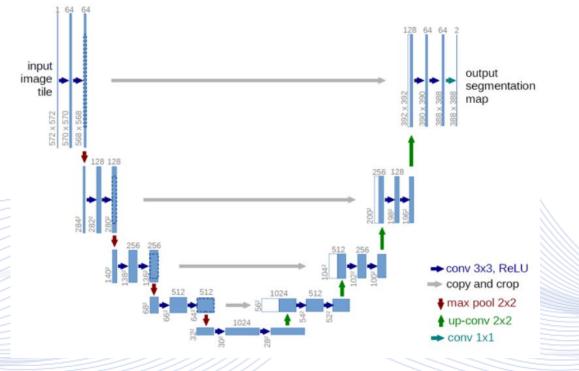
#### Predicted segmentation



Improved segmentation results with skip connections [LON2015].

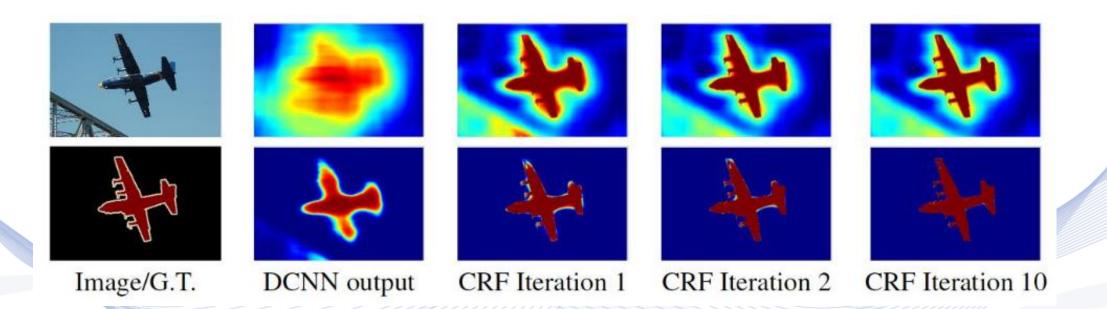






U-Net network architecture [RON 2015].



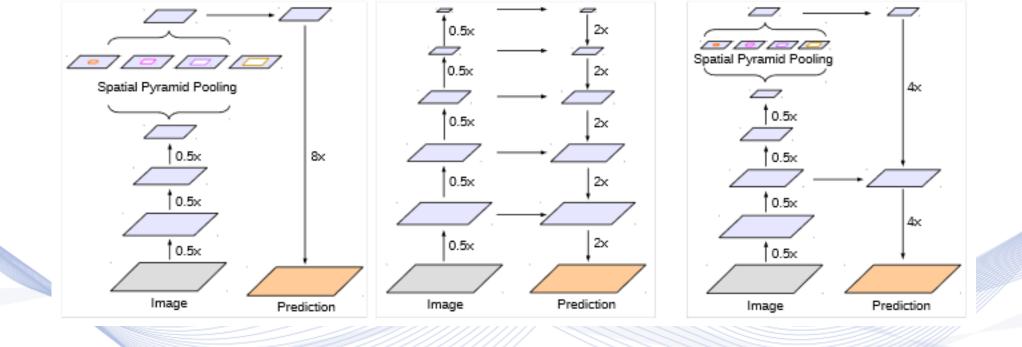


VML

Fully convolutional networks with CRFs [CHE2017].







**Spatial Pyramid Pooling** 

Encoder-Decoder

Combined [CHE2018]



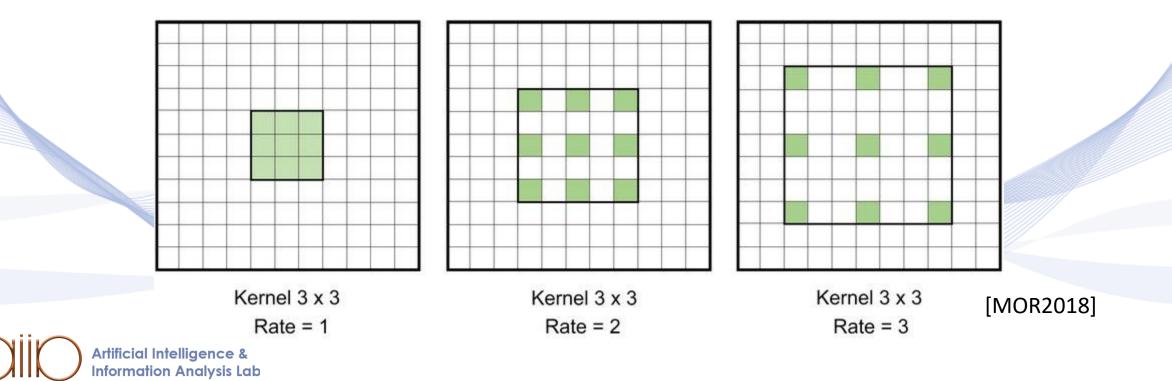


- Encoder-decoder architectures can be very slow due to the operations required by the convolution layers.
- In this direction, atrous or dilated convolution has been introduced as a replacement to the convolution layer.
  - Atrous convolution offers a wider field of view at the same computational cost.





• The **dilation rate** defines a spacing between the values in a convolving kernel.







(a) ASPP

(b) OCR

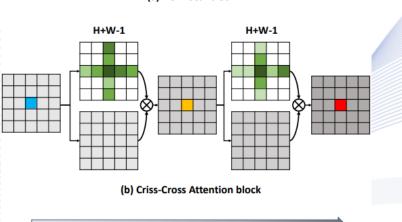
a) ASPP (using dilated convolution): The context of a pixel (red box) is the set of sparsely sampled pixels around it (blue and ochre boxes). b) OCR: The context is a set of pixels residing in the object it belongs to.



Learnable attention matrices can help semantic segmentation by eliminating spurious regions/noise [HUA2019].

- Criss-cross attention mechanism is a better alternative to regular attention matrix for semantic segmentation [HUA2019].
- It adaptively captures contextual information for each pixel on the vertical and horizontal axes.

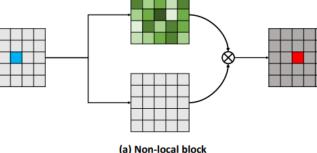
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Few context



**Rich context** 



**H**xW

### Joint 3D Scene Geometry and **VML** Semantics Estimation

X

 $T_n(F(X))$ 

F

T

 $T_1(F(X))$ 

#### Typical multitask networks have:

- Common input X.
- Common feature extraction operator F.
- *n* concurrent task operators:

 $\mathbf{T}_1, \dots, \mathbf{T}_n, \ n \geq 2.$ 

• The multitask network output is the set:

 $\mathcal{T} = \{\mathbf{T}_1(\mathbf{F}(\mathbf{X})), \dots, \mathbf{T}_n(\mathbf{F}(\mathbf{X}))\}.$ 





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## Crowd detection using view semantic image segmentation

- The crowd detection problem is effectively approached using semantic image segmentation.
- If only two object classes are considered (i.e., crowd, no-crowd), semantic image segmentation corresponds to crowd detection.



# Crowd detection using **CML** semantic image segmentation



Crowd detection as semantic image segmentation.

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# Crowd detection using commentation commentation

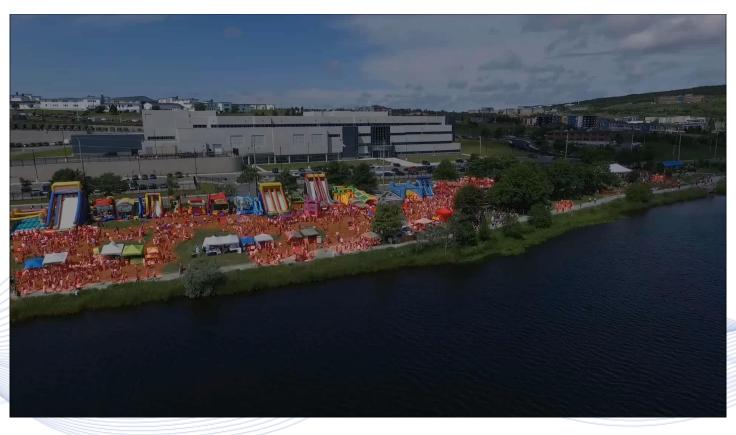
 The semantic image segmentation branch is trained using the following loss function:

$$J_s = J_p + \alpha \sum_{i=2}^{s} J_{a_i},$$

- $J_p$ : principal segmentation loss.
- $J_{a_2}, J_{a_3}$ : auxiliary loss for stage 2,3 of the base model, respectively.
- Both  $J_p$ ,  $J_{a_i}$  are standard softmax loss functions.

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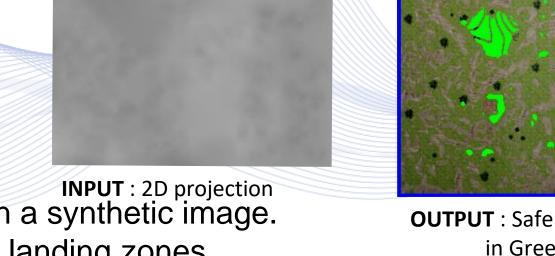
## Crowd detection using **CML** semantic image segmentation



Crowd detection results on a UAV-captured video.

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### Semantic segmentation for landing site detection



3D projection INPUT : 2D projection Landing site detection results on a synthetic image.

**OUTPUT** : Safe Landing Areas in Green Color







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#### Q & A

#### Thank you very much for your attention!

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