## Edge Detection With 1D Masks Tutorial Exercise

At an edge detection system, the input image is initially row-wise scanned by employing the mask:  $\begin{bmatrix} 1 & -2 & 1 \end{bmatrix}$  and the output of this convolution is columnwise scanned by the filter:  $\begin{bmatrix} 1 & -2 & 1 \end{bmatrix}^T$ . Prove that the z-transform property for convolutions is useful for determining the transfer function of this system without the need of calculating the convolutions and define a 2D mask that can achieve the same result.