

Drone Human centered interfaces

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Multidrone Personnel and Roles

• **Director**. Person in charge of the media production. Specify the shots to be taken by the drone team. He will interface with the system through the Dashboard.

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- Supervisor Operator. Person in charge of the security of the system. Throughout the Supervisor module, this person will validate plans as safe, and will give a green light to the Director.
- Drone Pilots(?). For security reasons, each drone will have a human pilot in charge to take over in case of emergency.
- Cameramen (?). There will be a cameraman in charge of each camera on board the drones to take manual control if required by Director.

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Multiple drone operation modes



Manual operation

- 1 pilot and 1 cameraman per drone.
- Scalability and operation cost issues, when multiple drones operate.

Automatic operation

- 1 drone or multiple drones.
- 1 director (+ director dashboard).
- 1 Flight supervisor (+ supervisor station).
- 1 pilot per drone (due to regulations, redundant in the future?).



Drone Human centered interfaces

- Director dashboard
- Flight supervisor station



Design principles



- Classical web application.
- Based on state-of-the-art web development tools:
 - MySQL
 - Apache Tomcat
 - Angular.js, Bootstrap, HTML5.
- Layered architecture:
 - Database
 - REST API
 - Application/controller/services
 - HTML front-end.



Dashboard Logical Architecture

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Application Logic (Java, Angular.js)

Data Access (REST)

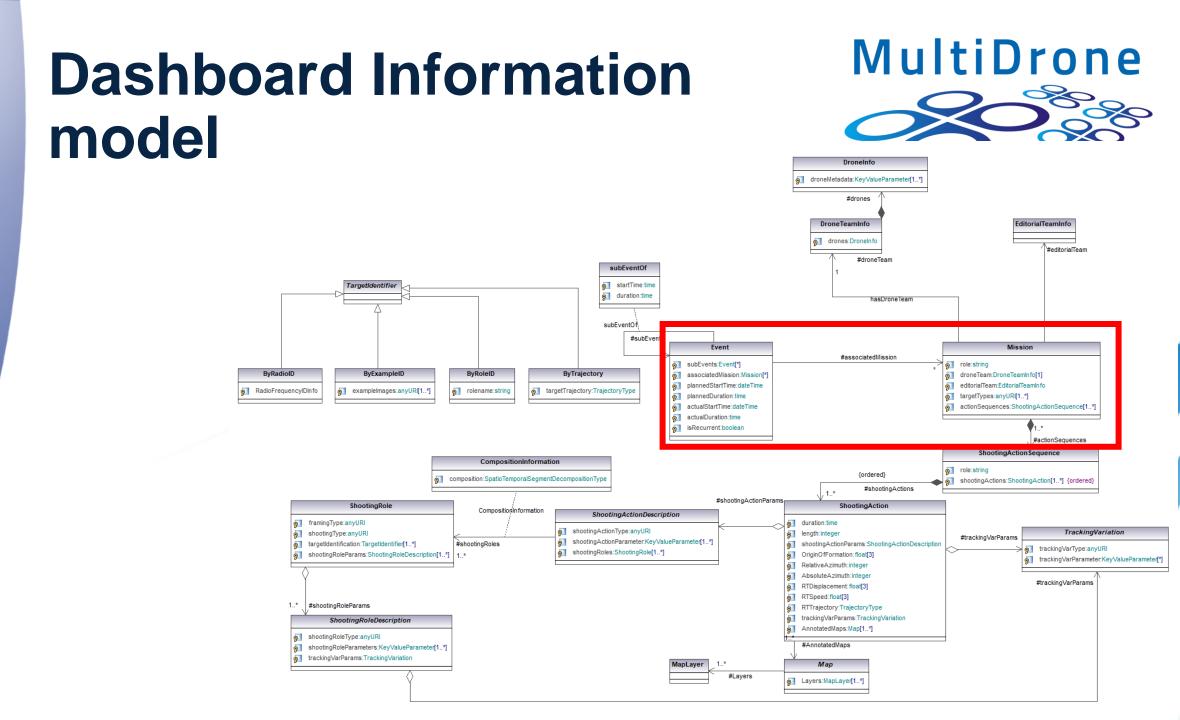
Data Persistence (Database)



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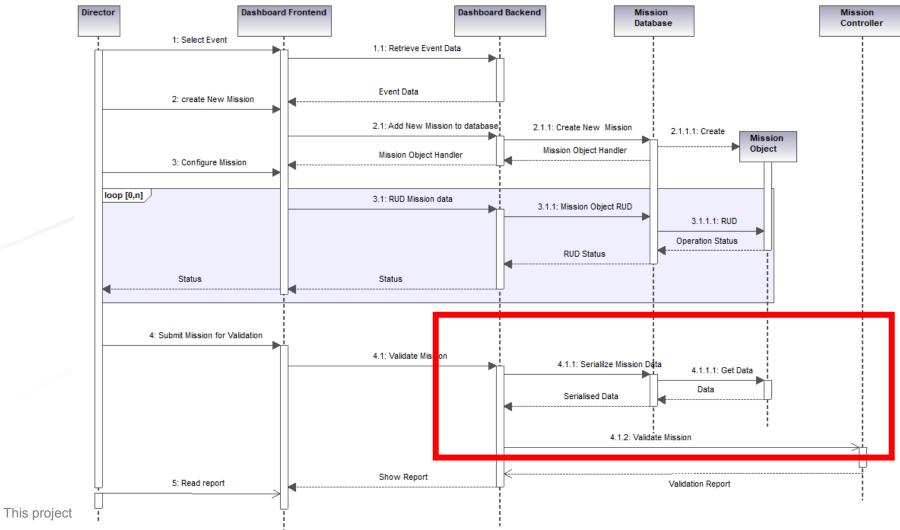
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MultiDrone Dashboard Deploy pkg Dashboard Collaboration «component» 🗧 component» 1 Ground Station Backend «use» Editorial staff Director EM_API «component» 🕄 Event Manager 3DMT_AP Studio Infrastructure Dashboard «component» 1 DataAccess «component» \$ 3D Model tracker Monitor/Multiview «component» § SMM_API «component» នា «component» 1 Mission Database EventNotification Semantic Map Manager Interphono / voice comm VS_Output Dashboard_GUI L/O ŧ REST API នា MC API «component» «component» «component» § «component» 🕄 Dashboard Frontend Dashboard backend Mission Controller Video switch Multidrone Platform Advanced Controls នា «component» ACC GUL «component» នា component» 🕄 Drone 1 CameraCtrl:CameraControl Advanced Camera Control Cameraman CarneraControl VideoStream:VideoStream នា «component» Drone 2 CameraCtrl:CameraControl VideoStream VideoStream:VideoStream Mixer_API Mixer_Controls នា «component» «component» 👔 «component» 🕄 Drone N CameraCtrl:CameraControl Video Technician Video mixer VideoStream:VideoStream Mixer_Output



Dashboard Interaction with Mission Planner





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Dashboard mockup video

	MULTIDRONE dashboard		
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Dashboard Implementation issues

- Database design:
 - mySQL.
- Serialised representation of the Shooting Mission:
 - XML Schema.



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Supervision station

- Supervise several drones with one operator is challenging:
 - Operator needs a good situational awareness to take the good decision.
 - Operator have to simultaneously:
 - Handle the mission.
 - Ensure security.
 - Re-plan drone mission in real-time when necessary.
 - Monitor and manage the payload, e.g. gimbal and Cameras.



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⇒ Need for a well adapted cognitive system that allows the supervision of several UAVs by one/few operator(s).



Supervision station

- Objectives:
 - Supervise the execution of the Mission in terms of safety and security.
 - Reduce the cognitive payload of the operator and help him to focus on its mission.
- Graphic User Interface (GUI):
 - Intuitive interactions based on touch screen system for contextual menu.
 - Dual screen approach: head-up and head-down displays.
 - Display:
 - Annotated map
 - Video streams from the drone's navigation cameras
 - Telemetry and status information from the drones.
- The GUI allows the operator to:
 - Check and validate the safety of the flight plan provided by the Shooting Mission.
 - Monitor the mission execution, including the overall state of the drones.
 - Abort the mission if needed for security reasons.
 - Insert manually safety- and logistics-related annotations in a semantic map.
- Can be use above the GCS.

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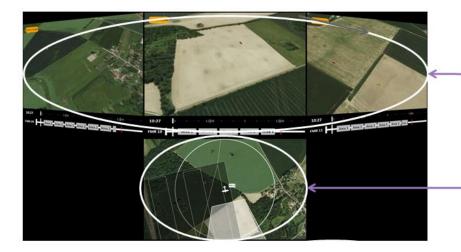
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Supervision station

Head up display for sensor information



data — and processing results (for example Object tracking)

Display of sensor

Neighborhood situation around a specific drone (zoom of the map around the drone)

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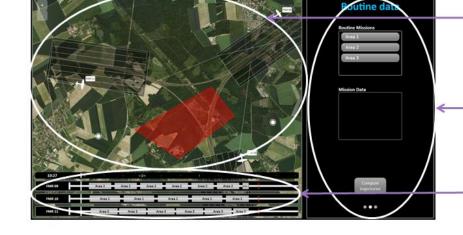
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Situation overview (Map with planned trajectories, forbidden areas...)

> Mission data, navigation data, ...

> > Mission status – Timeline

Head down display for mission monitoring









Thank you very much for your attention!

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